

NEW VISIONS IN NATURAL SCIENCE AND MATHEMATICS:

CONCEPTS - THEORIES - APPLICATIONS



Editor
Prof. Dr. N.Gülşah Deniz



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Editör

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New Visions In Natural Science And Mathematics: :Concepts - Theories - Applications
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Chapter 1

Curvatures Of Tube Surfaces with Frenet Frame In 4-Dimensional Space

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ÖZET

Bu çalışmada öncelikle Öklidyen 4-uzaydaki bir uzay eğrisi için Frenet çatısı ile ilgili tanımlar ile teoremler verilmiştir. Burada Frenet çatılı bir eğri için Frenet vektörleri, Frenet türev denklemleri ve eğrinin κ , τ ve η eğriliklerinden bahsedilmiştir. 4-boyutlu Öklidyen uzayda yüzeyler ile ilgili kavramlar ve onların bir çeşidi olan kanal yüzeyleri için verilmiş incelemeler üzerinde durulmuştur. Bu uzayda kanal yüzeyinin özel hali olan merkezi düzgün bir eğri üzerindeki noktalar ve bu eğrinin bu noktalardaki normal düzleminde bulunan sabit yarıçaplı bir çemberin oluşturduğu dairesel yüzey olan tüp (tubular) yüzey incelenmiştir. Öklid 4-uzayında tüp yüzeyinin Frenet çatılı genel denklemleri verilmiştir. Genel denklemler kullanılarak birinci ve ikinci kısmi türevler, yüzeyin U_1 birim normal vektör alanı ve U_1 birim normal vektör alanına Gram-Schmidt yöntemi uygulanarak U_2 birim normal vektör alanı bulunup ardından yüzeyin birinci ve ikinci temel form katsayıları elde edilmiştir. Ek olarak yüzeyin U_1 ve U_2 birim normal vektör alanları için Gauss eğrilikleri ve ortalama eğrilikler hesaplanmıştır. Elde edilen hesaplar için bir örnek verilmiş ve yüzeyin izdüşüm uzaylarındaki şekilleri çizdirilmiştir.

Anahtar Kelimeler: Öklid 4-uzayı, Frenet çatısı, Tüp yüzeyi

ABSTRACT

In this research, the definitions and theorems of a space curve with respect to the Frenet frame are initially presented in Euclidean 4-space. These are Frenet vectors, Frenet derivative equations and curvatures κ , τ and η of a curve with Frenet frame. The concepts related to surfaces in 4-dimensional Euclidean space and their variants, such as canal surfaces, are analyzed. In this space, a special case of the canal surface, the tube surface, a circular surface formed by points on a central smooth curve and a circle of constant radius in the normal plane of this curve at these points, is studied. The general equation of the tube surface in Euclidean 4-space with Frenet frame is given. Using the general equation, the first and second partial derivatives, the \mathbf{U}_1 unit normal vector field of the surface and the \mathbf{U}_2 unit normal vector field by applying the Gram-Schmidt method to the \mathbf{U}_1 unit normal vector field are found and then the first and second fundamental form coefficients of the surface are obtained. In addition, Gaussian curvatures and mean curvatures are calculated for \mathbf{U}_1 and \mathbf{U}_2 unit normal vector fields of the surface. An example is given for the obtained calculations and the surface shapes in projection spaces are plotted.

Keywords: Euclid 4-space, Frenet frame, Tube surface

INTRODUCTION

Frenet equations were independently discovered by Frenet in 1847 and Serret in 1851. In 1760, Euler was the first to study curves and surfaces formed by the intersection of various planes. The canal surface, a specific type of surface, was defined by Monge in 1850. Canal surfaces are parametrized with distinct frames in \mathbb{E}^4 . A tube surface, which is a special case of a canal surface, is the envelope of a moving sphere with a constant radius function $r(t)$, and is simpler to describe both analytically and kinematically (Doğan and Yaylı, 2017). Blaga (2005) introduced a technique for parameterizing tubular surfaces by utilizing the parameter along the generating curve and expressing the position vector of a point on the surface as ψ . Numerous studies in the literature have explored these surfaces in similar spaces (Bayram et al., 2009; Alessio, 2009; Bulca et al., 2017). Otsuki demonstrated the existence of a graphical representation of a surface in \mathbb{E}^4 and investigated the isometric immersions of two-dimensional connected oriented manifolds in \mathbb{E}^4 . Furthermore, Otsuki (1966) provided a characterization of surfaces within hyperplanes, compact surfaces with constant mean curvature and non-negative Gaussian curvature, as well as surfaces in the three-dimensional sphere in \mathbb{E}^4 . In 2008, Ganchev and Milousheva classified several important classes of surfaces in four-dimensional Euclidean space, distinguished by their invariants. Óláh-Gál and Pál (2009) studied the global isometry of two surfaces in \mathbb{E}^4 , demonstrating that, while these surfaces are not globally isomorphic, they remain globally isometric. Mello (2009) analyzed the properties of surfaces immersed in \mathbb{E}^4 and provided conditions under which such surfaces exhibit hypersphericity. Kişi et al. (2019) examined the conditions under which canal surfaces with parallel transport frame vectors in \mathbb{E}^4 are flat, minimal, or linear Weingarten, and also determined the normal vectors of canal surfaces. Finally, Bulca et al. (2017) characterized surfaces in \mathbb{E}^4 using the coefficients of the first and second fundamental forms. Tube surfaces have been studied using different spaces and different frames (Maekawa et. al., 1998; Abdel-Aziz and Saad, 2011; Dede, 2013; Dede et. al., 2015; Ekici et. al., 2017; Kızıltuğ et.al., 2019; Tozak et. al., 2019; Yağbasan and Ekici, 2023; Yağbasan et. al., 2023; Yağbasan et. al., 2023a). Similarly, different studies are given for the canal surface, which is the general form of the tube surface (Xu et. al., 2006; Kim et. al., 2016; Uçum and İlarıslan, 2016; Doğan and Yaylı, 2017; Bulca et. al., 2017; Kaymanlı et. al., 2018; Şekerci and Çimdiker, 2019). In addition, there have been studies on surfaces created using different frame vectors in 3 and 4-space (Kaymanlı et. al., 2022; Ekici et. al., 2023; Ekici Coşkun and Akça, 2023; Dede et. al., 2024). In this research, investigations into tube surfaces are discussed in

\mathbb{E}^4 . We offer the parametrization of the tube surface using the Frenet frame in \mathbb{E}^4 . Furthermore, we are given the first and second unit normal vector fields, principal curvatures, Gaussian curvature, and mean curvature of tube surfaces in 4-dimensional space. Finally, an example of a tube surface is provided, with corresponding figures of the surface plotted in projection spaces.

PRELIMINARIES

Let $\mathbf{X} = (x_1, x_2, x_3, x_4)$, $\mathbf{Y} = (y_1, y_2, y_3, y_4)$ and $\mathbf{Z} = (z_1, z_2, z_3, z_4)$ be three vectors in \mathbb{E}^4 . Here the inner product is expressed as $\langle \mathbf{X}, \mathbf{Y} \rangle = x_1y_1 + x_2y_2 + x_3y_3 + x_4y_4$, the norm of a vector as $\|\mathbf{X}\| = \sqrt{\langle \mathbf{X}, \mathbf{X} \rangle}$ and the vector product as

$$\begin{aligned} \mathbf{X} \wedge \mathbf{Y} \wedge \mathbf{Z} = & (x_2y_3z_4 - x_2y_4z_3 - x_3y_2z_4 + x_3y_4z_2 + x_4y_2z_3 - x_4y_3z_2)\mathbf{e}_1 \\ & - (x_1y_3z_4 - x_1y_4z_3 - x_3y_1z_4 + x_3y_4z_1 + x_4y_1z_3 - x_4y_3z_1)\mathbf{e}_2 \\ & + (x_1y_2z_4 - x_1y_4z_2 - x_2y_1z_4 + x_2y_4z_1 + x_4y_1z_2 - x_4y_2z_1)\mathbf{e}_3 \\ & - (x_1y_2z_3 - x_1y_3z_2 - x_2y_1z_3 + x_2y_3z_1 + x_3y_1z_2 - x_3y_2z_1)\mathbf{e}_4 \end{aligned} \quad (1)$$

where $\mathbf{e}_1 \wedge \mathbf{e}_2 \wedge \mathbf{e}_3 = \mathbf{e}_4$, $\mathbf{e}_2 \wedge \mathbf{e}_3 \wedge \mathbf{e}_4 = \mathbf{e}_1$, $\mathbf{e}_3 \wedge \mathbf{e}_4 \wedge \mathbf{e}_1 = \mathbf{e}_2$ and $\mathbf{e}_4 \wedge \mathbf{e}_1 \wedge \mathbf{e}_2 = -\mathbf{e}_3$ (Allesio, 2009; Elsayied et. al., 2021). If $\langle \alpha', \alpha' \rangle = 1$, $a(t) = a : I \subset \mathbb{R} \rightarrow \mathbb{E}^4$ is the unit speed curve. The Frenet equations of variation for the $a(t)$ curve given by the spring parameter are

$$\begin{bmatrix} \mathbf{T}' \\ \mathbf{N}' \\ \mathbf{B}'_1 \\ \mathbf{B}'_2 \end{bmatrix} = \begin{bmatrix} 0 & \kappa & 0 & 0 \\ -\kappa & 0 & \tau & 0 \\ 0 & -\tau & 0 & \eta \\ 0 & 0 & -\eta & 0 \end{bmatrix} \begin{bmatrix} \mathbf{T} \\ \mathbf{N} \\ \mathbf{B}_1 \\ \mathbf{B}_2 \end{bmatrix} \quad (2)$$

where the functions

$$\kappa = \langle \mathbf{T}', \mathbf{N} \rangle, \quad \tau = \langle \mathbf{N}', \mathbf{B}_1 \rangle, \quad \eta = \langle \mathbf{B}'_1, \mathbf{B}_2 \rangle \quad (3)$$

respectively (Gray, 1993; Gluck, 1966). A canal surface, centered at a spine curve $a(t)$ with radius $r(t)$, is parametrized by

$$\psi(t, v) = a(t) + r(t)(\cos v \mathbf{e}_1(t) + \sin v \mathbf{e}_2(t)) \quad (4)$$

where $r(t)$ is a real differentiable function (Kişi et. al., 2019; Bulca et. al., 2017). Let M be a smooth surface in \mathbb{R}^4 given with the patch $\psi : U \subset \mathbb{R}^2 \rightarrow \mathbb{R}^4$, $\psi(t, v)$. The tangent space to M at an arbitrary point $p = \psi(t, v)$ of M span

$\{\psi_t, \psi_v\}$. In the chart (t, v) the coefficients of the first fundamental form of M are given by

$$E = \langle \psi_t, \psi_t \rangle, F = \langle \psi_t, \psi_v \rangle, G = \langle \psi_v, \psi_v \rangle \text{ and } W = EG - F^2 \quad (5)$$

where \langle, \rangle is the Euclidean inner product (Mello, 2009; Bayram et. al., 2009). Consider $\psi_{tt}, \psi_{tv}, \psi_{vv}$ as the second-order partial derivatives, and let $\mathbf{U}_1, \mathbf{U}_2, \dots, \mathbf{U}_{n-2}$ represent the normal vector fields of the manifold M with the coefficients of its second fundamental form given by, $1 \leq k \leq n - 2$,

$$L_k = \langle \psi_{tt}, \mathbf{U}_k \rangle, \quad M_k = \langle \psi_{tv}, \mathbf{U}_k \rangle \text{ and } N_k = \langle \psi_{vv}, \mathbf{U}_k \rangle. \quad (6)$$

The Gaussian and mean curvatures of the surface are typically expressed as

$$K = \frac{LN - M^2}{EG - F^2} \text{ and } H = \frac{LG - 2MF + NE}{EG - F^2}. \quad (7)$$

respectively (Chen and Piccini, 1973; Mello, 2009; Bulca et. al., 2017).

TUBE SURFACES CREATED WITH T AND B_1 FRENET VECTORS IN 4-DIMENSIONAL SPACE

In order to form the equation of the 2-dimensional Frenet frame tube surface in 4-dimensional space, a circle that accepts each point on $\alpha(t)$ as the centre in the plane stretched by T and B_1 vectors must be moved.

Thus, the formed tube surface

$$\psi(t, v) = a(t) + r(\cos v T(t) + \sin v B_1(t)) \quad (8)$$

The necessary theorems and proofs for the parametric equation are given. Here $r \in \mathbb{R}$ is taken. Frenet curvatures are taken constant throughout this study.

Theorem Let $M \subset \mathbb{E}^4$ be a tube surface at a distance r from the spine curve $\alpha(t)$ according to Frenet frame $\{T, N, B_1, B_2\}$ with parametrization $\psi(t, v)$, given by $\psi: U \subset \mathbb{E}^2 \rightarrow \mathbb{E}^4$, $(t, v) \in U$ and let tangent space to M at a point $p \in \psi(t, v)$ be spanned by $\{\psi_t, \psi_v\}$. As a result, the following assertions are true:

1. The unit normal vector fields \mathbf{U}_1 and \mathbf{U}_2 of tube surface in \mathbb{E}^4 are found to be

$$\mathbf{U}_1 = \frac{-r\eta\sin v\mathbf{N} + r(\kappa\cos v - \tau\sin v)\mathbf{B}_2}{r\sqrt{\cos^2 v(\kappa^2 - \tau^2 - \eta^2) - \kappa\tau\sin 2v + \eta^2 + \tau^2}}$$

and

$$\mathbf{U}_2 = \frac{r\tau\cos v\sin v\mathbf{T} + (r\tau - r\tau\cos^2 v)\mathbf{N} - \cos v\mathbf{B}_1}{r\sqrt{\cos^2 v(\kappa^2 - \tau^2 - \eta^2) - \kappa\tau\sin 2v + \eta^2 + \tau^2}}$$

respectively.

2. Gaussian curvature K_1 and Mean curvature H_1 of tube surface with unit normal vector fields \mathbf{U}_1 in \mathbb{E}^4 are obtained as

$$K_1 = \frac{-r^2\kappa^2\eta^2[\cos^2 v(\kappa^2 - \tau^2 - \eta^2) - \kappa\tau\sin 2v + \eta^2 + \tau^2]^{-1}}{r^2[1 + r^2\cos^2 v(\kappa^2 - \tau^2 - \eta^2) - r^2\kappa\tau\sin 2v + r^2(\eta^2 + \tau^2)] - r^2\sin^2 v}$$

and

$$H_1 = \frac{r^2\sin v[\kappa\eta + r\eta(\tau'\sin v - \kappa'\cos v) + r\eta'(\kappa\cos v - \tau\sin v)](\cos^2 v(\kappa^2 - \tau^2 - \eta^2) - \kappa\tau\sin 2v + \eta^2 + \tau^2)^{-1/2}}{r^2(1 + r^2[\cos^2 v(\kappa^2 - \tau^2 - \eta^2) + (\eta^2 + \tau^2) - \kappa\tau\sin 2v]) - r^2\sin^2 v}$$

respectively.

3. Gaussian curvature K_2 and Mean curvature H_2 of tube surface with unit normal vector fields \mathbf{U}_2 in \mathbb{E}^4 are obtained as

$$K_2 = \frac{-r^2\eta[2r^2\kappa\eta\cos v\sin v(\cos^2 v - 1) + r^2\cos^2 v(\kappa^2\eta - 2\tau^2\eta - 2r^2\tau^3)]}{\frac{[\cos^2 v(r^2\eta^2 - 1) - r^2\eta^2][r^2(1 + r^2\cos^2 v(\kappa^2 - \tau^2 - \eta^2) - r^2\kappa\tau\sin 2v + r^2(\eta^2 + \tau^2)) - r^2\sin^2 v]}{r^2\eta[r^2\eta\cos^4 v(\tau^2 - \kappa^2 + \eta^2) + r\eta'\cos v(1 - \cos^2 v) + r^2\eta(\tau^2 + \eta^2) + \eta\cos^4 v]} - \frac{[\cos^2 v(r^2\eta^2 - 1) - r^2\eta^2][r^2(1 + r^2\cos^2 v(\kappa^2 - \tau^2 - \eta^2) - r^2\kappa\tau\sin 2v + r^2(\eta^2 + \tau^2)) - r^2\sin^2 v]}}{r^2\eta[r^2\eta\cos^4 v(\tau^2 - \kappa^2 + \eta^2) + r\eta'\cos v(1 - \cos^2 v) + r^2\eta(\tau^2 + \eta^2) + \eta\cos^4 v]}}$$

and

$$H_2 = \frac{2\eta\cos^2 v\sin v(1 + r^2\eta^2 - r^2\kappa^2) + 4r^2\kappa\eta\cos v(1 - \cos^2 v)}{\sqrt{r^2\eta^2\sin^2 v + \cos^2 v}[\cos^2 v(\kappa^2 - \tau^2 - \eta^2) + r^2(\eta^2 + \tau^2) - 2r^2\kappa\tau\cos v\sin v + \cos^2 v]} + \frac{2r^2\eta\sin v(\tau^2\cos^2 v - \eta^2 - \tau^2) + \eta\sin v + r\eta'\cos v\sin v}{\sqrt{r^2\eta^2\sin^2 v + \cos^2 v}[\cos^2 v(\kappa^2 - \tau^2 - \eta^2) + r^2(\eta^2 + \tau^2) - 2r^2\kappa\tau\cos v\sin v + \cos^2 v]}$$

respectively.

Proof Tube surface, at a distance r from the spine curve $\alpha(t)$ with Frenet frame $\{\mathbf{T}, \mathbf{N}, \mathbf{B}_1, \mathbf{B}_2\}$ are parametrized by

$$\psi(t, v) = a(t) + r(\cos v \mathbf{T} + \sin v \mathbf{B}_1)$$

The partial derivatives of $\psi(t, v)$, with respect to t and v , are determined by

$$\psi_t = 1 + (r\kappa \cos v - r\tau \sin v) \mathbf{N} + r\eta \sin v \mathbf{B}_2 \quad (9)$$

and

$$\psi_v = r(-\sin v \mathbf{T} + \cos v \mathbf{B}_1). \quad (10)$$

Then, second order partial derivatives of $\psi(t, v)$, with respect to t and v , are given as

$$\psi_{tt} = (r\kappa\tau \sin v - r\kappa^2 \cos v) \mathbf{T} + \kappa \mathbf{N} + (r\kappa\tau \cos v - r\tau^2 \sin v - r\eta^3 \sin v) \mathbf{B}_1 \quad (11)$$

$$\psi_{tv} = (-r\kappa \sin v - r\tau \cos v) \mathbf{N} + r\eta \cos v \mathbf{B}_2 \quad (12)$$

and

$$\psi_{vv} = -r \cos v \mathbf{T} - r \sin v \mathbf{B}_1. \quad (13)$$

The unit normal vector fields \mathbf{U}_1 and \mathbf{U}_2 of the surface should be provided with the following conditions

$$\begin{aligned} \langle \psi_t, \mathbf{U}_1 \rangle &= 0 & \langle \psi_t, \mathbf{U}_2 \rangle &= 0 \\ \langle \psi_v, \mathbf{U}_1 \rangle &= 0 & \langle \psi_v, \mathbf{U}_2 \rangle &= 0 \quad \text{and} \quad \langle \mathbf{U}_1, \mathbf{U}_2 \rangle = 0 \\ \langle \mathbf{U}_1, \mathbf{U}_1 \rangle &= 1 & \langle \mathbf{U}_2, \mathbf{U}_2 \rangle &= 1 \end{aligned} \quad (14)$$

where ψ_t and ψ_v are the partial derivatives of $\psi(t, v)$, with respect to t and v . The unit normal vector field \mathbf{U}_1 of tube surface is obtained as

$$\mathbf{U}_1 = \frac{-r\eta \sin v \mathbf{N} + r(\kappa \cos v - \tau \sin v) \mathbf{B}_2}{r\sqrt{\cos^2 v (\kappa^2 - \tau^2 - \eta^2) - \kappa\tau \sin 2v + \eta^2 + \tau^2}} \quad (15)$$

using equation

$$\mathbf{U}_1 = \frac{a_1 \mathbf{T} + a_2 \mathbf{N} + a_3 \mathbf{B}_1 + a_4 \mathbf{B}_2}{\sqrt{a_1^2 + a_2^2 + a_3^2 + a_4^2}}$$

where $a_3 = 0$ and $a_1 = 0$ then $a_4 = r\kappa \cos v - r\tau \sin v$ and $a_2 = -r\eta \sin v$.

Since $\langle \mathbf{U}_1, \mathbf{U}_1 \rangle = 1$, \mathbf{U}_1 is the unit normal vector field of the tube surface. Then using methods of Gram Schmidt with \mathbf{U}_1 , the unit vector field \mathbf{U}_2 is given as

$$\mathbf{U}_2 = \frac{r\tau\cos v\sin v\mathbf{T} + (r\tau - r\tau\cos^2 v)\mathbf{N} - \cos v\mathbf{B}_1}{r\sqrt{\cos^2 v(\kappa^2 - \tau^2 - \eta^2) - \kappa\tau\sin 2v + \eta^2 + \tau^2}} \quad (16)$$

Using equation (14), the vector fields \mathbf{U}_1 and \mathbf{U}_2 are identified as unit normal vector fields for the tube surfaces. By substituting equations (9) and (10) into equation (5), the coefficients of the first fundamental form for the tube surfaces

$$\begin{aligned} E &= 1 + r^2[\cos^2 v(\kappa^2 - \tau^2 - \eta^2) + \eta^2 + \tau^2 - \kappa\tau\sin 2v] \\ F &= -r\sin v \\ G &= r^2 \end{aligned} \quad (17)$$

and

$$W = r^2(1 + r^2[\cos^2 v(\kappa^2 - \tau^2 - \eta^2) + \eta^2 + \tau^2 - \kappa\tau\sin 2v]) - r^2\sin^2 v$$

are subsequently derived. Equations (6), (11), (12), (13), and (15) lead to the coefficients of the second fundamental form of the tube surface with the unit vector field \mathbf{U}_1 in \mathbb{E}^4 obtained as,

$$\begin{aligned} L_1 &= \frac{r\kappa\eta\sin v}{r\sqrt{\cos^2 v(\kappa^2 - \tau^2 - \eta^2) - \kappa\tau\sin 2v + \eta^2 + \tau^2}} \\ M_1 &= \frac{r\kappa\eta}{\sqrt{\cos^2 v(\kappa^2 - \tau^2 - \eta^2) - \kappa\tau\sin 2v + \eta^2 + \tau^2}} \\ N_1 &= 0 \end{aligned} \quad (18)$$

Substituting equations (17) and (18) into equation (7) implies that Gaussian and mean curvatures with respect to \mathbf{U}_1 following as

$$K_1 = \frac{-r^2\kappa^2\eta^2[\cos^2 v(\kappa^2 - \tau^2 - \eta^2) - \kappa\tau\sin 2v + \eta^2 + \tau^2]^{-1}}{r^2[1 + r^2\cos^2 v(\kappa^2 - \tau^2 - \eta^2) - r^2\kappa\tau\sin 2v + r^2(\eta^2 + \tau^2)] - r^2\sin^2 v}$$

and

$$H_1 = \frac{\sin v[\kappa\eta + r\eta(\tau'\sin v - \kappa'\cos v) + r\eta'(\kappa\cos v - \tau\sin v)](\cos^2 v(\kappa^2 - \tau^2 - \eta^2) - \kappa\tau\sin 2v + \eta^2 + \tau^2)^{-1/2}}{(1 + r^2[\cos^2 v(\kappa^2 - \tau^2 - \eta^2) + \eta^2 + \tau^2 - \kappa\tau\sin 2v]) - \sin^2 v}$$

equations (6), (11), (12), (13), and (16) lead to the coefficients of the second fundamental form of the tube surface with the unit vector field \mathbf{U}_2 in \mathbb{E}^4 obtained as,

$$\begin{aligned}
L_2 &= \frac{-r^2\eta\sin v[\cos^2 v(\kappa^2 - \tau^2 - \eta^2) + \eta^2 + \tau^2 - \kappa\tau\sin 2v]}{\sqrt{\cos^2 v + r\eta^2(1 + \cos^2 v)}} \\
M_2 &= \frac{-r\eta\cos^2 v}{\sqrt{\cos^2 v + r\eta^2(1 + \cos^2 v)}} \\
N_2 &= \frac{-r^2\eta\sin v}{\sqrt{\cos^2 v + r\eta^2(1 + \cos^2 v)}}
\end{aligned} \tag{19}$$

Substituting equations (17) and (19) into equation (7) implies that Gaussian and mean curvatures with respect to \mathbf{U}_2 following as

$$K_2 = \frac{-r^2\eta[-2r^2\kappa\eta\cos v\sin^3 v + r^2\cos^2 v(\kappa^2\eta - 2\tau^2\eta - 2r^2\tau^3)]}{\frac{[\cos^2 v(r^2\eta^2 - 1) - r^2\eta^2][r^2(1 + r^2\cos^2 v(\kappa^2 - \tau^2 - \eta^2) - r^2\kappa\tau\sin 2v + r^2(\eta^2 + \tau^2)) - r^2\sin^2 v]}{r^2\eta[r^2\eta\cos^4 v(\tau^2 - \kappa^2 + \eta^2) + r\eta'\cos v\sin^2 v + r^2\eta(\tau^2 + \eta^2) + \eta\cos^4 v]}}{\frac{[\cos^2 v(r^2\eta^2 - 1) - r^2\eta^2][r^2(1 + r^2\cos^2 v(\kappa^2 - \tau^2 - \eta^2) - r^2\kappa\tau\sin 2v + r^2(\eta^2 + \tau^2)) - r^2\sin^2 v]}{r^2\eta[r^2\eta\cos^4 v(\tau^2 - \kappa^2 + \eta^2) + r\eta'\cos v\sin^2 v + r^2\eta(\tau^2 + \eta^2) + \eta\cos^4 v]}}$$

and

$$\begin{aligned}
H_2 &= \frac{2\eta\cos^2 v\sin v(1 + r^2\eta^2 - r^2\kappa^2) + 4r^2\kappa\eta\cos v\sin^2 v}{[\cos^2 v(\kappa^2 - \tau^2 - \eta^2) + r^2(\eta^2 + \tau^2) - 2r^2\kappa\tau\cos v\sin v + \cos^2 v]\sqrt{r^2\eta^2\sin^2 v + \cos^2 v}} \\
&+ \frac{2r^2\eta\sin v(\tau^2\cos^2 v - \eta^2 - \tau^2) + \eta\sin v + r\eta'\cos v\sin v}{[\cos^2 v(\kappa^2 - \tau^2 - \eta^2) + r^2(\eta^2 + \tau^2) - 2r^2\kappa\tau\cos v\sin v + \cos^2 v]\sqrt{r^2\eta^2\sin^2 v + \cos^2 v}}.
\end{aligned}$$

Corollary If the Gaussian and mean curvatures corresponding to the unit normal vector fields obtained for the Frenet vectors \mathbf{T} and \mathbf{B}_1 are similarly calculated using the shape operators corresponding to the unit normal vector fields, the same result is obtained.

TUBE SURFACES CREATED WITH \mathbf{T} AND \mathbf{B}_2 FRENET VECTORS IN 4-DIMENSIONAL SPACE

In order to form the equation of the 2-dimensional Frenet frame tube surface in 4-dimensional space, a circle that accepts each point on $\alpha(t)$ as the centre in the plane stretched by \mathbf{T} and \mathbf{B}_2 vectors must be moved. Thus, the formed tube surface

$$\psi(t, v) = \alpha(t) + r(\cos v\mathbf{T}(t) + \sin v\mathbf{B}_2(t)) \tag{20}$$

The necessary theorems and proofs for the parametric equation are given. Here $r \in \mathbb{R}$ is taken.

Theorem Let $M \subset \mathbb{E}^4$ be a tube surface at a distance r from the spine curve $\alpha(t)$ according to Frenet frame $\{\mathbf{T}, \mathbf{N}, \mathbf{B}_1, \mathbf{B}_2\}$ with parametrization $\psi(t, v)$, given by $\psi: U \subset \mathbb{E}^2 \rightarrow \mathbb{E}^4$, $(t, v) \in U$ and let tangent space to M at a point $p \in \psi(t, v)$ be spanned by $\{\psi_t, \psi_v\}$. Then, the following statements hold:

1. Unit normal vector fields \mathbf{U}_1 and \mathbf{U}_2 of tube surface in \mathbb{E}^4 are obtained as

$$\mathbf{U}_1 = \frac{r\cos v\mathbf{T} + (\eta\sin v - 1)\mathbf{N} + \kappa\cos v\mathbf{B}_1 - r\kappa\sin v\mathbf{B}_2}{\sqrt{1 + \kappa^2(r^2 + \cos^2 v) + \eta^2\sin^2 v - 2\eta\sin v}}$$

and

$$\mathbf{U}_2 = \frac{-r\kappa\cos v(\kappa^2\cos^2 v + \eta^2\sin^2 v - \eta\sin v)\mathbf{T} + \kappa^2(r^2\eta\sin v + \cos^2 v)\mathbf{N}}{\kappa[1 + \eta^2 - 2\eta\sin v + r^2\kappa^2 + \cos^2 v(\kappa^2 - \eta^2)]^{3/2}[\kappa^2\cos^2 v + \eta^2\sin^2 v]\sqrt{\cos^2 v(1 + r^2\kappa^2) + r^2\eta^2\sin^2 v}} - \frac{\kappa\cos v(\eta\sin v - 1 - r^2\kappa^2)\mathbf{B}_1 + \kappa(r\cos^2 v\sin v(\kappa^2 - \eta^2) + r\eta^2\sin v - r\eta\sin^2 v)\mathbf{B}_2}{\kappa[1 + \eta^2 - 2\eta\sin v + r^2\kappa^2 + \cos^2 v(\kappa^2 - \eta^2)]^{3/2}[\kappa^2\cos^2 v + \eta^2\sin^2 v]\sqrt{\cos^2 v(1 + r^2\kappa^2) + r^2\eta^2\sin^2 v}}$$

respectively.

2. Gaussian curvature K_1 and Mean curvature H_1 of tube surface with unit normal vector fields \mathbf{U}_1 in \mathbb{E}^4 are obtained as

$$K_1 = \frac{r^2\kappa[\eta\sin v(\kappa + r\tau) + \cos^2 v(r^2\kappa^3 - r\kappa^2\tau - r^2\tau\eta^2 + \kappa) + \eta^2(r^2\kappa - \kappa - r\tau)]}{[r^2 + r^4(\kappa^2\cos^2 v + \eta^2\sin^2 v) - r^2\sin^2 v][1 + \cos^2 v(\kappa^2 - \eta^2) + r^2\kappa^2 + \eta^2 - 2\eta\sin v]}$$

and

$$H_1 = \frac{-r^2[\eta\sin v(\kappa + r\tau) + \cos^2 v(2r^2\kappa^3 - r\kappa^2\tau - 2r^2\kappa\eta^2 + r\tau\eta^2 + 2\kappa) + r\eta^2(2r\kappa - \tau)]}{[r^2 + r^4(\kappa^2\cos^2 v + \eta^2\sin^2 v) - r^2\sin^2 v][1 + \eta^2\sin^2 v + \kappa^2(\cos^2 v + r^2)]}$$

respectively.

3. Gaussian curvature K_2 and Mean curvature H_2 of tube surface with unit normal vector fields \mathbf{U}_2 in \mathbb{E}^4 are obtained as

$$K_2 = \frac{-\kappa^2\eta^2}{[\kappa^2\cos^2 v + \eta^2\sin^2 v][r^2\eta^2\sin^2 v + r^2\kappa^2\cos^2 v + \cos^2 v]}$$

and

$$H_2 = \frac{[-\kappa\eta\sin v + r\tau\cos^2 v(\kappa^2 - \eta^2) + r\tau\eta^2]}{[r^2\eta^2\sin^2 v + r^2\kappa^2\cos^2 v + \cos^2 v]\sqrt{\kappa^2\cos^2 v + \eta^2\sin^2 v}}$$

respectively.

Proof Tube surface, at a distance r from the spine curve $\alpha(t)$ with Frenet frame $\{\mathbf{T}, \mathbf{N}, \mathbf{B}_1, \mathbf{B}_2\}$ are parametrized by

$$\psi(t, v) = \alpha(t) + r(\cos v\mathbf{B}_1 + \sin v\mathbf{B}_2)$$

The partial derivatives of $\psi(t, v)$, with respect to t and v , are determined by

$$\psi_t = \mathbf{T} + r\kappa\cos v\mathbf{N} - r\eta\sin v\mathbf{B}_1 \quad (21)$$

and

$$\psi_v = r(-\sin v\mathbf{T} + \cos v\mathbf{B}_2). \quad (22)$$

Then, second order partial derivatives of $\psi(t, v)$, with respect to t and v , are given as

$$\psi_{tt} = -r\kappa^2\cos v\mathbf{T} + (\kappa + r\tau\eta\sin v)\mathbf{N} + r\kappa\tau\cos v\mathbf{B}_1 - r\eta^2\sin v\mathbf{B}_2 \quad (23)$$

$$\psi_{tv} = -r\kappa\sin v\mathbf{N} - r\eta\cos v\mathbf{B}_1 \quad (24)$$

and

$$\psi_{vv} = -r\cos v\mathbf{T} - r\sin v\mathbf{B}_2. \quad (25)$$

The unit normal vector fields \mathbf{U}_1 and \mathbf{U}_2 of the surface should be provided with the following conditions

$$\begin{aligned} \langle \psi_t, \mathbf{U}_1 \rangle &= 0 & \langle \psi_t, \mathbf{U}_2 \rangle &= 0 \\ \langle \psi_v, \mathbf{U}_1 \rangle &= 0 & \langle \psi_v, \mathbf{U}_2 \rangle &= 0 \quad \text{and} \quad \langle \mathbf{U}_1, \mathbf{U}_2 \rangle = 0 \\ \langle \mathbf{U}_1, \mathbf{U}_1 \rangle &= 1 & \langle \mathbf{U}_2, \mathbf{U}_2 \rangle &= 1 \end{aligned} \quad (26)$$

where ψ_t and ψ_v are the partial derivatives of $\psi(t, v)$, with respect to t and v .

The unit normal vector field \mathbf{U}_1 of tube surface is obtained as

$$\mathbf{U}_1 = \frac{r\cos v\mathbf{T} + (\eta\sin v - 1)\mathbf{N} + \kappa\cos v\mathbf{B}_1 - r\kappa\sin v\mathbf{B}_2}{\sqrt{1 + \kappa^2(r^2 + \cos^2 v) + \eta^2\sin^2 v - 2\eta\sin v}} \quad (27)$$

using equation

$$\mathbf{U}_1 = \frac{a_1\mathbf{T} + a_2\mathbf{N} + a_3\mathbf{B}_1 + a_4\mathbf{B}_2}{\sqrt{a_1^2 + a_2^2 + a_3^2 + a_4^2}}$$

where $a_3 = \cos v$ and $a_1 = r\tau\cos v$ then $a_4 = \sin v$ and $a_2 = 1$. Since $\langle \mathbf{U}_1, \mathbf{U}_1 \rangle = 1$, \mathbf{U}_1 is the unit normal vector field of the tube surface. Then using methods of Gram Schmidt with \mathbf{U}_1 , the unit vector field \mathbf{U}_2 is given as

$$\mathbf{U}_2 = \frac{-r\kappa\cos v(\kappa^2\cos^2 v + \eta^2\sin^2 v - \eta\sin v)\mathbf{T} + \kappa^2(r^2\eta\sin v + \cos^2 v)\mathbf{N}}{\kappa[1 + \eta^2 - 2\eta\sin v + r^2\kappa^2 + \cos^2 v(\kappa^2 - \eta^2)]^{3/2}[\kappa^2\cos^2 v + \eta^2\sin^2 v]\sqrt{\cos^2 v(1 + r^2\kappa^2) + r^2\eta^2\sin^2 v}} \quad (28)$$

$$\frac{\kappa\cos v(\eta\sin v - 1 - r^2\kappa^2)\mathbf{B}_1 + \kappa(r\cos^2 v\sin v(\kappa^2 - \eta^2) + r\eta^2\sin v - r\eta\sin^2 v)\mathbf{B}_2}{\kappa[1 + \eta^2 - 2\eta\sin v + r^2\kappa^2 + \cos^2 v(\kappa^2 - \eta^2)]^{3/2}[\kappa^2\cos^2 v + \eta^2\sin^2 v]\sqrt{\cos^2 v(1 + r^2\kappa^2) + r^2\eta^2\sin^2 v}}$$

Using equation (26), the vector fields \mathbf{U}_1 and \mathbf{U}_2 are identified as unit normal vector fields for the tube surfaces. By substituting equations (21) and (22) into equation (5), the coefficients of the first fundamental form for the tube surfaces

$$\begin{aligned} E &= 1 + r^2\kappa^2\cos^2v + r^2\eta^2\cos^2v \\ F &= -r\sin v \\ G &= r^2 \end{aligned} \quad (29)$$

and

$$W = r^2 + r^4(\kappa^2\cos^2v + \eta^2\sin^2v) - r^2\sin^2v$$

are subsequently derived.

Equations (6), (23), (24), (25), and (27) lead to the coefficients of the second fundamental form of the tube surface with the unit vector field \mathbf{U}_1 in \mathbb{E}^4 obtained as,

$$\begin{aligned} L_1 &= \frac{\eta\sin v(r\tau - \kappa) + \kappa + r\tau\cos^2v(\eta^2 - \kappa^2) + r^2\kappa\cos^2v(\kappa^2 - \eta^2) + r\eta^2(r\kappa - \tau)}{(1 + \kappa^2(r^2 + \cos^2v) + \eta^2\sin^2v - 2\eta\sin v)^{1/2}} \\ M_1 &= \frac{r\kappa(\sin v - \eta)}{(1 + \kappa^2(r^2 + \cos^2v) + \eta^2\sin^2v - 2\eta\sin v)^{1/2}} \\ N_1 &= \frac{-r^2\kappa}{(1 + \kappa^2(r^2 + \cos^2v) + \eta^2\sin^2v - 2\eta\sin v)^{1/2}}. \end{aligned} \quad (30)$$

Substituting equations (29) and (30) into equation (7) implies that Gaussian and mean curvatures with respect to \mathbf{U}_1 following as

$$K_1 = \frac{r^2\kappa[\eta\sin v(\kappa + r\tau) + \cos^2v(r^2\kappa^3 - r\kappa^2\tau - r^2\tau\eta^2 + \kappa) + \eta^2(r^2\kappa - \kappa - r\tau)]}{[r^2 + r^4(\kappa^2\cos^2v + \eta^2\sin^2v) - r^2\sin^2v][1 + \cos^2v(\kappa^2 - \eta^2) + r^2\kappa^2 + \eta^2 - 2\eta\sin v]}$$

and

$$H_1 = \frac{-r^2[\eta\sin v(\kappa + r\tau) + \cos^2v(2r^2\kappa^3 - r\kappa^2\tau - 2r^2\kappa\eta^2 + r\tau\eta^2 + 2\kappa) + r\eta^2(2r\kappa - \tau)]}{[r^2 + r^4(\kappa^2\cos^2v + \eta^2\sin^2v) - r^2\sin^2v][1 + \eta^2\sin^2v + \kappa^2(\cos^2v + r^2)]}$$

equations (6), (23), (24), (3), and (28) lead to the coefficients of the second fundamental form of the tube surface with the unit vector field \mathbf{U}_2 in \mathbb{E}^4 obtained as,

$$\begin{aligned} L_2 &= \frac{\kappa\eta\sin v + r\tau\eta^2 + r\tau\cos^2v(\kappa^2 - \eta^2)}{\sqrt{\kappa^2\cos^2v + \eta^2\sin^2v}} \\ M_2 &= \frac{-r\kappa\eta}{\sqrt{\kappa^2\cos^2v + \eta^2\sin^2v}} \\ N_2 &= 0 \end{aligned} \quad (31)$$

Substituting equations (29) and (31) into equation (7) implies that Gaussian and mean curvatures with respect to \mathbf{U}_2 following as

$$K_2 = \frac{-\kappa^2 \eta^2}{[\kappa^2 \cos^2 v + \eta^2 \sin^2 v][r^2 \eta^2 \sin^2 v + r^2 \kappa^2 \cos^2 v + \cos^2 v]}$$

and

$$H_2 = \frac{[-\kappa \eta \sin v + r \tau \cos^2 v (\kappa^2 - \eta^2) + r \tau \eta^2]}{[r^2 \eta^2 \sin^2 v + r^2 \kappa^2 \cos^2 v + \cos^2 v] \sqrt{\kappa^2 \cos^2 v + \eta^2 \sin^2 v}}$$

Corollary If the Gaussian and mean curvatures corresponding to the unit normal vector fields obtained for the Frenet vectors \mathbf{T} and \mathbf{B}_2 are similarly calculated using the shape operators corresponding to the unit normal vector fields, the same result is obtained.

Example 1 Let $\alpha(s)$ be a centre curve with Frenet frame of tube surface in \mathbb{E}^4 such as

$$\alpha(t) = \left(\sqrt{3} \cos \frac{s}{\sqrt{7}} - \frac{\sqrt{5}}{2}, -2 + \sqrt{3} \sin \frac{s}{\sqrt{7}}, 5 + \cos \frac{2s}{\sqrt{7}}, \sin \frac{2s}{\sqrt{7}} \right) \quad (32)$$

From $\|\alpha(s)\| = 1$, it is easy to see that Frenet vectors are given as

$$\begin{aligned} \mathbf{T} &= \left(-\frac{\sqrt{3}}{\sqrt{7}} \sin \frac{s}{\sqrt{7}}, \frac{\sqrt{3}}{\sqrt{7}} \cos \frac{s}{\sqrt{7}}, -\frac{2}{\sqrt{7}} \sin \frac{2s}{\sqrt{7}}, \frac{2}{\sqrt{7}} \cos \frac{2s}{\sqrt{7}} \right) \\ \mathbf{N} &= \left(-\frac{\sqrt{3}}{\sqrt{19}} \cos \frac{s}{\sqrt{7}}, -\frac{\sqrt{3}}{\sqrt{19}} \sin \frac{s}{\sqrt{7}}, -\frac{4}{\sqrt{19}} \cos \frac{2s}{\sqrt{7}}, -\frac{4}{\sqrt{19}} \sin \frac{2s}{\sqrt{7}} \right) \\ \mathbf{B}_1 &= \left(\frac{2}{\sqrt{7}} \sin \frac{s}{\sqrt{7}}, -\frac{2}{\sqrt{7}} \cos \frac{s}{\sqrt{7}}, -\frac{\sqrt{3}}{\sqrt{7}} \sin \frac{2s}{\sqrt{7}}, \frac{\sqrt{3}}{\sqrt{7}} \cos \frac{2s}{\sqrt{7}} \right) \\ \mathbf{B}_2 &= \left(\frac{4\sqrt{3}}{\sqrt{57}} \cos \frac{s}{\sqrt{7}}, \frac{4\sqrt{3}}{\sqrt{57}} \sin \frac{s}{\sqrt{7}}, -\frac{3}{\sqrt{57}} \cos \frac{2s}{\sqrt{7}}, -\frac{3}{\sqrt{57}} \sin \frac{2s}{\sqrt{7}} \right) \end{aligned} \quad (33)$$

and from equation (3), Frenet curvatures are given as

$$\kappa = \frac{19}{7\sqrt{19}}, \quad \tau = -\frac{6\sqrt{3}}{7\sqrt{19}} \text{ and } \eta = \frac{2}{\sqrt{19}}.$$

Substituting equations (32) and (33) into equation (5), the tube surface formed by the Frenet vectors \mathbf{T} and \mathbf{B}_1 is parametrized as

$$\begin{aligned}
\psi(s, v) = & \left(\sqrt{3}\cos\frac{s}{\sqrt{7}} - \frac{\sqrt{5}}{2} + r \left(-\frac{\sqrt{3}}{\sqrt{7}}\sin\frac{s}{\sqrt{7}}\cos v + \frac{2}{\sqrt{7}}\sin\frac{s}{\sqrt{7}}\sin v \right), \right. \\
& -2 + \sqrt{3}\sin\frac{s}{\sqrt{7}} + r \left(\frac{\sqrt{3}}{\sqrt{7}}\cos\frac{s}{\sqrt{7}}\cos v - \frac{2}{\sqrt{7}}\cos\frac{s}{\sqrt{7}}\sin v \right), \\
& 5 + \cos\frac{2s}{\sqrt{7}} + r \left(-\frac{2}{\sqrt{7}}\sin\frac{2s}{\sqrt{7}}\cos v - \frac{\sqrt{3}}{\sqrt{7}}\sin\frac{2s}{\sqrt{7}}\sin v \right), \\
& \left. \sin\frac{2s}{\sqrt{7}} + r \left(\frac{2}{\sqrt{7}}\cos\frac{2s}{\sqrt{7}}\cos v + \frac{\sqrt{3}}{\sqrt{7}}\cos\frac{2s}{\sqrt{7}}\sin v \right) \right).
\end{aligned}$$

Hence for $r = 7$, it is easily say that

$$\begin{aligned}
\psi(s, v) = & \left(\sqrt{3}\cos\frac{s}{\sqrt{7}} - \frac{\sqrt{5}}{2} + \frac{7\sqrt{3}}{\sqrt{7}}\sin\frac{s}{\sqrt{7}}\cos v + \frac{14}{\sqrt{7}}\sin\frac{s}{\sqrt{7}}\sin v, \right. \\
& -2 + \sqrt{3}\sin\frac{s}{\sqrt{7}} + \frac{7\sqrt{3}}{\sqrt{7}}\cos\frac{s}{\sqrt{7}}\cos v - \frac{14}{\sqrt{7}}\cos\frac{s}{\sqrt{7}}\sin v, \\
& 5 + \cos\frac{2s}{\sqrt{7}} - \frac{14}{\sqrt{7}}\sin\frac{2s}{\sqrt{7}}\cos v - \frac{7\sqrt{3}}{\sqrt{7}}\sin\frac{2s}{\sqrt{7}}\sin v, \\
& \left. \sin\frac{2s}{\sqrt{7}} + \frac{14}{\sqrt{7}}\cos\frac{2s}{\sqrt{7}}\cos v + \frac{7\sqrt{3}}{\sqrt{7}}\cos\frac{2s}{\sqrt{7}}\sin v \right).
\end{aligned} \tag{34}$$

Then for $r = 7$, the unit normal vector fields in equation (35) of tube surface are given as

$$\begin{aligned}
u_1 = & \frac{1}{\sqrt{16 + 3\cos^2 v + 6\sqrt{3}\sin 2v}} \left(0, -\frac{14}{\sqrt{19}}\sin v, 0, \frac{19\cos v + 6\sqrt{3}\sin v}{\sqrt{19}} \right) \\
u_2 = & \frac{\sqrt{4 + \cos^2 v + 3\sqrt{3}\cos v \sin v}}{\sqrt{16 + 3\cos^2 v + 6\sqrt{3}\sin 2v}} \left(\frac{\cos v}{2}, \frac{-\cos v \sqrt{19}(19\cos v + 6\sqrt{3}\sin v)}{38(16 + 3\cos^2 v + 6\sqrt{3}\sin 2v)}, \frac{\sin v}{2}, \frac{-7\cos v \sin v}{(16 + 3\cos^2 v + 6\sqrt{3}\sin 2v)\sqrt{19}} \right)
\end{aligned} \tag{35}$$

Gaussian and mean curvatures in equations (36) and (37) of tube surface are given as

$$\begin{aligned}
K_1 = & \frac{-1}{48\sqrt{3}\sin 2v + 64 + \cos^2 v(21\sqrt{3}\cos v \sin v - 105\cos^2 v + 136)} \\
H_1 = & \frac{\sin v}{2(4 + \cos^2 v + 3\sqrt{3}\cos v \sin v)\sqrt{4\sqrt{3}\sin 2v + 16 + 3\cos^2 v}}
\end{aligned} \tag{36}$$

and

$$\begin{aligned}
K_2 = & \frac{\cos^2 v(2142\cos^4 v + 2394\sqrt{3}\cos^3 v \sin v + 8076\cos^2 v - 4425\sqrt{3}\cos v \sin v - 11726) - 2048 - 2328\sqrt{3}\sin 2v}{392(-256 + \cos^2 v(294\cos^4 v + 294\sqrt{3}\cos^3 v \sin v + 959\cos^2 v - 294\sqrt{3}\sin 2v - 1472) + 288\sqrt{3}\sin 2v)} \\
H_2 = & -\frac{264 + 3\sqrt{3}\cos v \sin v(129 + 28\cos^2 v) + 4\cos^2 v(134 - 105\cos^2 v)}{[64 + \cos^2 v(136 - 105\cos^2 v) + \sqrt{3}\cos v \sin v(96 + 21\cos^2 v)]\sqrt{4\sqrt{3}\sin 2v + 16 + 3\cos^2 v}}
\end{aligned} \tag{37}$$

respectively. Finally for $r = 7$, a tube surface shown in Figure 1 is parametrized as

$$\begin{aligned} \psi(s, v) = & \left(\sqrt{3}\cos\frac{s}{\sqrt{7}} - \frac{\sqrt{5}}{2} + -\frac{7\sqrt{3}}{\sqrt{7}}\sin\frac{s}{\sqrt{7}}\cos v + \frac{14}{\sqrt{7}}\sin\frac{s}{\sqrt{7}}\sin v, \right. \\ & -2 + \sqrt{3}\sin\frac{s}{\sqrt{7}} + \frac{7\sqrt{3}}{\sqrt{7}}\cos\frac{s}{\sqrt{7}}\cos v - \frac{14}{\sqrt{7}}\cos\frac{s}{\sqrt{7}}\sin v, \\ & \left. 5 + \cos\frac{2s}{\sqrt{7}} - \frac{14}{\sqrt{7}}\sin\frac{2s}{\sqrt{7}}\cos v - \frac{7\sqrt{3}}{\sqrt{7}}\sin\frac{2s}{\sqrt{7}}\sin v \right) \end{aligned}$$

in projection space, xyz . Finally for $r = 7$, a tube surface shown in Figure 1 is parametrized as

$$\begin{aligned} \psi(s, v) = & \left(\sqrt{3}\cos\frac{s}{\sqrt{7}} - \frac{\sqrt{5}}{2} + -\frac{7\sqrt{3}}{\sqrt{7}}\sin\frac{s}{\sqrt{7}}\cos v + \frac{14}{\sqrt{7}}\sin\frac{s}{\sqrt{7}}\sin v, \right. \\ & -2 + \sqrt{3}\sin\frac{s}{\sqrt{7}} + \frac{7\sqrt{3}}{\sqrt{7}}\cos\frac{s}{\sqrt{7}}\cos v - \frac{14}{\sqrt{7}}\cos\frac{s}{\sqrt{7}}\sin v, \\ & \left. \sin\frac{2s}{\sqrt{7}} + \frac{14}{\sqrt{7}}\cos\frac{2s}{\sqrt{7}}\cos v + \frac{7\sqrt{3}}{\sqrt{7}}\cos\frac{2s}{\sqrt{7}}\sin v \right) \end{aligned}$$

in projection space, xyt . Finally for $r = 7$, a tube surface shown in Figure 1 is parametrized as

$$\begin{aligned} \psi(s, v) = & \left(\sqrt{3}\cos\frac{s}{\sqrt{7}} - \frac{\sqrt{5}}{2} + -\frac{7\sqrt{3}}{\sqrt{7}}\sin\frac{s}{\sqrt{7}}\cos v + \frac{14}{\sqrt{7}}\sin\frac{s}{\sqrt{7}}\sin v, \right. \\ & 5 + \cos\frac{2s}{\sqrt{7}} - \frac{14}{\sqrt{7}}\sin\frac{2s}{\sqrt{7}}\cos v - \frac{7\sqrt{3}}{\sqrt{7}}\sin\frac{2s}{\sqrt{7}}\sin v, \\ & \left. \sin\frac{2s}{\sqrt{7}} + \frac{14}{\sqrt{7}}\cos\frac{2s}{\sqrt{7}}\cos v + \frac{7\sqrt{3}}{\sqrt{7}}\cos\frac{2s}{\sqrt{7}}\sin v \right) \end{aligned}$$

in projection space, xzt . Finally for $r = 7$, a tube surface shown in Figure 1 is parametrized as

$$\begin{aligned} \psi(s, v) = & \left(-2 + \sqrt{3}\sin\frac{s}{\sqrt{7}} + \frac{7\sqrt{3}}{\sqrt{7}}\cos\frac{s}{\sqrt{7}}\cos v - \frac{14}{\sqrt{7}}\cos\frac{s}{\sqrt{7}}\sin v, \right. \\ & 5 + \cos\frac{2s}{\sqrt{7}} - \frac{14}{\sqrt{7}}\sin\frac{2s}{\sqrt{7}}\cos v - \frac{7\sqrt{3}}{\sqrt{7}}\sin\frac{2s}{\sqrt{7}}\sin v, \\ & \left. \sin\frac{2s}{\sqrt{7}} + \frac{14}{\sqrt{7}}\cos\frac{2s}{\sqrt{7}}\cos v + \frac{7\sqrt{3}}{\sqrt{7}}\cos\frac{2s}{\sqrt{7}}\sin v \right) \end{aligned}$$

in projection space, yzt .

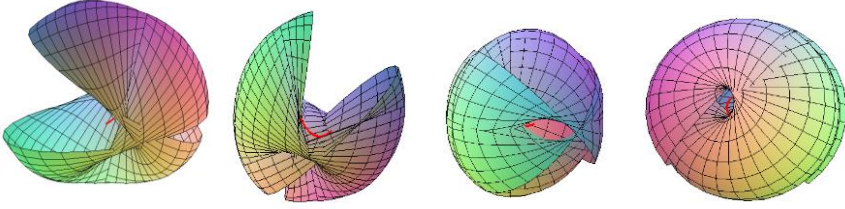


Figure 1 Tube surfaces in xyz, xyt, xzt and yzt projection spaces.

The tube surface formed by the Frenet vectors \mathbf{T} and \mathbf{B}_2 in \mathbb{E}^4 is parametrized as

$$\begin{aligned} \psi(s, v) = & \left(\sqrt{3}\cos\frac{s}{\sqrt{7}} - \frac{\sqrt{5}}{2} + r \left(-\frac{\sqrt{3}}{\sqrt{7}}\sin\frac{s}{\sqrt{7}}\cos v + \frac{4\sqrt{3}}{\sqrt{57}}\cos\frac{s}{\sqrt{7}}\sin v \right), \right. \\ & -2 + \sqrt{3}\sin\frac{s}{\sqrt{7}} + r \left(\frac{\sqrt{3}}{\sqrt{7}}\cos\frac{s}{\sqrt{7}}\cos v + \frac{4\sqrt{3}}{\sqrt{57}}\sin\frac{s}{\sqrt{7}}\sin v \right), \\ & 5 + \cos\frac{2s}{\sqrt{7}} + r \left(-\frac{2}{\sqrt{7}}\sin\frac{2s}{\sqrt{7}}\cos v - \frac{3}{\sqrt{57}}\cos\frac{2s}{\sqrt{7}}\sin v \right), \\ & \left. \sin\frac{2s}{\sqrt{7}} + r \left(\frac{2}{\sqrt{7}}\cos\frac{2s}{\sqrt{7}}\cos v - \frac{3}{\sqrt{57}}\sin\frac{2s}{\sqrt{7}}\sin v \right) \right) \end{aligned}$$

Hence for $r = 7$, it is easily say that

$$\begin{aligned} \psi(s, v) = & \left(\sqrt{3}\cos\frac{s}{\sqrt{7}} - \frac{\sqrt{5}}{2} - \frac{7\sqrt{3}}{\sqrt{7}}\sin\frac{s}{\sqrt{7}}\cos v + \frac{28\sqrt{3}}{\sqrt{57}}\cos\frac{s}{\sqrt{7}}\sin v, \right. \\ & -2 + \sqrt{3}\sin\frac{s}{\sqrt{7}} + \frac{7\sqrt{3}}{\sqrt{7}}\cos\frac{s}{\sqrt{7}}\cos v + \frac{28\sqrt{3}}{\sqrt{57}}\sin\frac{s}{\sqrt{7}}\sin v, \\ & 5 + \cos\frac{2s}{\sqrt{7}} - \frac{14}{\sqrt{7}}\sin\frac{2s}{\sqrt{7}}\cos v - \frac{21}{\sqrt{57}}\cos\frac{2s}{\sqrt{7}}\sin v, \\ & \left. \sin\frac{2s}{\sqrt{7}} + \frac{14}{\sqrt{7}}\cos\frac{2s}{\sqrt{7}}\cos v - \frac{21}{\sqrt{57}}\sin\frac{2s}{\sqrt{7}}\sin v \right) \end{aligned} \quad (38)$$

Then for $r = 7$, the unit normal vector fields in equation (39) of tube surface are given as

$$\begin{aligned} \mathbf{U}_1 = & \frac{1}{\sqrt{18816 + 165\cos^2 v - 196\sqrt{19}\sin v}} (133\cos v, \frac{7(-19 + 2\sqrt{19}\sin v)}{\sqrt{19}}, 19\cos v, 133\sin v) \quad (39) \\ \mathbf{U}_2 = & \frac{\sqrt{49 + 46\cos^2 v}\sqrt{3724 + 3135\cos^2 v}}{\Gamma[18816 + 165\cos^2 v - 196\sqrt{19}\sin v]} \left(\frac{\sqrt{19}\cos v(98\sqrt{19}\sin v - 165\cos^2 v - 196)}{2}, \frac{2(98\sin v + \sqrt{19}\cos^2 v)}{\sqrt{19}}, \right. \\ & \left. 7\sqrt{19}\cos v(190 - \sqrt{19}\sin v), \frac{-\sqrt{19}\sin v(98\sqrt{19}\sin v - 165\cos^2 v - 196)}{2} \right). \end{aligned}$$

respectively, where

$$\Gamma = \sqrt{15\cos^2v(2089132 + 1815\cos^2v) - 98\sqrt{19}(165\cos v \sin 2v - 392\sin v) + 3687936}.$$

Gaussian and mean curvatures in equations (40) and (41) of tube surface are given as

$$K_1 = \frac{1}{3724\Delta} [\sqrt{19}\cos^2v \sin v(156408\sqrt{3} - 84966 + 689871) + \cos v \sin v(1038597 + 256956\sqrt{3}) + \cos^4v(9693441 + 312816\sqrt{3} + 44688\sqrt{57}) - \sqrt{19}\cos v(500346 + 44688\sqrt{3}) - 406847 + \sin v\sqrt{3}(2013012\cos^3v + 70756) + \cos^3v(500346\sqrt{19} - 24738\sqrt{3}) - 2665322\cos^2v] \quad (40)$$

$$H_1 = \frac{\cos^4v(4332\sqrt{3} - 7581) - \cos v \sin v(16758\sqrt{3} + 11913) - 266\sqrt{19}\sin v + \cos^2v \sin v(532\sqrt{19} - 1083\cos v)}{532(4 + 3\sqrt{3}\cos v \sin v + \cos^2v)\sqrt{18816 - 196\sqrt{19}\sin v + 165\cos^2v} + \frac{\sqrt{19}\cos v(3724 + 168\sqrt{3}) - \cos^2v(6498\sqrt{3} + 96026 + 30324\sqrt{3}) - \sqrt{19}\cos^3v(3724 + 168\sqrt{3}) + 2427}{532(4 + 3\sqrt{3}\cos v \sin v + \cos^2v)\sqrt{18816 - 196\sqrt{19}\sin v + 165\cos^2v}}$$

and

$$K_2 = \frac{1}{6} [2\cos^4v(1131735\sqrt{19} + 5943504\sqrt{3}\sqrt{19} - 94125696\sqrt{3} - 139632652\cos^2v - 4014243464) - 47045881 - \sqrt{3}\cos^2v(11887008\sqrt{19} + 249627168) + \cos^2v(8468249869 + 2688728\sqrt{19}) + \sqrt{3}\cos v \sin 2v(60060672\sqrt{19} + 11887008) - \cos v \sin 2v(30224768\sqrt{19} + 12771458) + \cos^4v \sin v(30331392\sqrt{19} + 20013840\sqrt{3} + 1053360\sqrt{3}\sqrt{19}) + \sqrt{19}\cos^2v(14747040\sqrt{3} - 6144600) + \sqrt{19}\cos^3v(700707840 - 51480576\sqrt{3}) + \cos^5v(36733536\sqrt{3}\sqrt{19} - 694563240\sqrt{19} + 63377160) + \cos^5v \sin v(12414600\sqrt{3}\cos v - 72053520\sqrt{19}) + \sin 2v(14856594\sqrt{3} + 576156\sqrt{19}) - \cos^5v \sin v(1098133120 + 554131150\sqrt{3}) + \cos v(60657300\cos^7v - 71635396 + 8258236\cos^2v) + \cos^3v \sin v(3328898496\sqrt{3} - 37642192\sqrt{19} - 1456158480)] \quad (41)$$

$$H_2 = \frac{-7(294\sqrt{3}\sin 2v + 784 + 196\cos^2v)^{-1}\sqrt{3135\cos^2v + 3724\sqrt{49} - 46\cos^2v}}{4\sqrt{165\cos^2v + 196\sqrt{196\sqrt{19}\sin v} - 18816 - 165\cos^2v}} [\cos^5v(44688\sqrt{3} + 7644) - 6859 - \cos^4v \sin v(11172 + 6384\sqrt{3}) - \cos^3v(22344\sqrt{3} + 14224 + 21448\sqrt{19}\sin v) + \cos^4v(13056\sqrt{19} + 63840\sqrt{3}\sqrt{19}) + \cos^2v \sin v(9576\sqrt{3} - 134064) + \sqrt{57}\cos^3v \sin v(6684 + 3960\cos^2v) + 990\sqrt{19}\cos^6v + \cos v(6580 - 22344\sqrt{3}) + \cos^2v(13419 - 95760\sqrt{3}\sqrt{19} + 14112\sqrt{19}) + \sin 2v(1176\sqrt{19}\sqrt{3} + 2166\sqrt{3} + 85036\sqrt{19})]$$

respectively, where

$$\Delta = \cos v \sin v(56448\sqrt{3} - 196\sqrt{19}\cos v + 495\sqrt{3}\cos^2v) + 75264 - 784\sqrt{19}\sin v + \cos^2v(19476 + 165\cos^2v) + 588\sqrt{57}\cos v(\cos v - 1).$$

and

$$\theta = \sqrt{3}\cos^3v(2620863\sin v + 1764\sqrt{19}) + \sqrt{3}\cos v(2765952\sin v - 28812\sqrt{19}) + \cos^4v(903981 - 9016\sqrt{19}\sin v) - 38416\sqrt{19}\sin v + 3687936 + \sqrt{57}\cos^5v(27048 + 22770\sin v) + 7590\cos^5v + \cos^2v(4416468 - 45668\sqrt{19}\sin v).$$

Finally for $r = 7$, a tube surface shown in Figure 2 is parametrized as

$$\psi(s, v) = \left(\sqrt{3}\cos \frac{s}{\sqrt{7}} - \frac{\sqrt{5}}{2} - \frac{7\sqrt{3}}{\sqrt{7}} \sin \frac{s}{\sqrt{7}} \cos v + \frac{28\sqrt{3}}{\sqrt{57}} \cos \frac{s}{\sqrt{7}} \sin v, \right. \\ \left. -2 + \sqrt{3}\sin \frac{s}{\sqrt{7}} + \frac{7\sqrt{3}}{\sqrt{7}} \cos \frac{s}{\sqrt{7}} \cos v + \frac{28\sqrt{3}}{\sqrt{57}} \sin \frac{s}{\sqrt{7}} \sin v, \right. \\ \left. 5 + \cos \frac{2s}{\sqrt{7}} - \frac{14}{\sqrt{7}} \sin \frac{2s}{\sqrt{7}} \cos v - \frac{21}{\sqrt{57}} \cos \frac{2s}{\sqrt{7}} \sin v \right)$$

in projection space, xyz . Finally for $r = 7$, a tube surface shown in Figure 2 is parametrized as

$$\psi(s, v) = \left(\sqrt{3}\cos\frac{s}{\sqrt{7}} - \frac{\sqrt{5}}{2} - \frac{7\sqrt{3}}{\sqrt{7}}\sin\frac{s}{\sqrt{7}}\cos v + \frac{28\sqrt{3}}{\sqrt{57}}\cos\frac{s}{\sqrt{7}}\sin v, \right. \\ \left. -2 + \sqrt{3}\sin\frac{s}{\sqrt{7}} + \frac{7\sqrt{3}}{\sqrt{7}}\cos\frac{s}{\sqrt{7}}\cos v + \frac{28\sqrt{3}}{\sqrt{57}}\sin\frac{s}{\sqrt{7}}\sin v, \right. \\ \left. \sin\frac{2s}{\sqrt{7}} + \frac{14}{\sqrt{7}}\cos\frac{2s}{\sqrt{7}}\cos v - \frac{21}{\sqrt{57}}\sin\frac{2s}{\sqrt{7}}\sin v \right)$$

in projection space, xyt . Finally for $r = 7$, a tube surface shown in Figure 2 is parametrized as

$$\psi(s, v) = \left(\sqrt{3}\cos\frac{s}{\sqrt{7}} - \frac{\sqrt{5}}{2} - \frac{7\sqrt{3}}{\sqrt{7}}\sin\frac{s}{\sqrt{7}}\cos v + \frac{28\sqrt{3}}{\sqrt{57}}\cos\frac{s}{\sqrt{7}}\sin v, \right. \\ \left. 5 + \cos\frac{2s}{\sqrt{7}} - \frac{14}{\sqrt{7}}\sin\frac{2s}{\sqrt{7}}\cos v - \frac{21}{\sqrt{57}}\cos\frac{2s}{\sqrt{7}}\sin v, \right. \\ \left. \sin\frac{2s}{\sqrt{7}} + \frac{14}{\sqrt{7}}\cos\frac{2s}{\sqrt{7}}\cos v - \frac{21}{\sqrt{57}}\sin\frac{2s}{\sqrt{7}}\sin v \right)$$

in projection space, xzt . Finally for $r = 7$, a tube surface shown in Figure 2 is parametrized as

$$\psi(s, v) = \left(-2 + \sqrt{3}\sin\frac{s}{\sqrt{7}} + \frac{7\sqrt{3}}{\sqrt{7}}\cos\frac{s}{\sqrt{7}}\cos v + \frac{28\sqrt{3}}{\sqrt{57}}\sin\frac{s}{\sqrt{7}}\sin v, \right. \\ \left. 5 + \cos\frac{2s}{\sqrt{7}} - \frac{14}{\sqrt{7}}\sin\frac{2s}{\sqrt{7}}\cos v - \frac{21}{\sqrt{57}}\cos\frac{2s}{\sqrt{7}}\sin v, \right. \\ \left. \sin\frac{2s}{\sqrt{7}} + \frac{14}{\sqrt{7}}\cos\frac{2s}{\sqrt{7}}\cos v - \frac{21}{\sqrt{57}}\sin\frac{2s}{\sqrt{7}}\sin v \right)$$

in projection space, yzt .

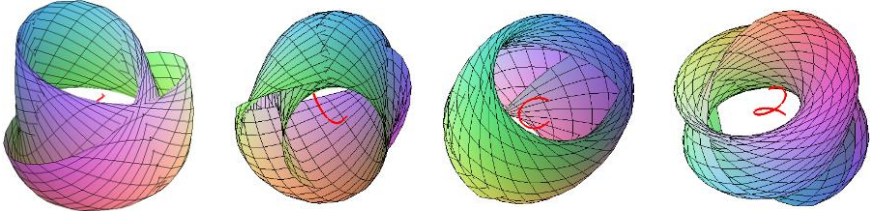


Figure 2 Tube surfaces in xyz, xyt, xzt and yzt projection spaces.

The visualization of all tube surfaces are given with using Maple programme.

CONCLUSION

In this study, using the parametrization of the tube, we investigate the tube surface generated by Frenet vectors T , B_1 and B_2 . The unit normal vector fields of this surface are obtained. In addition, Gaussian curvatures, mean curvatures, and first and second fundamental forms of this tube surface are calculated. An example is given and plotted in projection spaces.

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Chapter 2

Relations Between Quasi Frame and Frenet Frame In Euclidean 4-Space

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ÖZET

Bu çalışmada 4-boyutlu Öklid uzayında regüler bir eğri için Frenet çatısı ve quasi çatısı hakkında bilgi verilmiştir. 4-boyutlu Öklid uzayında bir uzay eğrisi, örneğin xy -düzlemindeki k_x ve k_y izdüşüm vektörleri olmak üzere t birim teğet, n_q birim quasi normal, b_{q1} birinci birim quasi binormal ve b_{q2} ise ikinci birim quasi binormal kullanılarak quasi çatısı ve quasi eğrilikleri verilmiştir. Sonra 4-boyutlu Öklid uzayında bir uzay eğrisi için Frenet çatısı ve quasi çatısı arasındaki geçiş matrisleri hesaplanmıştır. Ayrıca bu çatıların eğrilikleri arasındaki bağıntılar da verilmiştir. Bulunan bu hesapların daha anlaşılabilir olması adına 4-boyutlu Öklid uzayında bir uzay eğrisi için quasi çatı ve quasi eğriliklerinin elde edildiği bir örnek yapılmıştır.

Anahtar Kelimeler: Quasi çatı, Frenet çatısı, quasi eğrilikleri

ABSTRACT

In this paper we give information about the Frenet frame and quasi frame for a regular curve in 4-dimensional Euclidean space. For a space curve in 4-dimensional Euclidean space, e.g. \mathbf{k}_x and \mathbf{k}_y are projection vectors in the xy - plane, \mathbf{t} is the unit tangent, \mathbf{n}_q is the unit quasi normal, \mathbf{b}_{q1} is the first unit quasi binormal and \mathbf{b}_{q2} is the second unit quasi binormal, the quasi frame and quasi curvatures are given. Then, for a space curve in 4-dimensional Euclidean space, the transition matrices between the Frenet frame and the quasi frame are calculated. The relations between the curvatures of these frames are also given. In order to make these calculations more understandable, an example is given in which the quasi frame and quasi curvatures are obtained for a space curve in 4-dimensional Euclidean space.

Keywords: Quasi frame, Frenet frame, quasi curvatures

INTRODUCTION

The study of curves with in Euclidean 3-space is a key area in differential geometry, with the Frenet frame being particularly significant in classical geometry. However, the Frenet frame has certain limitations in practical applications, such as its inability to be defined when curvature is zero. Additionally, a major drawback of the Frenet frame is the unwanted rotation around the tangent vector (Bloomenthal, 1990). It's well understood that for a differentiable curve in an open interval, a set of mutually orthogonal unit vectors can be constructed at every point, known as the Frenet frame or moving frame vectors. The changes in these vectors along the curve define the curvatures of the curve. The collection of these vectors and curvatures is known as the Frenet apparatus of the curve. Recently, the theory of degenerate submanifolds has attracted attention, with extensions of classical differential geometry concepts being applied to Minkowski space (Turgut, 2009; Turgut and Yılmaz, 2008; Öztürk et al., 2014) and Galilean space (Magden and Yılmaz, 2014). The Bishop frame (Bishop, 1975), also called the parallel transport frame, provides an alternative framework for describing a moving frame, which remains well-defined even when the curve's second derivative is zero. By parallel transporting each element of an orthonormal frame along the curve in Euclidean 4-space, we achieve this frame. When curvatures vanish at certain points, the Frenet frame cannot be used, and the Bishop frame takes its place (Bishop, 1975). For curves with unit speed α in 4-dimensional Euclidean space E^4 , where $\alpha'' \neq 0$, Frenet curvature functions k_1 , k_2 and k_3 are provided by Alessio (Alessio, 2009). This concept was later extended to 4-dimensional space with the introduction of a parallel transport frame (Çelik et al., 2014). In four-dimensional Euclidean space, this parallel transport frame is known as the Bishop frame, and it has been discussed in various studies (Ateş et al., 2019; Körpınar and Turhan, 2013; Özdemir et al., 2015; Hanson and Ma, 1995). Klok (1987) introduced sweep surfaces using rotation-minimizing frames, and a reliable computation of the rotation-minimizing frame for such surfaces was presented by Wang et al. (2008). Coquillart's work (Coquillart, 1987) inspired Mustafa to develop a new adapted frame for space curves, termed the quasi-frame (O'Neil, 1983). Çelik et al. (2014) conducted further investigations into the parallel transport frame within four dimensional space. They introduced the quasi frame as an alternative to the Frenet frame, which offers computational ease without sacrificing precision. This quasi frame can be viewed as an extension of the parallel transport frame. The concept of the quasi frame is based on a constant projection vector and the Euclidean angle between the principal normal and the quasi-normal vector field (Dede et al., 2015). When the second derivative vanishes, the frame rotates by a Euclidean

angle, with the quasi-normal being the unit vector orthogonal to both the tangent and projection vectors. Several studies have been carried out in 4-dimensional space using this frame (Gezer and Ekici, 2023; Ekici Coşkun and Akça, 2023; Yağbasan et. al., 2023). This paper is structured as follows: We provide some basic definitions of Euclidean 4-space (E^4) and the quasi-frame in 4-space. We then introduce both the Frenet and quasi-frames for curves in 4-dimensional Euclidean space. Additionally, we derive the transition matrices between the Frenet and quasi-frames for a space curve in 4-dimensional space and establish the relationships between the curvatures of the two frames in Euclidean 4-space (E^4).

PRELIMINARIES

Let $\alpha(s) = \alpha: I \subset \mathbb{R} \rightarrow E^4$ be any space curve in Euclidean 4-space. Let $\mathbf{u} = (u_1, u_2, u_3, u_4)$, $\mathbf{v} = (v_1, v_2, v_3, v_4)$ and $\mathbf{w} = (w_1, w_2, w_3, w_4)$ be three vectors in E^4 , with the standard inner product as $\langle \mathbf{u}, \mathbf{v} \rangle = u_1v_1 + u_2v_2 + u_3v_3 + u_4v_4$. The norm of vector of E^4 is given by $\|\mathbf{u}\| = \sqrt{g(\mathbf{u}, \mathbf{u})}$. The curve α is said to be parametrized by arc length s if $g(\alpha', \alpha') = 1$. The vector product of $\mathbf{u}, \mathbf{v}, \mathbf{w}$ is given by the determinant as follows

$$\mathbf{u} \times \mathbf{v} \times \mathbf{w} = \begin{bmatrix} e_1 & e_2 & e_3 & e_4 \\ u_1 & u_2 & u_3 & u_4 \\ v_1 & v_2 & v_3 & v_4 \\ w_1 & w_2 & w_3 & w_4 \end{bmatrix},$$

where $e_1 \wedge e_2 \wedge e_3 = e_4$, $e_2 \wedge e_3 \wedge e_4 = e_1$, $e_3 \wedge e_4 \wedge e_1 = e_2$ and $e_4 \wedge e_1 \wedge e_2 = -e_3$ (Allesio, 2009; Elsayed et al., 2021).

Let u, v and w vectors in E^4 . If these vectors are linearly independent, then the vector $\mathbf{u} \wedge \mathbf{v} \wedge \mathbf{w} \in E^4$ is orthogonal to u, v , and w , and swapping any two vectors reverses the sign. If the vectors are linearly dependent, the cross product results in the zero vector. In four dimensions, $\mathbf{u} \wedge \mathbf{v}$ is undefined, as there is no determinant calculation of the 3×4 (Alessio, 2009).

The Frenet vectors for the curve with unit speed $\alpha: I \rightarrow E^4$ in Euclidean 4-space E^4 with $\alpha'' \neq 0$ are given by

$$\begin{aligned} \mathbf{t}(s) &= \alpha'(s) & \mathbf{n}(s) &= \frac{\alpha''(s)}{\|\alpha''(s)\|} \\ \mathbf{b}_2(s) &= \frac{\alpha'(s) \wedge \alpha''(s) \wedge \alpha'''(s)}{\|\alpha'(s) \wedge \alpha''(s) \wedge \alpha'''(s)\|} & \mathbf{b}_1(s) &= \mathbf{b}_2(s) \wedge \mathbf{t}(s) \wedge \mathbf{n}(s) \end{aligned} \quad (1)$$

(Alessio, 2009).

Given an $\alpha(t) = \alpha: I \subset \mathbb{R} \rightarrow E^4$ curve with arc parameter in 4-dimensional space. Let $\mathbf{t}(s) = \alpha'(s)$, representing the unit tangent vector of α at the point s . The first Serret-Frenet curvature of α is defined as $k_1(s) = \|\alpha''\|$. Then we have the Serret-Frenet formulae (Gluck, 1966):

$$\begin{aligned} \mathbf{t}'(s) &= k_1(s)\mathbf{n}(s) \\ \mathbf{n}'(s) &= -k_1(s)\mathbf{t}(s) + k_2(s)\mathbf{b}_1(s) \\ \mathbf{b}'_1(s) &= -k_2(s)\mathbf{n}(s) + k_3(s)\mathbf{b}_2(s) \\ \mathbf{b}'_2(s) &= -k_3(s)\mathbf{b}_1(s) \end{aligned} \quad (2)$$

Here Frenet curvatures $\kappa = k_1$, $\tau = k_2$ and $\eta = k_3$ are the first, second and third curvature functions of the α curve, respectively (Öztürt et al., 2017).

The transformation matrix should be chosen to keep the tangent vector \mathbf{t} unchanged. Then, we consider three possible planes of rotations for the Frenet vectors, $\{\mathbf{t}, \mathbf{n}, \mathbf{b}_1, \mathbf{b}_2\}$. The first rotation is in the space spanned by \mathbf{b}_1 and \mathbf{b}_2 with an angle ϕ . The second rotation in the space plane spanned by \mathbf{n} and \mathbf{b}_2 with an angle θ . The third rotation in the space plane spanned by \mathbf{n} and \mathbf{b}_1 with an angle ψ (Elsayied et. al. 2021). The transformation matrix M is of the form

$$M = \begin{bmatrix} 1 & 0 & 0 & 0 \\ 0 & \cos\theta\cos\psi & \cos\theta\sin\psi & -\sin\theta \\ 0 & \cos\psi\sin\theta\sin\phi - \cos\phi\sin\psi & \cos\phi\cos\psi + \sin\theta\sin\phi\sin\psi & \cos\theta\sin\phi \\ 0 & \cos\phi\cos\psi\sin\theta + \sin\phi\sin\psi & -\cos\psi\sin\phi + \cos\phi\sin\theta\sin\psi & \cos\theta\cos\phi \end{bmatrix}.$$

The quasi frame is an alternative to the Frenet frame, and involves a fixed unit vector \mathbf{k} . For a curve $\alpha(t)$ in E^3 , the quasi-frame consist of three orthogonal vectors called the unit tangent \mathbf{t} , the quasi-normal \mathbf{n}_q and the quasi-binormal \mathbf{b}_q with a Euclidean angle θ between the principal normal and quasi-normal. The quasi frame $\{\mathbf{t}, \mathbf{n}_q, \mathbf{b}_q, \mathbf{k}\}$ is defined by

$$\mathbf{t} = \frac{\alpha'}{\|\alpha'\|}, \quad \mathbf{n}_q = \frac{\mathbf{t} \wedge \mathbf{k}}{\|\mathbf{t} \wedge \mathbf{k}\|}, \quad \mathbf{b}_q = \mathbf{t} \wedge \mathbf{n}_q \quad (3)$$

where \mathbf{k} is the projection vector. The quasi frame becomes singular in all cases where \mathbf{t} and \mathbf{k} are parallel and in these cases we change the projection i.e. near a point where $\mathbf{t}=(0,0,1)$ we could choose $\mathbf{k}=(0,1,0)$ or $(1,0,0)$ but not $(0,0,1)$. Let θ be the angle between the vectors \mathbf{n} and \mathbf{n}_q given as in Figure 3.3 in Euclidean 3-space. The connection between the Frenet frame and the quasi-frame, as described by equation (3), is represented by

$$\begin{bmatrix} \mathbf{t} \\ \mathbf{n}_q \\ \mathbf{b}_q \end{bmatrix} = \begin{bmatrix} 1 & 0 & 0 \\ 0 & \cos\theta & \sin\theta \\ 0 & -\sin\theta & \cos\theta \end{bmatrix} \begin{bmatrix} \mathbf{t} \\ \mathbf{n} \\ \mathbf{b} \end{bmatrix}$$

(Dede et al., 2015). For the unit speed $\alpha(s)$ curve, the angle θ between \mathbf{n} normal and \mathbf{n}_q quasi-normal vectors is expressed in the form of a relationship between Frenet curvatures and quasi curvatures as

$$\begin{aligned} k_{q1} &= k_1 \cos\theta \\ k_{q2} &= -k_1 \sin\theta \\ k_{q3} &= d\theta + k_2 \end{aligned} \quad (4)$$

and angle θ as

$$\cos\theta = \frac{\det(\alpha'', \alpha', \kappa)}{\|\alpha' \wedge \kappa\| \|\alpha''\|}$$

(Dede et al., 2015). Let $\alpha = \alpha(s)$ be a space curve, the quasi frame in E^4 consists of four orthonormal vectors $\{\mathbf{t}, \mathbf{n}_q, \mathbf{b}_{q1}, \mathbf{b}_{q2}\}$, where \mathbf{t} is the unit tangent vector, \mathbf{n}_q is the quasi-normal vector field, \mathbf{b}_{q1} and \mathbf{b}_{q2} are the first and second quasi-binormals, respectively. The frame is given by

$$\begin{aligned} \mathbf{t} &= \frac{\alpha'(s)}{\|\alpha'(s)\|} & \mathbf{n}_q &= \frac{\mathbf{t} \wedge \mathbf{k}_x \wedge \mathbf{k}_y}{\|\mathbf{t} \wedge \mathbf{k}_x \wedge \mathbf{k}_y\|} \\ \mathbf{b}_{q2} &= \frac{\alpha'(s) \wedge \mathbf{n}_q \wedge \alpha'''(s)}{\|\alpha'(s) \wedge \mathbf{n}_q \wedge \alpha'''(s)\|} & \mathbf{b}_{q1} &= \mathbf{b}_{q2} \wedge \mathbf{t} \wedge \mathbf{n}_q \end{aligned} \quad (5)$$

where \mathbf{k}_x and \mathbf{k}_y are the projection vectors.

To simplify the calculations, we select $\mathbf{k}_x = (1,0,0,0)$ and $\mathbf{k}_y = (0,1,0,0)$. The expression becomes singular when \mathbf{t} is contained within the plane defined by \mathbf{k}_x and \mathbf{k}_y . In such instances, we can modify our projection vectors accordingly. Thus, we classified the quasi frame into six types; xy -plane, xz -plane, xt -plane, yz -plane, yt -plane and zt -plane directional quasi frames denoted by

$$\begin{aligned} &\{\mathbf{t}, \mathbf{n}_q, \mathbf{b}_{q1}, \mathbf{b}_{q2}, \mathbf{k}_x, \mathbf{k}_y\}, \{\mathbf{t}, \mathbf{n}_q, \mathbf{b}_{q1}, \mathbf{b}_{q2}, \mathbf{k}_y, \mathbf{k}_z\}, \{\mathbf{t}, \mathbf{n}_q, \mathbf{b}_{q1}, \mathbf{b}_{q2}, \mathbf{k}_x, \mathbf{k}_z\}, \\ &\{\mathbf{t}, \mathbf{n}_q, \mathbf{b}_{q1}, \mathbf{b}_{q2}, \mathbf{k}_y, \mathbf{k}_t\}, \{\mathbf{t}, \mathbf{n}_q, \mathbf{b}_{q1}, \mathbf{b}_{q2}, \mathbf{k}_x, \mathbf{k}_t\}, \{\mathbf{t}, \mathbf{n}_q, \mathbf{b}_{q1}, \mathbf{b}_{q2}, \mathbf{k}_z, \mathbf{k}_t\} \end{aligned} \quad (6)$$

with the projection vectors $\mathbf{k}_t = (0,0,0,1)$, $\mathbf{k}_z = (0,0,1,1)$, $\mathbf{k}_y = (0,1,0,0)$ and $\mathbf{k}_x = (1,0,0,0)$. Let $\alpha(s)$ be a curve without unit speed that is parameterized by s (Gezer and Ekici, 2023). By differentiating equation (5) with respect to s , we obtain the variation equations of the quasi-frame in the form

$$\begin{bmatrix} \mathbf{t}' \\ \mathbf{n}'_q \\ \mathbf{b}'_{q1} \\ \mathbf{b}'_{q2} \end{bmatrix} = \|\alpha'\| \begin{bmatrix} 0 & k_{q1} & k_{q2} & 0 \\ -k_{q1} & 0 & k_{q3} & 0 \\ -k_{q2} & -k_{q3} & 0 & k_{q4} \\ 0 & 0 & -k_{q4} & 0 \end{bmatrix} \begin{bmatrix} \mathbf{t} \\ \mathbf{n}_q \\ \mathbf{b}_{q1} \\ \mathbf{b}_{q2} \end{bmatrix}. \quad (7)$$

The q -curvatures (quasi-curvatures) are also

$$\begin{aligned} k_{q1} &= \frac{\langle \mathbf{t}', \mathbf{n}_q \rangle}{\|\alpha'\|} & k_{q2} &= \frac{\langle \mathbf{t}', \mathbf{b}_{q1} \rangle}{\|\alpha'\|} \\ k_{q3} &= \frac{\langle \mathbf{n}'_q, \mathbf{b}_{q1} \rangle}{\|\alpha'\|} & k_{q4} &= \frac{\langle \mathbf{b}'_{q1}, \mathbf{b}_{q2} \rangle}{\|\alpha'\|} \end{aligned} \quad (8)$$

In this here, when the fourth curvature k_{q4} calculated with respect to the quasi frame, is taken to be zero, the derivative formulas of the quasi frame for the space curve in 3-dimensional Euclidean space are obtained (Dede et al., 2015; Gezer and Ekici, 2023).

RELATIONS BETWEEN QUASI FRAME AND FRENET FRAME IN EUCLIDEAN 4-SPACE

In this section, we first have obtained the matrix forms in 4-dimensional Euclidean space in which we will express the relations that will make possible the transitions between the Frenet frame and the quasi frame.

Theorem 1 In 4-dimensional Euclidean space, let

$$M = \begin{bmatrix} 1 & 0 & 0 & 0 \\ 0 & \cos\theta\cos\psi & \cos\theta\sin\psi & \sin\theta \\ 0 & -\sin\psi\cos\phi - \sin\phi\sin\theta\cos\psi & \cos\psi\cos\phi - \sin\phi\sin\theta\sin\psi & \cos\theta\sin\phi \\ 0 & \sin\psi\sin\phi - \cos\psi\sin\theta\cos\phi & -\cos\phi\sin\theta\sin\psi - \cos\psi\sin\phi & \cos\theta\cos\phi \end{bmatrix}$$

be the transformation matrix, and the quasi frame vectors are $\{\mathbf{t}, \mathbf{n}_q, \mathbf{b}_{q1}, \mathbf{b}_{q2}\}$ and the Frenet frame vectors are $\{\mathbf{t}, \mathbf{n}, \mathbf{b}_1, \mathbf{b}_2\}$ the equality

$$\begin{bmatrix} \mathbf{t} \\ \mathbf{n}_q \\ \mathbf{b}_{q1} \\ \mathbf{b}_{q2} \end{bmatrix} = M \begin{bmatrix} \mathbf{t} \\ \mathbf{n} \\ \mathbf{b}_1 \\ \mathbf{b}_2 \end{bmatrix}$$

is satisfied.

Proof Let the tangent vector of the transformation matrix be chosen to remain unchanged. Consider three possible rotation planes where $\{\mathbf{t}, \mathbf{n}_q, \mathbf{b}_{q1}, \mathbf{b}_{q2}\}$ are quasi frame vectors and $\{\mathbf{t}, \mathbf{n}, \mathbf{b}_1, \mathbf{b}_2\}$ are Frenet frame vectors. The first return is taken such that the angle between the vectors \mathbf{b}_1 and \mathbf{b}_{q1} in the space covered by the first binormal \mathbf{b}_1 and the second binormal \mathbf{b}_2 is ϕ , as shown in Figure 1, then the inner product is $\langle \mathbf{b}_1, \mathbf{b}_{q1} \rangle = \cos \phi$.

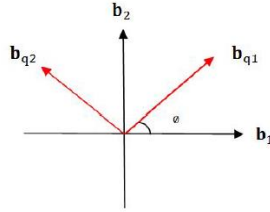


Figure 1 The first rotation plane, the plane $\text{Span}\{\mathbf{b}_1, \mathbf{b}_2\}$ at angle ϕ

Here are

$$\mathbf{b}_{q1} = \cos\phi \mathbf{b}_1 + \cos\left(\frac{\pi}{2} - \phi\right) \mathbf{b}_2$$

and

$$\mathbf{b}_{q2} = \cos\left(\frac{\pi}{2} + \phi\right) \mathbf{b}_1 + \sin\left(\frac{\pi}{2} - \phi\right) \mathbf{b}_2$$

and from here

$$\mathbf{b}_{q1} = \cos\phi \mathbf{b}_1 + \sin\phi \mathbf{b}_2$$

is written with

$$\mathbf{b}_{q2} = -\sin\phi \mathbf{b}_1 + \cos\phi \mathbf{b}_2$$

In that case,

$$\begin{bmatrix} \mathbf{t} \\ \mathbf{n}_q \\ \mathbf{b}_{q1} \\ \mathbf{b}_{q2} \end{bmatrix} = \begin{bmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & \cos\phi & \sin\phi \\ 0 & 0 & -\sin\phi & \cos\phi \end{bmatrix} \begin{bmatrix} \mathbf{t} \\ \mathbf{n} \\ \mathbf{b}_1 \\ \mathbf{b}_2 \end{bmatrix} \quad (9)$$

will be. If the angle between the normal vector \mathbf{n} and the second binormal vector \mathbf{b}_2 in the space they encompass is taken to be θ , as shown in Figure 2, then $\langle \mathbf{n}, \mathbf{n}_q \rangle = \cos \theta$.

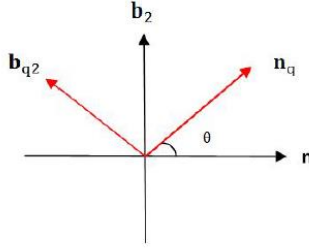


Figure 2 The second rotation plane, angle θ in the $\text{Span}\{\mathbf{n}, \mathbf{b}_2\}$

Since there will be

$$\mathbf{n}_q = \cos\theta \mathbf{n} + \sin\left(\frac{\pi}{2} - \theta\right) \mathbf{b}_2$$

and

$$\mathbf{b}_{q2} = \cos\left(\frac{\pi}{2} + \theta\right) \mathbf{n} + \sin\left(\frac{\pi}{2} - \theta\right) \mathbf{b}_2$$

here,

$$\mathbf{n}_q = \cos\theta \mathbf{n} + \sin \theta \mathbf{b}_2$$

and

$$\mathbf{b}_{q2} = \cos\theta \mathbf{b}_2 - \sin \theta \mathbf{n}$$

are written. Then it becomes

$$\begin{bmatrix} \mathbf{t} \\ \mathbf{n}_q \\ \mathbf{b}_{q1} \\ \mathbf{b}_{q2} \end{bmatrix} = \begin{bmatrix} 1 & 0 & 0 & 0 \\ 0 & \cos\theta & 0 & \sin\theta \\ 0 & 0 & 1 & 0 \\ 0 & -\sin\theta & 0 & \cos\theta \end{bmatrix} \begin{bmatrix} \mathbf{t} \\ \mathbf{n} \\ \mathbf{b}_1 \\ \mathbf{b}_2 \end{bmatrix} \quad (10)$$

The third rotation is taken such that the angle between the vector \mathbf{n} and the vector \mathbf{n}_q in the space formed by the normal vector \mathbf{t} and the first binormal vector \mathbf{b}_1 is ψ , as shown in Figure 3 which means $\langle \mathbf{n}, \mathbf{n}_q \rangle = \cos \psi$.

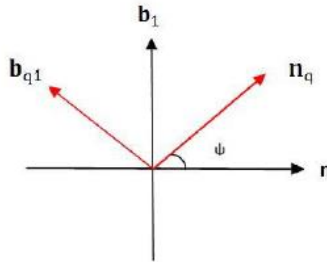


Figure 3 Third rotation plane, angle ψ in the $\text{Span}\{\mathbf{t}, \mathbf{b}_1\}$ plane

Since there are

$$\mathbf{n}_q = \cos\psi\mathbf{n} + \cos\left(\frac{\pi}{2} + \psi\right)\mathbf{b}_1$$

and

$$\mathbf{b}_{q1} = \cos\left(\frac{\pi}{2} + \left(\frac{\pi}{2} + \psi\right)\right)\mathbf{n} + \cos\left(\frac{\pi}{2} - \left(\frac{\pi}{2} - \psi\right)\right)\mathbf{b}_1$$

here

$$\mathbf{n}_q = \cos\psi\mathbf{n} + \sin\psi\mathbf{b}_1$$

and

$$\mathbf{b}_{q1} = -\sin\psi\mathbf{n} + \cos\psi\mathbf{b}_1$$

are written then it becomes,

$$\begin{bmatrix} \mathbf{t} \\ \mathbf{n}_q \\ \mathbf{b}_{q1} \\ \mathbf{b}_{q2} \end{bmatrix} = \begin{bmatrix} 1 & 0 & 0 & 0 \\ 0 & \cos\psi & \sin\psi & 0 \\ 0 & -\sin\psi & \cos\psi & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} \mathbf{t} \\ \mathbf{n} \\ \mathbf{b}_1 \\ \mathbf{b}_2 \end{bmatrix} \quad (11)$$

Accordingly, the transformation matrix M is written as

$$M = \left(\begin{bmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & \cos\phi & \sin\phi \\ 0 & 0 & -\sin\phi & \cos\phi \end{bmatrix} \begin{bmatrix} 1 & 0 & 0 & 0 \\ 0 & \cos\theta & 0 & \sin\theta \\ 0 & 0 & 1 & 0 \\ 0 & -\sin\theta & 0 & \cos\theta \end{bmatrix} \right) \begin{bmatrix} 1 & 0 & 0 & 0 \\ 0 & \cos\psi & \sin\psi & 0 \\ 0 & -\sin\psi & \cos\psi & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix}$$

It is also found as

$$M = \begin{bmatrix} 1 & 0 & 0 & 0 \\ 0 & \cos\theta\cos\psi & \cos\theta\sin\psi & \sin\theta \\ 0 & -\sin\psi\cos\phi - \sin\phi\sin\theta\cos\psi & \cos\psi\cos\phi - \sin\phi\sin\theta\sin\psi & \cos\theta\sin\phi \\ 0 & \sin\psi\sin\phi - \cos\psi\sin\theta\cos\phi & -\cos\phi\sin\theta\sin\psi - \cos\psi\sin\phi & \cos\theta\cos\phi \end{bmatrix}$$

from here. As a result, using M as the transformation matrix, the relationship between the Frenet frame and the quasi frame is derived as

$$\begin{bmatrix} \mathbf{t} \\ \mathbf{n}_q \\ \mathbf{b}_{q1} \\ \mathbf{b}_{q2} \end{bmatrix} = M \begin{bmatrix} \mathbf{t} \\ \mathbf{n} \\ \mathbf{b}_1 \\ \mathbf{b}_2 \end{bmatrix}.$$

Theorem 2 In 4-dimensional Euclidean space, let the inverse transformation matrix be

$$M^{-1} = \begin{bmatrix} 1 & 0 & 0 & 0 \\ 0 & \cos\theta\cos\psi & -\sin\theta\sin\phi\cos\psi - \sin\psi\cos\phi & -\sin\theta\cos\phi\cos\psi + \sin\psi\sin\phi \\ 0 & \sin\psi\cos\theta & -\sin\theta\sin\phi\sin\psi + \cos\psi\cos\phi & -\sin\theta\cos\phi\sin\psi - \sin\phi\cos\psi \\ 0 & \sin\theta & \sin\phi\cos\theta & \cos\theta\cos\phi \end{bmatrix}$$

and the quasi frame vectors be $\{\mathbf{t}, \mathbf{n}_q, \mathbf{b}_{q1}, \mathbf{b}_{q2}\}$ and the Frenet frame vectors be $\{\mathbf{t}, \mathbf{n}, \mathbf{b}_1, \mathbf{b}_2\}$ the equality

$$\begin{bmatrix} \mathbf{t} \\ \mathbf{n} \\ \mathbf{b}_1 \\ \mathbf{b}_2 \end{bmatrix} = M^{-1} \begin{bmatrix} \mathbf{t} \\ \mathbf{n}_q \\ \mathbf{b}_{q1} \\ \mathbf{b}_{q2} \end{bmatrix}$$

is satisfied.

Proof In the equalities (9), the expression \mathbf{b}_{q1} is expanded with $\cos\phi$ and the expression \mathbf{b}_{q2} is expanded with $(-\sin\phi)$. If these expressions are added side by side, we obtain the quality

$$\mathbf{b}_1 = \cos\phi\mathbf{b}_{q1} - \sin\phi\mathbf{b}_{q2}$$

Similarly, if the expression \mathbf{b}_{q1} is expanded with $\sin\phi$ and the expression \mathbf{b}_{q2} is expanded with $(\cos\phi)$, and if these expressions are added side by side, we arrive at the equation

$$\mathbf{b}_2 = \sin\phi\mathbf{b}_{q1} + \cos\phi\mathbf{b}_{q2}$$

$$\begin{bmatrix} \mathbf{t} \\ \mathbf{n} \\ \mathbf{b}_1 \\ \mathbf{b}_2 \end{bmatrix} = \begin{bmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & \cos\phi & \sin\phi \\ 0 & 0 & -\sin\phi & \cos\phi \end{bmatrix} \begin{bmatrix} \mathbf{t} \\ \mathbf{n}_q \\ \mathbf{b}_{q1} \\ \mathbf{b}_{q2} \end{bmatrix}$$

is written from here. In the equation (10), the expression \mathbf{n}_q is expanded with $\sin\theta$ and the expression \mathbf{b}_{q2} is expanded with $\cos\theta$, and if these expressions are added side by side, the equality

$$\mathbf{b}_2 = \sin\theta\mathbf{n}_q + \cos\theta\mathbf{b}_{q2}$$

is reached. In a similar manner, if the \mathbf{n}_q expression is expanded with $\cos\theta$ and the \mathbf{b}_{q2} expression is expanded with $(-\sin\theta)$, and these expressions are added side by side, the equality

$$\mathbf{n} = \cos\theta\mathbf{n}_q - \sin\theta\mathbf{b}_{q2}$$

is reached.

$$\begin{bmatrix} \mathbf{t} \\ \mathbf{n} \\ \mathbf{b}_1 \\ \mathbf{b}_2 \end{bmatrix} = \begin{bmatrix} 1 & 0 & 0 & 0 \\ 0 & \cos\theta & 0 & -\sin\theta \\ 0 & 0 & 1 & 0 \\ 0 & \sin\theta & 0 & \cos\theta \end{bmatrix} \begin{bmatrix} \mathbf{t} \\ \mathbf{n}_q \\ \mathbf{b}_{q1} \\ \mathbf{b}_{q2} \end{bmatrix}$$

is written from here. In equations (11), the expression \mathbf{n}_q is expanded with $\cos\psi$ and the expression \mathbf{b}_{q1} is expanded with $(-\sin\psi)$; if these expressions are summed side by side, the equality

$$\mathbf{n} = \cos\psi\mathbf{n}_q - \sin\psi\mathbf{b}_{q1}$$

is reached. Similarly, if the expression \mathbf{n}_q is expanded with $\sin\psi$ and the expression \mathbf{b}_{q1} is expanded with $\cos\psi$, and if these expressions are added side by side, the equality

$$\mathbf{b}_{q1} = \sin\psi\mathbf{n}_q + \cos\psi\mathbf{b}_{q1}$$

is reached.

$$\begin{bmatrix} \mathbf{t} \\ \mathbf{n} \\ \mathbf{b}_1 \\ \mathbf{b}_2 \end{bmatrix} = \begin{bmatrix} 1 & 0 & 0 & 0 \\ 0 & \cos\psi & -\sin\psi & 0 \\ 0 & \sin\psi & \cos\psi & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} \mathbf{t} \\ \mathbf{n}_q \\ \mathbf{b}_{q1} \\ \mathbf{b}_{q2} \end{bmatrix}$$

is written from here. Accordingly, the inverse transformation matrix is written as

$$M^{-1} = \begin{bmatrix} 1 & 0 & 0 & 0 \\ 0 & \cos\psi & -\sin\psi & 0 \\ 0 & \sin\psi & \cos\psi & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix} \left(\begin{bmatrix} 1 & 0 & 0 & 0 \\ 0 & \cos\theta & 0 & -\sin\theta \\ 0 & 0 & 1 & 0 \\ 0 & \sin\theta & 0 & \cos\theta \end{bmatrix} \begin{bmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & \cos\phi & -\sin\phi \\ 0 & 0 & \sin\phi & \cos\phi \end{bmatrix} \right)$$

such that $M M^{-1} = I$. From here,

$$M^{-1} = \begin{bmatrix} 1 & 0 & 0 & 0 \\ 0 & \cos\theta\cos\psi & -\sin\theta\sin\phi\cos\psi - \sin\psi\cos\phi & -\sin\theta\cos\phi\cos\psi + \sin\psi\sin\phi \\ 0 & \sin\psi\cos\theta & -\sin\theta\sin\phi\sin\psi + \cos\psi\cos\phi & -\sin\theta\cos\phi\sin\psi - \sin\phi\cos\psi \\ 0 & \sin\theta & \sin\phi\cos\theta & \cos\theta\cos\phi \end{bmatrix}$$

is found. The relationship between the Frenet frame and the quasi-frame can then be expressed as

$$\begin{bmatrix} \mathbf{t} \\ \mathbf{n} \\ \mathbf{b}_1 \\ \mathbf{b}_2 \end{bmatrix} = M^{-1} \begin{bmatrix} \mathbf{t} \\ \mathbf{n}_q \\ \mathbf{b}_{q1} \\ \mathbf{b}_{q2} \end{bmatrix}$$

with M^{-1} represents the inverse of the transformation matrix.

Theorem 3 For the curve $\alpha(s)$, $\|\alpha'(s)\| = 1$, the angle θ is normal and quasi-normal, the angle ϕ is first binormal and first quasi-binormal, and the angle ψ is given as the angles between the second binormal and second quasi-binormal vectors, in the form of the relationships between the quasi-curvatures and Frenet curvatures belonging to the space curve $\alpha(s)$

$$\begin{aligned} k_{q1} &= k_1 \cos\theta \cos\psi \\ k_{q2} &= k_1 (\sin\theta \sin\phi \cos\psi + \sin\psi \cos\phi) \\ k_{q3} &= (\sin\phi d\theta) + (\cos\phi \cos\theta d\psi) + k_2 (\cos\theta \cos\phi) \\ &\quad + k_3 (\sin\psi \sin\phi - \sin\theta \cos\phi \cos\psi) \\ k_{q4} &= (d\phi) + (\sin\theta d\psi) + k_2 (\sin\theta) + k_3 (\cos\theta \cos\psi) \end{aligned}$$

Proof First, to find the curvature k_{q1} , if the derivative of \mathbf{n}_q in expression (10) is taken it becomes

$$\begin{aligned} \mathbf{n}_q &= (\cos\theta \cos\psi) \mathbf{n} + (\cos\theta \sin\psi) \mathbf{b}_1 + (\sin\theta) \mathbf{b}_2 \\ \mathbf{n}_q' &= (-\sin\theta \cos\psi d\theta) \mathbf{n} - (\cos\theta \sin\psi d\psi) \mathbf{n} \\ &\quad + (\cos\theta \cos\psi) \mathbf{n}' + (\cos\theta d\theta) \mathbf{b}_2 + (\sin\theta) \mathbf{b}_2' \\ &\quad - (\sin\theta \sin\psi d\theta) \mathbf{b}_1 + (\cos\theta \cos\psi d\psi) \mathbf{b}_1 \\ &\quad + (\cos\theta \sin\psi) \mathbf{b}_1' \end{aligned}$$

and if the Frenet formulas given by equality (7) are substituted into the above expression,

$$\begin{aligned}
\mathbf{n}_q' = & (-\sin\theta\cos\psi d\theta)\mathbf{n} - (\cos\theta\sin\psi d\psi)\mathbf{n} - (\sin\theta)(k_3\mathbf{b}_1) \\
& + (\cos\theta\cos\psi)(-k_1\mathbf{t} + k_2\mathbf{b}_1) + (\cos\theta d\theta)\mathbf{b}_2 \\
& - (\sin\theta\sin\psi d\theta)\mathbf{b}_1 + (\cos\theta\cos\psi d\psi)\mathbf{b}_1 \\
& + (\cos\theta\sin\psi)(-k_2\mathbf{n} + k_3\mathbf{b}_2)
\end{aligned}$$

If this expression is multiplied by \mathbf{t} , it becomes

$$k_{q1} = -\langle \mathbf{t}, \mathbf{n}_q' \rangle = k_1 \cos\theta\cos\psi.$$

To find the k_{q2} curvature now, if we take the derivative of \mathbf{b}_{q1} in expression (10), it is found as

$$\begin{aligned}
\mathbf{b}_{q1}' = & (-\cos\phi d\psi \sin\theta)\mathbf{n} + (\sin\phi \sin\psi d\psi \sin\theta)\mathbf{n} \\
& - (\sin\phi \cos\psi \cos\theta d\theta)\mathbf{n} - (\sin\phi \cos\psi \sin\theta)\mathbf{n}' \\
& - (\cos\psi d\psi \cos\phi)\mathbf{n} + (\sin\psi \sin\phi d\phi)\mathbf{n} - (\sin\psi \cos\phi)\mathbf{n}' \\
& - (\sin\psi \cos\phi d\psi)\mathbf{b}_1 - (\sin\phi \cos\psi d\phi)\mathbf{b}_1 + (\cos\psi \cos\phi)\mathbf{b}_1' \\
& - (\cos\phi \sin\theta \sin\psi d\phi)\mathbf{b}_1 - (\sin\phi \cos\theta d\theta \sin\psi)\mathbf{b}_1 \\
& - (\sin\phi \sin\theta \cos\psi d\psi)\mathbf{b}_1 - (\sin\theta \sin\psi \sin\phi)\mathbf{b}_1' \\
& - (\sin\phi \sin\theta d\theta)\mathbf{b}_2 + (\cos\theta \cos\phi d\phi)\mathbf{b}_2 + (\sin\phi \cos\theta)\mathbf{b}_2'
\end{aligned}$$

since it is

$$\begin{aligned}
\mathbf{b}_{q1} = & (-\sin\phi \cos\psi \sin\theta - \sin\psi \cos\phi)\mathbf{n} \\
& + (\cos\psi \cos\phi - \sin\phi \sin\theta \sin\psi)\mathbf{b}_1 + (\cos\theta \sin\phi)\mathbf{b}_2
\end{aligned}$$

If the Frenet formulas given by (7) are substituted and the necessary simplifications are made, it becomes

$$\begin{aligned}
\mathbf{b}_{q1}' = & (-\cos\phi \cos\psi \sin\theta d\phi)\mathbf{n} + (\sin\psi \sin\theta \sin\phi d\psi)\mathbf{n} \\
& - (\cos\theta \sin\phi \cos\psi d\theta)\mathbf{n} + (\sin\theta \cos\psi \sin\phi)(k_1\mathbf{t} + k_2\mathbf{b}_1) \\
& + (\sin\phi \cos\psi d\psi)\mathbf{n} + (\sin\psi \cos\phi d\phi)\mathbf{n} - (\cos\psi \cos\phi d\psi)\mathbf{n} \\
& - (\sin\psi \cos\phi d\psi)\mathbf{b}_1 - (\sin\phi \cos\psi d\phi)\mathbf{b}_1 \\
& - (\cos\psi \cos\phi)\mathbf{b}_2(k_2\mathbf{n} + k_3\mathbf{b}_2) - (\sin\theta \cos\phi \sin\psi d\phi)\mathbf{b}_1 \\
& - (\cos\theta \sin\psi \sin\phi d\theta)\mathbf{b}_1 - (\sin\phi \sin\theta \cos\psi d\psi)\mathbf{b}_1 \\
& + (\cos\theta \cos\phi d\phi)\mathbf{b}_2 - (\cos\theta \sin\phi)(k_3\mathbf{b}_1)
\end{aligned}$$

If the above expression is multiplied by \mathbf{t} and the necessary adjustments are made

$$k_{q2} = \langle \mathbf{t}, \mathbf{b}_{q1}' \rangle = k_1 (\sin \theta \cos \psi \sin \phi + \sin \psi \cos \phi)$$

is obtained.

Now, to find the k_{q3} curvature, if the \mathbf{n}_{q1}' and \mathbf{b}_{q1} vectors are multiplied scalar-wise and the necessary simplifications are made, it is calculated as

$$\langle \mathbf{n}_{q1}', \mathbf{b}_{q1} \rangle = (\sin \phi d\theta) + (\cos \theta \cos \phi d\psi) + (k_2 \cos \theta \cos \phi) + (k_3 \sin \theta \cos \psi \cos \phi) + (k_3 \sin \psi \sin \phi)$$

and

$$k_{q3} = (\sin \phi d\theta) + (\cos \theta \cos \phi d\psi) + k_2 (\cos \theta \cos \phi) + k_3 (\sin \psi \sin \phi - \sin \theta \cos \psi \cos \phi)$$

Finally, to find the k_{q4} curvature, \mathbf{b}_{q1}' and \mathbf{b}_{q2} in expression (10) are multiplied by a scalar, and if necessary simplifications are made,

$$\langle \mathbf{b}_{q1}', \mathbf{b}_{q2} \rangle = (\cos^2 \phi d\phi) + (\sin \theta d\psi) + (k_2 \sin \theta) + (\sin^2 \phi d\phi) + (k_3 \cos \psi \cos \theta)$$

is obtained. Then it'll be

$$k_{q4} = d\phi + (\sin \theta d\psi) + (k_2 \sin \theta) + (k_3 \cos \psi \cos \theta).$$

Corollary In this theorem, if the angle ϕ in the space covered by the first quasi-binormal \mathbf{b}_{q1} and the second quasi-binormal \mathbf{b}_{q2} and the normal vector \mathbf{n} , as well as the angle ψ in the space covered by the first quasi-binormal \mathbf{b}_{q1} , are taken as zero, then relations between quasi curvatures and Frenet curvatures in 3-dimensional space given by (7) is found.

Example 1 Let $\alpha(s)$ represent a central curve with the Frenet frame of a tubular surface in E^4 , defined as

$$\alpha(s) = \frac{\sqrt{2}}{2} (\cos s, \sin s, \frac{1}{2} \cos 2s, \frac{1}{2} \sin 2s)$$

Since $\|\alpha(s)\| = 1$, it follows that the Frenet vectors are

$$\begin{aligned}\mathbf{t} &= \frac{\sqrt{2}}{2}(-\sin s, \cos s, -\sin 2s, \cos 2s) \\ \mathbf{n} &= \frac{\sqrt{5}}{5}(-\cos s, -\sin s, -2\cos 2s, -2\sin 2s) \\ \mathbf{b}_2 &= \frac{\sqrt{5}}{5}(2\cos s, 2\sin s, -2\cos^2 s + 1, -\sin 2s) \\ \mathbf{b}_1 &= \frac{\sqrt{2}}{2}(\sin s, -\cos s, -\sin 2s, 2\cos^2 s - 1)\end{aligned}$$

and from equation (2), Frenet curvatures are given as

$$k_1(s) = \frac{\sqrt{10}}{2}, k_2(s) = \frac{-3\sqrt{10}}{10} \text{ and } k_3(s) = \frac{2\sqrt{10}}{5}.$$

If quasi frame vectors are calculated using $\mathbf{k}_x = (1,0,0,0)$ and $\mathbf{k}_y = (0,1,0,0)$ projection vectors, it becomes

$$\begin{aligned}\mathbf{t} &= \frac{\sqrt{2}}{2}(-\sin s, \cos s, -\sin 2s, \cos 2s) \\ \mathbf{n}_q &= (0,0, \cos 2s, \sin 2s) \\ \mathbf{b}_{q2} &= (-\cos s, -\sin s, 0, 0) \\ \mathbf{b}_{q1} &= \frac{\sqrt{2}}{2}(\sin s, -\cos s, -\sin 2s, 2\cos^2 s - 1).\end{aligned}$$

If the quasi-curvatures are calculated with the help of (8),

$$k_{q1} = -\sqrt{2}, k_{q2} = 0, k_{q3} = \sqrt{2} \text{ and } k_{q4} = \frac{-\sqrt{2}}{2}$$

The curves in the projection spaces xyz and xyt and the normal and quasi-normal plane vectors at the points taken on them are plotted in Figure 4, respectively.

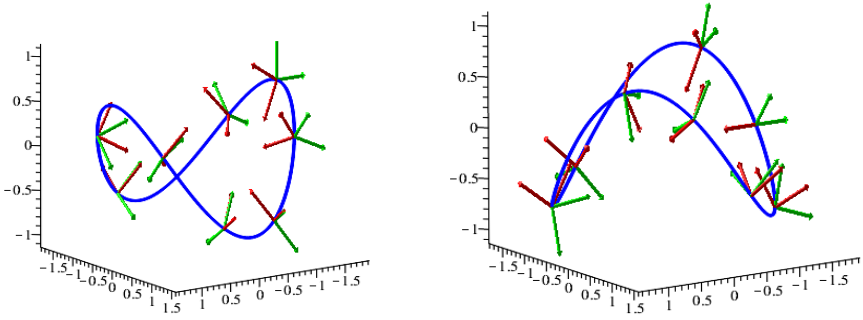


Figure 4 Frenet vectors \mathbf{n} and \mathbf{b} (red), quasi vectors \mathbf{n}_q and \mathbf{b}_q (green)

The curves in the projection spaces xzt and yzt and the normal and quasi-normal plane vectors at the points taken on them are plotted in Figure 5, respectively.

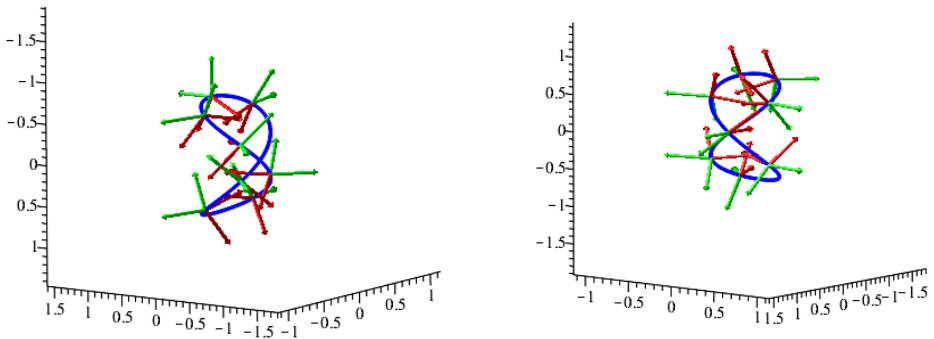


Figure 5 Frenet vectors \mathbf{n} and \mathbf{b} (red), quasi vectors \mathbf{n}_q and \mathbf{b}_q (green)

Example 2 Let $\alpha(s)$ represent a central curve with the Frenet frame of a tubular surface in E^4 , defined as

$$\alpha(s) = \left(\sin \frac{s}{\sqrt{2}}, \cos \frac{s}{\sqrt{2}}, \frac{1}{\sqrt{2}} \sin s, \frac{1}{\sqrt{2}} \cos s \right)$$

Since $\|\alpha(s)\| = 1$, it follows that the Frenet vectors are

$$\begin{aligned} \mathbf{t} &= \frac{1}{\sqrt{2}} \left(\cos \frac{s}{\sqrt{2}}, -\sin \frac{s}{\sqrt{2}}, \cos s, -\sin s \right) \\ \mathbf{n} &= \frac{-1}{\sqrt{3}} \left(\sin \frac{s}{\sqrt{2}}, \cos \frac{s}{\sqrt{2}}, \sqrt{2} \sin s, \sqrt{2} \cos s \right) \\ \mathbf{b}_2 &= \frac{-1}{\sqrt{3}} \left(-\sqrt{2} \sin \frac{s}{\sqrt{2}}, -\sqrt{2} \cos \frac{s}{\sqrt{2}}, \sin s, \cos s \right) \\ \mathbf{b}_1 &= -\frac{1}{\sqrt{2}} \left(\cos \frac{s}{\sqrt{2}}, -\sin \frac{s}{\sqrt{2}}, -\cos s, \sin s \right) \end{aligned}$$

and from equation (2), Frenet curvatures are given as

$$k_1(s) = \frac{\sqrt{3}}{2}, k_2(s) = -\frac{\sqrt{3}}{6} \text{ and } k_3(s) = \frac{\sqrt{6}}{3}. \quad (12)$$

If quasi frame vectors are calculated using $\mathbf{k}_x = (1,0,0,0)$ and $\mathbf{k}_y = (0,1,0,0)$ projection vectors, it becomes

$$\begin{aligned} \mathbf{t} &= \frac{1}{\sqrt{2}} \left(\cos \frac{s}{\sqrt{2}}, -\sin \frac{s}{\sqrt{2}}, \cos s, -\sin s \right) \\ \mathbf{n}_q &= (0,0, -\sin s, -\cos s) \\ \mathbf{b}_{q2} &= \left(\sin \frac{s}{\sqrt{2}}, \cos \frac{s}{\sqrt{2}}, 0,0 \right) \\ \mathbf{b}_{q1} &= -\frac{1}{\sqrt{2}} \left(\cos \frac{s}{\sqrt{2}}, -\sin \frac{s}{\sqrt{2}}, -\cos s, \sin s \right) \end{aligned} \quad (13)$$

If the quasi-curvatures are calculated with the help of (8),

$$k_{q1}(s) = \frac{1}{\sqrt{2}}, k_{q2}(s) = 0, k_{q3} = -\frac{1}{\sqrt{2}} \text{ and } k_{q4} = \frac{1}{2}$$

The curves in the projection spaces xyz and xyt and the normal and quasi-normal plane vectors at the points taken on them are plotted in Figure 6, respectively.

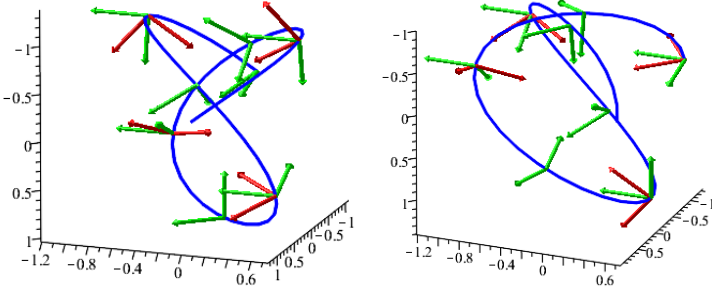


Figure 6 Frenet vectors \mathbf{n} and \mathbf{b} (red), quasi vectors \mathbf{n}_q and \mathbf{b}_q (green)

The curves in the projection spaces xzt and yzt and the normal and quasi-normal plane vectors at the points taken on them are plotted in Figure 7, respectively.

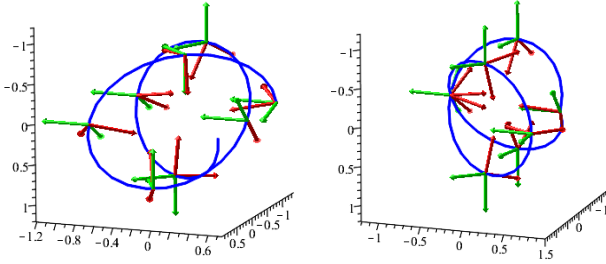


Figure 7 Frenet vectors \mathbf{n} and \mathbf{b} (red), quasi vectors \mathbf{n}_q and \mathbf{b}_q (green)

If the angles ψ , ϕ and θ in the matrix given in Theorem 1 are specially chosen such that $\psi = 0$, $\phi = 2\pi$ and $\theta = \arccos \frac{\sqrt{2}}{\sqrt{3}}$, then

$$\begin{bmatrix} \mathbf{t} \\ \mathbf{n}_q \\ \mathbf{b}_{q1} \\ \mathbf{b}_{q2} \end{bmatrix} = \begin{bmatrix} 1 & 0 & 0 & 0 \\ 0 & \frac{\sqrt{2}}{\sqrt{3}} & 0 & \frac{1}{\sqrt{3}} \\ 0 & 0 & 1 & 0 \\ 0 & -\frac{1}{\sqrt{3}} & 0 & \frac{\sqrt{2}}{\sqrt{3}} \end{bmatrix} \begin{bmatrix} \mathbf{t} \\ \mathbf{n} \\ \mathbf{b}_1 \\ \mathbf{b}_2 \end{bmatrix}.$$

is found with the help of the matrix M . If Frenet frame vectors are substituted in this equation, quasi frame vectors are obtained as

$$\begin{aligned}
\mathbf{t} &= \frac{1}{\sqrt{2}} \left(\cos \frac{s}{\sqrt{2}}, -\sin \frac{s}{\sqrt{2}}, \cos s, -\sin s \right) \\
\mathbf{n}_q &= -\frac{\sqrt{2}}{3} \left(\sin \frac{s}{\sqrt{2}}, \cos \frac{s}{\sqrt{2}}, \sqrt{2} \sin s, \sqrt{2} \cos s \right) \\
&\quad -\frac{1}{3} \left(-\sqrt{2} \sin \frac{s}{\sqrt{2}}, -\sqrt{2} \cos \frac{s}{\sqrt{2}}, \sin s, \cos s \right) \\
&= (0, 0, -\sin s, -\cos s) \\
\mathbf{b}_{q2} &= \frac{1}{3} \left(\sin \frac{s}{\sqrt{2}}, \cos \frac{s}{\sqrt{2}}, \sqrt{2} \sin s, \sqrt{2} \cos s \right) \\
&\quad -\frac{\sqrt{2}}{3} \left(-\sqrt{2} \sin \frac{s}{\sqrt{2}}, -\sqrt{2} \cos \frac{s}{\sqrt{2}}, \sin s, \cos s \right) \\
&= \left(\sin \frac{s}{\sqrt{2}}, \cos \frac{s}{\sqrt{2}}, 0, 0 \right) \\
\mathbf{b}_{q1} &= -\frac{1}{\sqrt{2}} \left(\cos \frac{s}{\sqrt{2}}, -\sin \frac{s}{\sqrt{2}}, -\cos s, \sin s \right)
\end{aligned}$$

respectively. They are the same as the vectors given above (13). In a similar way, by substituting the given angle values into the Frenet curvatures given by (12) in the equations in Theorem 3, the quasi-curvatures are obtained as

$$\begin{aligned}
k_{q1} &= k_1 \cos \theta \cos \psi = \left(\frac{\sqrt{3}}{2} \right) \left(\frac{\sqrt{2}}{\sqrt{3}} \right) = \frac{1}{\sqrt{2}} \\
k_{q2} &= k_1 (\sin \theta \sin \phi \cos \psi + \sin \psi \cos \phi) = 0 \\
k_{q3} &= (\sin \phi d\theta) + (\cos \phi \cos \theta d\psi) + k_2 (\cos \theta \cos \phi) \\
&\quad + k_3 (\sin \psi \sin \phi - \sin \theta \cos \phi \cos \psi) \\
&= \left(-\frac{\sqrt{3}}{6} \right) \frac{\sqrt{2}}{\sqrt{3}} + \frac{\sqrt{6}}{3} \left(-\frac{1}{\sqrt{3}} \right) = -\frac{\sqrt{2}}{6} - \frac{\sqrt{2}}{3} = -\frac{1}{\sqrt{2}} \\
k_{q4} &= (d\phi) + (\sin \theta d\psi) + k_2 (\sin \theta) + k_3 (\cos \theta \cos \psi) \\
&= \left(-\frac{\sqrt{3}}{6} \right) \left(\frac{1}{\sqrt{3}} \right) + \left(\frac{\sqrt{6}}{3} \right) \left(\frac{\sqrt{2}}{\sqrt{3}} \right) = \frac{1}{2}.
\end{aligned}$$

This value is the same as the above (19) quasi-curvature values.

All the figures in this study were created by using Maple programme.

CONCLUSION

In four-dimensional Euclidean space, we first defined the quasi frame and quasi curvatures with Frenet vectors. We emphasised the importance of the quasi frame in that it can be calculated easily and with the same accuracy even in the absence of the second derivative of the curve. We found the transition matrices between the quasi frame and the Frenet frame for a space curve in 4-dimensional space. We gave the relations between the curvatures of the two frames. We also took a curve for which we will calculate these two frame vectors and exemplified its images in projection spaces.

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Chapter 3

On New Structures Hardy-Hilbert-Type Inequalities with Diamond- α Calculus

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INTRODUCTION

Overall, dynamic inequalities and their different forms are important in harmonic analysis and other application areas. The most well-known of these are the Hardy and Hilbert inequalities. These integral inequalities also play an important role in time scales combining continuous and discrete state forms. At the same time, these integral inequalities are the cornerstones of applied mathematics. Before starting our work, we think giving some information about these inequalities would be useful. The reader can refer to the references section at the end of this work for more detailed information.

In [1], the theorems we give below are well-known classical statements about Hilbert's inequality.

Theorem 1.1. Let $p, q > 1$, $\frac{1}{p} + \frac{1}{q} \leq 1$, and $0 < w = 2 - \frac{1}{p} - \frac{1}{q} = \frac{1}{p'} + \frac{1}{q'} \leq 1$, then

$$\sum_{j=1}^{\infty} \sum_{i=1}^{\infty} \frac{f_j g_i}{(j+i)^w} \leq D \left(\sum_{j=1}^{\infty} f_j^p \right)^{\frac{1}{p}} \left(\sum_{i=1}^{\infty} g_i^q \right)^{\frac{1}{q}}, \quad (1)$$

where $D = D(p, q)$.

Theorem 1.2. Let $f \in L^p(0, \infty)$, $g \in L^q(0, \infty)$, and let p, q, p', q', w be as in Theorem 1.1, then

$$\int_0^{\infty} \int_0^{\infty} \frac{f(x)g(y)}{(x+y)^w} dx dy \leq D \left(\int_0^{\infty} f^p(x) dx \right)^{\frac{1}{p}} \left(\int_0^{\infty} g^q(y) dy \right)^{\frac{1}{q}}, \quad (2)$$

where $D = D(p, q)$.

In [2], Zhao et al. introduced a new inequality that is compatible with the structure of Theorem 1.2.

Theorem 1.3. Let $\frac{1}{p_i} + \frac{1}{q_i} = 1$ with $p_i > 1$, $\pi_i \geq 1$. Let differentiable function $f_i(\theta_i)$ on $[0, k_i)$, where $k_i \in (0, \infty)$. Assume $f_i(0) = 0$ for $(i = 1, \dots, n)$. Then

$$\int_0^{k_1} \int_0^{k_2} \dots \int_0^{k_n} \frac{\prod_{i=1}^n |f_i^{\pi_i}(\theta_i)|}{\left(\sum_{i=1}^n \frac{\theta_i}{q_i}\right)^{\sum_{i=1}^n \frac{1}{q_i}}} d\theta_n d\theta_{n-1} \dots d\theta_1 \leq D \prod_{i=1}^n \left(\int_0^{k_i} (k_i - \theta_i) |f_i^{\pi_i-1}(\theta_i) f_i'(\theta_i)|^{p_i} d\theta_i \right)^{\frac{1}{p_i}},$$

where $D = \left(n - \sum_{i=1}^n \frac{1}{p_i}\right)^{\sum_{i=1}^n \frac{1}{p_i} - n} \prod_{i=1}^n \pi_i k_i^{\frac{1}{q_i}}$.

In [3], Zhao and Chung introduced the following inequality.

Theorem 1.4. Let $\frac{1}{p_i} + \frac{1}{q_i} = 1$ with $p_i > 1$, p_i are constants. Let $f_i(\delta_{1i}, \dots, \delta_{ni})$ be real-valued $n - th$ differential functions defined on $[0, k_{1i}) \times \dots \times [0, k_{ni})$, where $\delta_{ji} \in (0, \infty)$ and $0 \leq k_{ji} \leq \delta_{ji}$, $(j, i = 1, \dots, n)$. Assume that

$$f_i(k_{1i}, \dots, k_{ni}) = \int_0^{k_{1i}} \dots \int_0^{k_{ni}} \frac{\partial^n}{\partial_{k_{1i}} \dots \partial_{k_{ni}}} f_i(\delta_{1i}, \dots, \delta_{ni}) d\delta_{ni} \dots d\delta_{1i},$$

then

$$\begin{aligned} & \int_0^{\epsilon_{11}} \dots \int_0^{\epsilon_{n1}} \int_0^{\epsilon_{12}} \dots \int_0^{\epsilon_{n2}} \dots \int_0^{\epsilon_{1n}} \dots \int_0^{\epsilon_{nn}} \frac{\prod_{i=1}^n \left(\int_0^{k_{1i}} \dots \int_0^{k_{ni}} \left| \frac{\partial^n}{\partial_{k_{1i}} \dots \partial_{k_{ni}}} f_i(\delta_{1i}, \dots, \delta_{ni}) \right|^{p_i} d\delta_{ni} \dots d\delta_{1i} \right)^{\frac{1}{p_i}}}{\left(\sum_{i=1}^n \frac{(k_{1i} \dots k_{ni})}{q_i}\right)^{\sum_{i=1}^n \frac{1}{q_i}}} \\ & \quad d_{k_{11}} \dots d_{k_{n1}} d_{k_{12}} \dots d_{k_{n2}} \dots d_{k_{1n}} \dots d_{k_{nn}} \\ & \leq M \prod_{i=1}^n \left(\int_0^{\epsilon_{1i}} \dots \int_0^{\epsilon_{ni}} \prod_{j=1}^n (\epsilon_{ji} - k_{ji}) \left| \frac{\partial^n}{\partial_{k_{1i}} \dots \partial_{k_{ni}}} f_i(k_{1i}, \dots, k_{ni}) \right|^{p_i} d_{k_{ni}} \dots d_{k_{1i}} \right)^{\frac{1}{p_i}}, \end{aligned} \tag{3}$$

Where $M = \left(n - \sum_{i=1}^n \frac{1}{p_i}\right)^{\sum_{i=1}^n \frac{1}{p_i} - n} \prod_{i=1}^n (\epsilon_{1i} \dots \epsilon_{ni})^{\frac{1}{q_i}}$.

For more detailed information on inequalities, time scales, and fractional calculus, see monographs [4-27, 52-61].

AUXILIARY STATEMENTS AND PRELIMINARIES

Although the history of time scale calculation is not very long, it has positioned itself in the field of mathematics and other disciplines of science. It owes this position to the unification of continuous and discrete cases in mathematics. Due to this situation, scientists in almost every field have integrated this field into their field of study and have contributed many innovations to the literature. Analytical solutions of differential equations in applied mathematics and mathematical modeling in economics are just a few examples of these application areas. Those who want more general information can look at references [28, 42-51]. \mathbb{T} is a time scale that arbitrary non-empty closed subset of real numbers (\mathbb{R}). In our study, we will take this situation of $(0, \infty)_{\mathbb{T}} = (0, \infty) \cap \mathbb{T}$ into consideration.

Now let's briefly give the basic concepts about the diamond-alpha derivative.

$\sigma, \rho: \mathbb{T} \rightarrow \mathbb{T}$ are defined by $\sigma(t) = \inf\{s \in \mathbb{T} : s > t\}$, $\rho(t) = \sup\{s \in \mathbb{T} : s > t\}$ for $t \in \mathbb{T}$. $\sigma(t)$ is the jump operator (forward), and $\rho(t)$ is the jump operator (backward), respectively. Let $\sigma(t) > t$, then t is *rs* (right-scattered), and let $\sigma(t) = t$, then t is called *rd* (right-dense). Let $\rho(t) < t$, then t is *ls* (left-scattered), and let $\rho(t) = t$, then t is called *ld* (left-dense).

Let $\mu, \vartheta: \mathbb{T} \rightarrow \mathbb{R}^+$ such that $\mu(t) = \sigma(t) - t$, $\vartheta(t) = t - \rho(t)$. $\mu(t)$ and $\vartheta(t)$ are called *gm* (graininess mappings).

If the time scale \mathbb{T} has a *ls* (left-scattered) maximum m , then $\mathbb{T}^k = \mathbb{T} - \{m\}$. Otherwise $\mathbb{T}^k = \mathbb{T}$.

\mathbb{T}^k is defined as follows

$$\mathbb{T}^k = \begin{cases} \mathbb{T} \setminus (\rho \sup \mathbb{T}, \sup \mathbb{T}], & \text{if } \sup \mathbb{T} < \infty \\ \mathbb{T}, & \text{if } \sup \mathbb{T} = \infty, \end{cases}$$

and

$$\mathbb{T}_k = \begin{cases} \mathbb{T} \setminus [\inf \mathbb{T}, \sigma(\inf \mathbb{T})], & \text{if } |\inf \mathbb{T}| < \infty \\ \mathbb{T}, & \text{if } \inf \mathbb{T} = -\infty. \end{cases}$$

Assume that $h: \mathbb{T} \rightarrow \mathbb{R}$ is a function. Let t be right-dense.

- i) Let π be delta differentiable at t ($t \in \mathbb{T}^k (t \neq \min \mathbb{T})$), then π is continuous at t .
- ii) Let π be *lc* (left continuous) at t , and t is *rs* (right-scattered), then π is delta differentiable at t ,

$$\pi^\Delta(t) = \frac{\pi^\sigma(t) - \pi(t)}{\mu(t)}$$

iii) Let π be delta differentiable at t and $\lim_{s \rightarrow t} \frac{\pi(t) - \pi(s)}{t - s}$, then

iv)

$$\pi^\Delta(t) = \lim_{s \rightarrow t} \frac{\pi(t) - \pi(s)}{t - s}.$$

v) Let π be delta differentiable at t , then $\pi^\sigma(t) = \pi(t) + \mu(t)\pi^\Delta(t)$.

Let $\mathbb{T} = \mathbb{R}$, then $\pi^\Delta(t) = \pi'(t)$, and Let $\mathbb{T} = \mathbb{Z}$, then $\pi^\Delta(t)$ reduces to $\Delta\pi(t)$.

Let $K: \mathbb{T} \rightarrow \mathbb{R}$ is defined as a delta antiderivative of $\pi: \mathbb{T} \rightarrow \mathbb{R}$, then $K^\Delta = \pi(t)$ holds for all $t \in \mathbb{T}$, and we define the delta integral of π by

$$\int_s^t \pi(\tau) \Delta\tau = K(t) - K(s),$$

for all $s, t \in \mathbb{T}$.

Suppose $\pi: \mathbb{R} \rightarrow \mathbb{R}$ is a continuous function and delta differentiable on \mathbb{T} . If $\varphi: \mathbb{R} \rightarrow \mathbb{R}$ is continuously differentiable, then we have

$$(\varphi \circ \pi)^\Delta(s) = \varphi'(\pi(m))\pi^\Delta(s), \quad m \in [s, \sigma(s)].$$

Let's now give some definitions for the nabla integral.

Let $\pi: \mathbb{T}_k \rightarrow \mathbb{R}$ is called nabla differentiable at $t \in \mathbb{T}_k$. If $\varepsilon > 0$, then the following inequality is provided

$$|\pi(\rho(t)) - \pi(s) - \pi^\nabla(t)(\rho(t) - s)| \leq \varepsilon|\rho(t) - s|,$$

for all $s \in V$.

Let $K: \mathbb{T} \rightarrow \mathbb{R}$ is called a nabla antiderivative of $\pi: \mathbb{T} \rightarrow \mathbb{R}$, then we define

$$\int_s^t \pi(\tau) \nabla\tau = K(t) - K(s),$$

for all $s, t \in \mathbb{T}$.

In [50], Let $\vartheta(t)$ be diamond alpha differentiable on \mathbb{T} for all $\alpha, t \in \mathbb{T}$, then we define $\vartheta^{\circ\alpha}(t)$ by

$$\vartheta^{\circ\alpha}(t) = \alpha \vartheta^{\Delta}(t) + (1-\alpha)\vartheta^{\nabla}(t)$$

for $0 \leq \alpha \leq 1$.

Theorem 2.1 [50] Let $\vartheta, h: \mathbb{T} \rightarrow \mathbb{R}$ be diamond alpha differentiable for all $\alpha, t \in \mathbb{T}$ and $0 \leq \alpha \leq 1$.

(i) Let $(\vartheta + h): \mathbb{T} \rightarrow \mathbb{R}$ be diamond alpha differentiable for all $t \in \mathbb{T}$, then

$$(\vartheta + h)^{\circ\alpha}(t) = \vartheta^{\circ\alpha}(t) + h^{\circ\alpha}(t).$$

(ii) Let $k\vartheta: \mathbb{T} \rightarrow \mathbb{R}$ be diamond alpha differentiable for all $\alpha, t \in \mathbb{T}$, then

$$(k\vartheta)^{\circ\alpha}(t) = k\vartheta^{\circ\alpha}(t),$$

where $t, k \in \mathbb{R}$.

(iii) Let $\vartheta, h: \mathbb{T} \rightarrow \mathbb{R}$ be diamond alpha differentiable for all $\alpha, t \in \mathbb{T}$, then

$$(\vartheta h)^{\circ\alpha}(t) = \vartheta^{\circ\alpha}(t)h(t) + \alpha \vartheta^{\sigma}(t)h^{\Delta}(t) + (1-\alpha)\vartheta^{\rho}(t)h^{\nabla}(t).$$

Definition 2.2 [50] If $\vartheta: \mathbb{T} \rightarrow \mathbb{R}$ is \diamond_{α} -integrable for all $\alpha, b, t \in \mathbb{T}$, then

$$\int_b^t \vartheta(\delta) \diamond_{\alpha} \delta = \alpha \int_b^t \vartheta(\delta) \Delta \delta + (1-\alpha) \int_b^t \vartheta(\delta) \nabla \delta$$

for $0 \leq \alpha \leq 1$.

Definition 2.3 [46, 52] Let $\vartheta \in C_{rd}(\mathbb{T}, \mathbb{R})$, $t \in \mathbb{T}^k$ and let $\vartheta: \mathbb{T} \rightarrow \mathbb{R}$ be diamond alpha integrable, then

$$\int_t^{\sigma(t)} \vartheta(\tau) \diamond_{\alpha} \tau = \mu(t)\vartheta(t).$$

The partial integration formula on the time scale is given by

$$\int_x^y u(s)w^{\circ\alpha}(s) \diamond_{\alpha} s = u(s)w(s)I_x^y - \int_x^y u^{\circ\alpha}(s)w^{\sigma}(s) \diamond_{\alpha} s$$

for $0 \leq \alpha \leq 1$.

Definition 2.4 [25, 51] (Conformable diamond-alpha derivative) Given $\vartheta: \mathbb{T} \rightarrow \mathbb{R}$ and $\beta \in \mathbb{T}$, ϑ is (λ, β) –diamond alpha differentiable at $\eta > \beta$, if it's diamond alpha differentiable at η , and its (λ, β) –diamond alpha derivative is defined by

$$\diamond_{\alpha}^{\lambda} \vartheta(\eta) = \Lambda_{1-\lambda}(\eta, \beta) \vartheta^{\circ\alpha}(\eta) \quad \eta > \beta, \quad (4)$$

Definition 2.5 [25, 51] (Conformable diamond-alpha integral) Suppose that $\beta, \eta_1, \eta_2 \in \mathbb{T}$, $\vartheta \in C(\mathbb{T})$, $0 < \lambda \leq 1, \beta \leq \eta_1 \leq \eta_2$, and the function ϑ is called (λ, β) –diamond alpha integrable on $[\eta_1, \eta_2]$ if

$$\diamond_{\alpha}^{\lambda} \vartheta(\eta) = \int_{\eta_1}^{\eta_2} \vartheta(\eta) \diamond_{\alpha}^{\lambda} \eta = \int_{\eta_1}^{\eta_2} \vartheta(\eta) \Lambda_{1-\lambda}(\sigma^{1-\lambda}(\eta), \beta) \diamond_{\alpha} \eta, \quad (5)$$

Lemma 2.6 [14] If $f, \varepsilon \in CC_{rd}^1([\omega, p]_{\mathbb{T}} \times [\omega, p]_{\mathbb{T}}, \mathbb{R})$ are diamond alpha integrable functions and $\frac{1}{p} + \frac{1}{q} = 1$ with $p > 1$ and let $\omega, p \in \mathbb{T}$ with $\omega < p$, then

$$\begin{aligned} & \int_{\omega}^p \int_{\omega}^p |f(t, \varepsilon) \varepsilon(t, \varepsilon)| \diamond_{\alpha}^{\lambda, \beta} t \diamond_{\alpha}^{\lambda, \beta} \varepsilon \\ & \leq \left(\int_{\omega}^p \int_{\omega}^p |f(t, \varepsilon)|^p \diamond_{\alpha}^{\lambda, \beta} t \diamond_{\alpha}^{\lambda, \beta} \varepsilon \right)^{\frac{1}{p}} \times \left(\int_{\omega}^p \int_{\omega}^p |\varepsilon(t, \varepsilon)|^q \diamond_{\alpha}^{\lambda, \beta} t \diamond_{\alpha}^{\lambda, \beta} \varepsilon \right)^{\frac{1}{q}}. \end{aligned} \quad (5)$$

In this study, we prove a new fractional inequality of Hilbert-type on time scales using the properties of Theorem 1.3 mentioned above. We also obtain discrete cases of Hilbert-type inequalities related to some special cases of our results.

Main Result

Theorem 3.1 Let $\epsilon_0, k_{ij}, \delta_{ij}, \epsilon_{ij} \in \mathbb{T}$, $(i, j = 1, \dots, n)$. Let $p_i, q_i > 1$ be constants and $\frac{1}{p_i} + \frac{1}{q_i} = 1$ and let $f_i(\delta_{1j}, \dots, \delta_{nj})$ be $\diamond_\alpha^{\lambda, \beta}$ -differentiable functions and also defined on $[\epsilon_0, k_{1i}]_{\mathbb{T}} \times \dots \times [\epsilon_0, k_{ni}]_{\mathbb{T}}$, where $\epsilon_{ji} \in (0, \infty)$ and $\epsilon_0 \leq k_{ji} \leq \epsilon_{ji}$, $(j, i = 1, \dots, n)$. Assume that

$$f_i(k_{1i}, \dots, k_{ni}) = \int_{\epsilon_0}^{k_{1i}} \dots \int_{\epsilon_0}^{k_{ni}} \frac{\partial^n}{\diamond_\alpha^{\lambda, \beta} \delta_{1i} \dots \diamond_\alpha^{\lambda, \beta} \delta_{ni}} f_i(\delta_{1i}, \dots, \delta_{ni}) \diamond_\alpha^{\lambda, \beta} \delta_{ni} \dots \diamond_\alpha^{\lambda, \beta} \delta_{1i},$$

then

$$\begin{aligned} & \int_{\epsilon_0}^{\epsilon_{11}} \dots \int_{\epsilon_0}^{\epsilon_{n1}} \int_{\epsilon_0}^{\epsilon_{12}} \dots \int_{\epsilon_0}^{\epsilon_{n2}} \dots \int_{\epsilon_0}^{\epsilon_{1n}} \dots \int_{\epsilon_0}^{\epsilon_{nn}} \dots \int_{\epsilon_0}^{\dots} \dots \\ & \frac{\prod_{i=1}^n \left(\int_{\epsilon_0}^{k_{1i}} \dots \int_{\epsilon_0}^{k_{ni}} \left| \frac{\partial^n}{\diamond_\alpha^{\lambda, \beta} \delta_{1i} \dots \diamond_\alpha^{\lambda, \beta} \delta_{ni}} f_i(\delta_{1i}, \dots, \delta_{ni}) \right|^{p_i} \diamond_\alpha^{\lambda, \beta} \delta_{ni} \dots \diamond_\alpha^{\lambda, \beta} \delta_{1i} \right)^{\frac{1}{p_i}}}{\left(\sum_{i=1}^n \frac{(k_{1i} - \epsilon_0) \dots (k_{ni} - \epsilon_0)}{q_i} \right)^{\sum_{i=1}^n \frac{1}{q_i}}} \\ & \diamond_\alpha^{\lambda, \beta} k_{11} \dots \diamond_\alpha^{\lambda, \beta} k_{n1} \dots \diamond_\alpha^{\lambda, \beta} k_{12} \dots \diamond_\alpha^{\lambda, \beta} k_{n2} \dots \diamond_\alpha^{\lambda, \beta} k_{1n} \dots \diamond_\alpha^{\lambda, \beta} k_{nn} \\ & \leq M \prod_{i=1}^n \left(\int_{\epsilon_0}^{\epsilon_{1i}} \dots \int_{\epsilon_0}^{\epsilon_{ni}} \prod_{j=1}^n (h(\epsilon_{ji}) - k_{ji}) \left| \frac{\partial^n}{\diamond_\alpha^{\lambda, \beta} k_{1i} \dots \diamond_\alpha^{\lambda, \beta} k_{ni}} f_i(k_{1i}, \dots, k_{ni}) \right|^{p_i} \diamond_\alpha^{\lambda, \beta} k_{1i} \dots \diamond_\alpha^{\lambda, \beta} k_{ni} \right)^{\frac{1}{p_i}} \end{aligned} \quad (6)$$

Where $M = M(\epsilon_{1i} \dots \epsilon_{ni}) \left(n - \sum_{i=1}^n \frac{1}{p_i} \right)^{\sum_{i=1}^n \frac{1}{p_i} - n} \prod_{i=1}^n ((\epsilon_{1i} - \epsilon_0) \dots (\epsilon_{ni} - \epsilon_0))^{\frac{1}{q_i}}$.

Proof. From Theorem 3.1, we obtain

$$f_i(k_{1i}, \dots, k_{ni}) \leq \int_{\epsilon_0}^{k_{1i}} \dots \int_{\epsilon_0}^{k_{ni}} \left| \frac{\partial^n}{\diamond_\alpha^{\lambda, \beta} \delta_{1i} \dots \diamond_\alpha^{\lambda, \beta} \delta_{ni}} f_i(\delta_{1i}, \dots, \delta_{ni}) \right| \diamond_\alpha^{\lambda, \beta} \delta_{ni} \dots \diamond_\alpha^{\lambda, \beta} \delta_{1i}. \quad (7)$$

On the other hand, by using Hölder's dynamic inequality and inequality

$$\left(\prod_{i=1}^n w_i^{\frac{1}{q_i}} \right)^{\frac{1}{\sum_{i=1}^n \frac{1}{q_i}}} \leq \frac{1}{\sum_{i=1}^n \frac{1}{q_i}} \sum_{i=1}^n \frac{w_i}{q_i}, \quad w_i > 0 \quad (i = 1, \dots, n),$$

we obtain

$$\begin{aligned} \prod_{i=1}^n |f_i(k_{1i}, \dots, k_{ni})| &\leq \prod_{i=1}^n \int_{\epsilon_0}^{k_{1i}} \dots \int_{\epsilon_0}^{k_{ni}} \left| \frac{\partial^n}{\diamond_{\alpha}^{\lambda, \beta} \delta_{1i} \dots \diamond_{\alpha}^{\lambda, \beta} \delta_{ni}} f_i(\delta_{1i}, \dots, \delta_{ni}) \right| \diamond_{\alpha}^{\lambda, \beta} \delta_{ni} \dots \diamond_{\alpha}^{\lambda, \beta} \delta_{1i} \\ &\leq \prod_{i=1}^n ((k_{1i} - \epsilon_0) \dots (k_{ni} - \epsilon_0))^{\frac{1}{q_i}} \\ &\times \left(\int_{\epsilon_0}^{k_{1i}} \dots \int_{\epsilon_0}^{k_{ni}} \left| \frac{\partial^n}{\diamond_{\alpha}^{\lambda, \beta} \delta_{1i} \dots \diamond_{\alpha}^{\lambda, \beta} \delta_{ni}} f_i(\delta_{1i}, \dots, \delta_{ni}) \right|^{p_i} \diamond_{\alpha}^{\lambda, \beta} \delta_{ni} \dots \diamond_{\alpha}^{\lambda, \beta} \delta_{1i} \right)^{\frac{1}{p_i}} \\ &\leq \frac{\left(\sum_{i=1}^n \frac{(k_{1i} - \epsilon_0) \dots (k_{ni} - \epsilon_0)}{q_i} \right)^{\sum_{i=1}^n \frac{1}{q_i}}}{\left(n - \sum_{i=1}^n \frac{1}{p_i} \right)^{n - \sum_{i=1}^n \frac{1}{p_i}}} \\ &\times \prod_{i=1}^n \left(\int_{\epsilon_0}^{k_{1i}} \dots \int_{\epsilon_0}^{k_{ni}} \left| \frac{\partial^n}{\diamond_{\alpha}^{\lambda, \beta} \delta_{1i} \dots \diamond_{\alpha}^{\lambda, \beta} \delta_{ni}} f_i(\delta_{1i}, \dots, \delta_{ni}) \right|^{p_i} \diamond_{\alpha}^{\lambda, \beta} \delta_{ni} \dots \diamond_{\alpha}^{\lambda, \beta} \delta_{1i} \right)^{\frac{1}{p_i}}. \end{aligned} \quad (8)$$

Divide (8) by $\left(\sum_{i=1}^n \frac{(k_{1i}-\epsilon_0)\dots(k_{ni}-\epsilon_0)}{q_i}\right)^{\sum_{i=1}^n \frac{1}{q_i}}$, then using dynamic Hölder inequality and $h(n) \geq n$, we have that

$$\begin{aligned}
& \int_{\epsilon_0}^{\epsilon_{11}} \dots \int_{\epsilon_0}^{\epsilon_{n1}} \int_{\epsilon_0}^{\epsilon_{12}} \dots \int_{\epsilon_0}^{\epsilon_{n2}} \dots \int_{\epsilon_0}^{\epsilon_{1n}} \dots \int_{\epsilon_0}^{\epsilon_{nn}} \square \\
& \frac{\prod_{i=1}^n \left(\int_{\epsilon_0}^{k_{1i}} \dots \int_{\epsilon_0}^{k_{ni}} \left| \frac{\partial^n}{\circ_{\alpha}^{\lambda, \beta} \delta_{1i} \dots \circ_{\alpha}^{\lambda, \beta} \delta_{ni}} f_i(\delta_{1i}, \dots, \delta_{ni}) \right|^{p_i} \circ_{\alpha}^{\lambda, \beta} \delta_{ni} \dots \circ_{\alpha}^{\lambda, \beta} \delta_{1i} \right)^{\frac{1}{p_i}}}{\left(\sum_{i=1}^n \frac{(k_{1i} - \epsilon_0) \dots (k_{ni} - \epsilon_0)}{q_i} \right)^{\sum_{i=1}^n \frac{1}{q_i}}} \\
& \quad \circ_{\alpha}^{\lambda, \beta} k_{11} \dots \circ_{\alpha}^{\lambda, \beta} k_{n1} \dots \circ_{\alpha}^{\lambda, \beta} k_{12} \dots \circ_{\alpha}^{\lambda, \beta} k_{n2} \dots \circ_{\alpha}^{\lambda, \beta} k_{1n} \dots \circ_{\alpha}^{\lambda, \beta} k_{nn} \\
& \leq \left(n - \sum_{i=1}^n \frac{1}{p_i} \right)^{\sum_{i=1}^n \frac{1}{p_i} - n} \\
& \times \prod_{i=1}^n \int_{\epsilon_0}^{\epsilon_{1i}} \dots \int_{\epsilon_0}^{\epsilon_{ni}} \left(\int_{\epsilon_0}^{k_{1i}} \dots \int_{\epsilon_0}^{k_{ni}} \left| \frac{\partial^n}{\circ_{\alpha}^{\lambda, \beta} \delta_{1i} \dots \circ_{\alpha}^{\lambda, \beta} \delta_{ni}} f_i(\delta_{1i}, \dots, \delta_{ni}) \right|^{p_i} \circ_{\alpha}^{\lambda, \beta} \delta_{ni} \dots \circ_{\alpha}^{\lambda, \beta} \delta_{1i} \right)^{\frac{1}{p_i}} \circ_{\alpha}^{\lambda, \beta} k_{ni} \dots \circ_{\alpha}^{\lambda, \beta} k_{1i} \\
& \leq \left(n - \sum_{i=1}^n \frac{1}{p_i} \right)^{\sum_{i=1}^n \frac{1}{p_i} - n} \prod_{i=1}^n ((\epsilon_{1i} - \epsilon_0) \dots (\epsilon_{ni} - \epsilon_0))^{\frac{1}{q_i}} \\
& \left(\int_{\epsilon_0}^{\epsilon_{1i}} \dots \int_{\epsilon_0}^{\epsilon_{ni}} \left(\int_{\epsilon_0}^{k_{1i}} \dots \int_{\epsilon_0}^{k_{ni}} \left| \frac{\partial^n}{\circ_{\alpha}^{\lambda, \beta} \delta_{1i} \dots \circ_{\alpha}^{\lambda, \beta} \delta_{ni}} f_i(\delta_{1i}, \dots, \delta_{ni}) \right|^{p_i} \circ_{\alpha}^{\lambda, \beta} \delta_{ni} \dots \circ_{\alpha}^{\lambda, \beta} \delta_{1i} \right)^{\frac{1}{p_i}} \circ_{\alpha}^{\lambda, \beta} k_{ni} \dots \circ_{\alpha}^{\lambda, \beta} k_{1i} \right)^{\frac{1}{p_i}} \\
& = M \prod_{i=1}^n \left(\int_{\epsilon_0}^{\epsilon_{1i}} \dots \int_{\epsilon_0}^{\epsilon_{ni}} \prod_{j=1}^n (\epsilon_{ji} - k_{ji}) \left| \frac{\partial^n}{\circ_{\alpha}^{\lambda, \beta} k_{1i} \dots \circ_{\alpha}^{\lambda, \beta} k_{ni}} f_i(k_{1i}, \dots, k_{ni}) \right|^{p_i} \circ_{\alpha}^{\lambda, \beta} k_{ni} \dots \circ_{\alpha}^{\lambda, \beta} k_{1i} \right)^{\frac{1}{p_i}} \\
& \leq M \prod_{i=1}^n \left(\int_{\epsilon_0}^{\epsilon_{1i}} \dots \int_{\epsilon_0}^{\epsilon_{ni}} \prod_{j=1}^n (h(\epsilon_{ji}) - k_{ji}) \left| \frac{\partial^n}{\circ_{\alpha}^{\lambda, \beta} k_{1i} \dots \circ_{\alpha}^{\lambda, \beta} k_{ni}} f_i(k_{1i}, \dots, k_{ni}) \right|^{p_i} \circ_{\alpha}^{\lambda, \beta} k_{ni} \dots \circ_{\alpha}^{\lambda, \beta} k_{1i} \right)^{\frac{1}{p_i}}.
\end{aligned}$$

Remarks 3.2

- i. In Theorem 3.1, let $\mathbb{T} = \mathbb{Z}$, $\alpha = 0$, and $\lambda = 1$, then we see the results of Theorem 2.1 in [3].
- ii. In Theorem 3.1, let $\mathbb{T} = \mathbb{R}$, $\alpha = 0$, and $\lambda = 1$, then we see the results of Theorem 2.2 in [3].

Corollary 3.3 In Theorem 3.1, let $\alpha=0$, if we take $f_i(\theta_i)$ instead of $f_i(k_{1i}, \dots, k_{ni})$, then we see $f_i(\epsilon_0) = 0$, and then we obtain

$$\int_{\epsilon_0}^{k_1} \int_{\epsilon_0}^{k_2} \dots \int_{\epsilon_0}^{k_n} \frac{\prod_{i=1}^n |f_i(\theta_i)|}{\left(\sum_{i=1}^n \frac{(\theta_i - \epsilon_0)}{q_i}\right)^{\sum_{i=1}^n \frac{1}{q_i}}} \diamond_{\alpha}^{\lambda, \beta} \theta_n \diamond_{\alpha}^{\lambda, \beta} \theta_{n-1} \dots \diamond_{\alpha}^{\lambda, \beta} \theta_1$$

$$\leq S \prod_{i=1}^n \left(\int_{\epsilon_0}^{k_i} (h(k_i) - h(\theta_i)) \left| f_i \diamond_{\alpha}^{\lambda, \beta}(\theta_i) \right|^{p_i} \diamond_{\alpha}^{\lambda, \beta} \delta_i \diamond_{\alpha}^{\lambda, \beta} \theta_i \right)^{\frac{1}{p_i}}, \quad (9)$$

where $S = \left(n - \sum_{i=1}^n \frac{1}{p_i}\right)^{\sum_{i=1}^n \frac{1}{p_i} - n} \prod_{i=1}^n (k_i - \epsilon_0)^{\frac{1}{q_i}}$.

Remarks 3.4 Let $n = 2, \alpha = 0$, in Corollary 3.3, if $p_1, p_2 > 1$ with $1/p_1 + 1/p_2 \geq 1$, and $0 < \lambda = 2 - 1/p_1 - 1/p_2 = 1/q_1 + 1/q_2 \leq 1$, inequality (9) reduces to inequality

$$\int_{\epsilon_0}^{k_1} \int_{\epsilon_0}^{k_2} \frac{|f_1(\theta_1)| |f_2(\theta_2)|}{(q_2(\theta_1 - \epsilon_0) + q_1(\theta_2 - \epsilon_0))^w} \diamond_{\alpha}^{\lambda, \beta} \theta_2 \diamond_{\alpha}^{\lambda, \beta} \theta_1 \leq \frac{1}{(wq_1q_2)^w} (k_1 - \epsilon_0)^{\frac{1}{q_1}} (k_2 - \epsilon_0)^{\frac{1}{q_2}}$$

$$\times \left(\int_{\epsilon_0}^{k_1} (h(k_1) - h(\theta_1)) \left| f_1 \diamond_{\alpha}^{\lambda, \beta}(\theta_1) \right|^{p_1} \diamond_{\alpha}^{\lambda, \beta} \theta_1 \right)^{\frac{1}{p_1}} \left(\int_{\epsilon_0}^{k_2} (h(k_2) - h(\theta_2)) \left| f_2 \diamond_{\alpha}^{\lambda, \beta}(\theta_2) \right|^{p_2} \diamond_{\alpha}^{\lambda, \beta} \theta_2 \right)^{\frac{1}{p_2}}.$$

Conclusion

Hardy and Hilbert inequalities in different structures have been presented by researchers before. In this study, we have constructed new structures of Hardy-Hilbert inequalities in time scales for diamond alpha calculation. To be more precise, we have constructed a new form of Hardy-Hilbert inequality in time scales. The results we have obtained will be a source of motivation for our work in different fields.

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Chapter 4

On n-Dimensional Hilbert-Type Inequalities on Time Scale

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INTRODUCTION

In general, inequalities and their different forms have a considerable place in harmonic analysis and other application areas. One of these is the well-known Hilbert inequality in mathematics. These integral inequalities also play an important role in calculating time scales, which combine continuous and different forms of cases. At the same time, these integral inequalities are one of the main cornerstones of applied mathematics. Before starting our work, we think giving some information about Hilbert's inequality will be useful. If the reader wants, he can look at the references section at the end of this work for more detailed information.

In [1], the theorems we give below are well-known classical statements about Hilbert's inequality.

Theorem 1.1. Let $p, q > 1$, $\frac{1}{p} + \frac{1}{q} \leq 1$, and $0 < w = 2 - \frac{1}{p} - \frac{1}{q} = \frac{1}{p'} + \frac{1}{q'} \leq 1$, then

$$\sum_{j=1}^{\infty} \sum_{i=1}^{\infty} \frac{f_j g_i}{(j+i)^w} \leq D \left(\sum_{j=1}^{\infty} f_j^p \right)^{\frac{1}{p}} \left(\sum_{i=1}^{\infty} g_i^q \right)^{\frac{1}{q}}, \quad (1)$$

where $D = D(p, q)$.

Theorem 1.2. Let $f \in L^p(0, \infty)$, $g \in L^q(0, \infty)$, and let p, q, p', q', w be as in Theorem 1.1, then

$$\int_0^{\infty} \int_0^{\infty} \frac{f(x)g(y)}{(x+y)^w} dx dy \leq D \left(\int_0^{\infty} f^p(x) dx \right)^{\frac{1}{p}} \left(\int_0^{\infty} g^q(y) dy \right)^{\frac{1}{q}}, \quad (2)$$

where $D = D(p, q)$.

In [2], Zhao et al. introduced a new inequality that is compatible with the structure of Theorem 1.2.

Theorem 1.3. Let $\frac{1}{p_i} + \frac{1}{q_i} = 1$ with $p_i > 1$, $\pi_i \geq 1$. Let differentiable function $f_i(\theta_i)$ on $[0, k_i]$, where $k_i \in (0, \infty)$. Assume $f_i(0) = 0$ for $(i = 1, \dots, n)$. Then

$$\int_0^{k_1} \int_0^{k_2} \dots \int_0^{k_n} \frac{\prod_{i=1}^n |f_i^{\pi_i}(\theta_i)|}{\left(\sum_{i=1}^n \frac{\theta_i}{q_i}\right)^{\sum_{i=1}^n \frac{1}{q_i}}} d\theta_n d\theta_{n-1} \dots d\theta_1 \leq D \prod_{i=1}^n \left(\int_0^{k_i} (k_i - \theta_i) |f_i^{\pi_i-1}(\theta_i) f_i'(\theta_i)|^{p_i} d\theta_i \right)^{\frac{1}{p_i}},$$

$$\text{where } D = \left(n - \sum_{i=1}^n \frac{1}{p_i} \right)^{\sum_{i=1}^n \frac{1}{p_i} - n} \prod_{i=1}^n \pi_i k_i^{\frac{1}{q_i}}.$$

For more detailed information on Hilbert inequalities, see monographs [3-27, 52-61].

PRELIMINARIES

Although the history of time scale calculation is not very long, it has positioned itself not only in the field of mathematics but also in other disciplines of science. It owes this position to the unification of continuous and discrete cases in mathematics. Due to this situation, scientists in almost every field have integrated this field into their field of study and have contributed many innovations to the literature. Analytical solutions of differential equations in applied mathematics and mathematical modeling in economics are just a few examples of these application areas. Those who want to have more general information can look at references [28, 42, 43, 44, 45-51]. \mathbb{T} is a time scale that arbitrary non-empty closed subset of real numbers (\mathbb{R}). In our study, we will take this situation of $(0, \infty)_{\mathbb{T}} = (0, \infty) \cap \mathbb{T}$ into consideration.

Now let's briefly give the basic concepts about the diamond-alpha derivative.

$\sigma, \rho: \mathbb{T} \rightarrow \mathbb{T}$ are defined by $\sigma(t) = \inf\{s \in \mathbb{T}: s > t\}$, $\rho(t) = \sup\{s \in \mathbb{T}: s > t\}$ for $t \in \mathbb{T}$. $\sigma(t)$ is the jump operator (forward), and $\rho(t)$ is the jump operator (backward), respectively. Let $\sigma(t) > t$, then t is *rs* (right-scattered), and let $\sigma(t) = t$, then t is called *rd* (right-dense). Let $\rho(t) < t$, then t is *ls* (left-scattered), and let $\rho(t) = t$, then t is called *ld* (left-dense).

Let $\mu, \vartheta: \mathbb{T} \rightarrow \mathbb{R}^+$ such that $\mu(t) = \sigma(t) - t$, $\vartheta(t) = t - \rho(t)$. $\mu(t)$ and $\vartheta(t)$ are called *gm* (graininess mappings).

If the time scale \mathbb{T} has a *ls* (left-scattered) maximum m , then $\mathbb{T}^k = \mathbb{T} - \{m\}$.
 Otherwise $\mathbb{T}^k = \mathbb{T}$.

\mathbb{T}^k is defined as follows

$$\mathbb{T}^k = \begin{cases} \mathbb{T} \setminus (\rho \sup \mathbb{T}, \sup \mathbb{T}], & \text{if } \sup \mathbb{T} < \infty \\ \mathbb{T}, & \text{if } \sup \mathbb{T} = \infty, \end{cases}$$

and

$$\mathbb{T}_k = \begin{cases} \mathbb{T} \setminus [\inf \mathbb{T}, \sigma(\inf \mathbb{T})], & |\inf \mathbb{T}| < \infty \\ \mathbb{T}, & \inf \mathbb{T} = -\infty. \end{cases}$$

Assume that $h: \mathbb{T} \rightarrow \mathbb{R}$ is a function. Let t be right-dense.

- i) Let π be delta differentiable at t ($t \in \mathbb{T}^k(t \neq \min \mathbb{T})$), then π is continuous at t .
- ii) Let π be *lc* (left continuous) at t , and t is *rs* (right-scattered), then π is delta differentiable at t ,

$$\pi^\Delta(t) = \frac{\pi^\sigma(t) - \pi(t)}{\mu(t)}$$

- iii) Let π be delta differentiable at t and $\lim_{s \rightarrow t} \frac{\pi(t) - \pi(s)}{t - s}$, then

$$\pi^\Delta(t) = \lim_{s \rightarrow t} \frac{\pi(t) - \pi(s)}{t - s}.$$

- iv) Let π be delta differentiable at t , then $\pi^\sigma(t) = \pi(t) + \mu(t)\pi^\Delta(t)$.

Let $\mathbb{T} = \mathbb{R}$, then $\pi^\Delta(t) = \pi'(t)$, and Let $\mathbb{T} = \mathbb{Z}$, then $\pi^\Delta(t)$ reduces to $\Delta\pi(t)$.

Let $K: \mathbb{T} \rightarrow \mathbb{R}$ is defined as a delta antiderivative of $\pi: \mathbb{T} \rightarrow \mathbb{R}$, then $K^\Delta = \pi(t)$ holds for all $t \in \mathbb{T}$, and we define the delta integral of π by

$$\int_s^t \pi(\tau) \Delta\tau = K(t) - K(s),$$

for all $s, t \in \mathbb{T}$.

Suppose $\pi: \mathbb{R} \rightarrow \mathbb{R}$ is a continuous function and delta differentiable on \mathbb{T} . If $\varphi: \mathbb{R} \rightarrow \mathbb{R}$ is continuously differentiable, then we have

$$(\varphi \circ \pi)^\Delta(s) = \varphi'(\pi(m))\pi^\Delta(s), \quad m \in [s, \sigma(s)].$$

Let's now give some definitions for the nabla integral.

Let $\pi: \mathbb{T}_k \rightarrow \mathbb{R}$ is called nabla differentiable at $t \in \mathbb{T}_k$. If $\varepsilon > 0$, then the following inequality is provided

$$|\pi(\rho(t)) - \pi(s) - \pi^\nabla(t)(\rho(t) - s)| \leq \varepsilon|\rho(t) - s|,$$

for all $s \in V$.

Let $K: \mathbb{T} \rightarrow \mathbb{R}$ is called a nabla antiderivative of $\pi: \mathbb{T} \rightarrow \mathbb{R}$, then we define

$$\int_s^t \pi(\tau) \nabla \tau = K(t) - K(s),$$

for all $s, t \in \mathbb{T}$.

In [50], Let $\vartheta(t)$ be diamond alpha differentiable on \mathbb{T} for all $\alpha, t \in \mathbb{T}$, then we define $\vartheta^{\circ\alpha}(t)$ by

$$\vartheta^{\circ\alpha}(t) = \alpha \vartheta^\Delta(t) + (1-\alpha)\vartheta^\nabla(t)$$

for $0 \leq \alpha \leq 1$.

Theorem 2.1 [50] Let $\vartheta, h: \mathbb{T} \rightarrow \mathbb{R}$ be diamond alpha differentiable for all $\alpha, t \in \mathbb{T}$ and $0 \leq \alpha \leq 1$.

(i) Let $(\vartheta + h): \mathbb{T} \rightarrow \mathbb{R}$ be diamond alpha differentiable for all $t \in \mathbb{T}$, then

$$(\vartheta + h)^{\circ\alpha}(t) = \vartheta^{\circ\alpha}(t) + h^{\circ\alpha}(t).$$

(ii) Let $k\vartheta: \mathbb{T} \rightarrow \mathbb{R}$ be diamond alpha differentiable for all $\alpha, t \in \mathbb{T}$, then

$$(k\vartheta)^{\circ\alpha}(t) = k\vartheta^{\circ\alpha}(t),$$

where $t, k \in \mathbb{R}$.

(iii) Let $\vartheta, h: \mathbb{T} \rightarrow \mathbb{R}$ be diamond alpha differentiable for all $\alpha, t \in \mathbb{T}$, then

$$(\vartheta h)^{\diamond_\alpha}(t) = \vartheta^{\diamond_\alpha}(t)h(t) + \alpha \vartheta^\sigma(t)h^\Delta(t) + (1-\alpha)\vartheta^\rho(t)h^\nabla(t).$$

Definition 2.2 [50] If $\vartheta: \mathbb{T} \rightarrow \mathbb{R}$ is \diamond_α -integrable for all $\alpha, b, t \in \mathbb{T}$, then

$$\int_b^t \vartheta(\delta) \diamond_\alpha \delta = \alpha \int_b^t \vartheta(\delta) \Delta \delta + (1-\alpha) \int_b^t \vartheta(\delta) \nabla \delta$$

for $0 \leq \alpha \leq 1$.

Definition 2.3 [46, 52] Let $\vartheta \in C_{rd}(\mathbb{T}, \mathbb{R})$, $t \in \mathbb{T}^k$ and let $\vartheta: \mathbb{T} \rightarrow \mathbb{R}$ be diamond alpha integrable, then

$$\int_t^{\sigma(t)} \vartheta(\tau) \diamond_\alpha \tau = \mu(t)\vartheta(t).$$

The partial integration formula on the time scale is given by

$$\int_x^y u(s)w^{\diamond_\alpha}(s) \diamond_\alpha s = u(s)w(s)I_x^y - \int_x^y u^{\diamond_\alpha}(s)w^\sigma(s) \diamond_\alpha s$$

for $0 \leq \alpha \leq 1$.

Definition 2.4 [25, 51] (Conformable diamond-alpha derivative) Given $\vartheta: \mathbb{T} \rightarrow \mathbb{R}$ and $\beta \in \mathbb{T}$, ϑ is (λ, β) -diamond alpha differentiable at $\eta > \beta$, if it's diamond alpha differentiable at η , and its (λ, β) -diamond alpha derivative is defined by

$$\diamond_{\alpha\beta}^\lambda \vartheta(\eta) = \Lambda_{1-\lambda}(\eta, \beta)\vartheta^{\diamond_\alpha}(\eta) \quad \eta > \beta, \quad (3)$$

Definition 2.5 [25, 51] (Conformable diamond-alpha integral) Suppose that $\beta, \eta_1, \eta_2 \in \mathbb{T}$, $\vartheta \in C(\mathbb{T})$, $0 < \lambda \leq 1$, $\beta \leq \eta_1 \leq \eta_2$, and the function ϑ is called (λ, β) -diamond alpha integrable on $[\eta_1, \eta_2]$ if

$$\diamond_{\alpha\beta}^{\lambda} \vartheta(\eta) = \int_{\eta_1}^{\eta_2} \vartheta(\eta) \diamond_{\alpha\beta}^{\lambda} \eta = \int_{\eta_1}^{\eta_2} \vartheta(\eta) \Lambda_{1-\lambda}(\sigma^{1-\lambda}(\eta), \beta) \diamond_{\alpha} \eta, \quad (4)$$

Lemma 2.6 [14] If $f, \varepsilon \in CC_{rd}^1([\omega, p]_{\mathbb{T}} \times [\omega, p]_{\mathbb{T}}, \mathbb{R})$ are diamond alpha integrable functions and $\frac{1}{p} + \frac{1}{q} = 1$ with $p > 1$ and let $\omega, p \in \mathbb{T}$ with $\omega < p$, then

$$\begin{aligned} & \int_{\omega}^p \int_{\omega}^p |f(t, \varepsilon) \varepsilon(t, \varepsilon)| \diamond_{\alpha}^{\lambda, \beta} t \diamond_{\alpha}^{\lambda, \beta} \varepsilon \\ & \leq \left(\int_{\omega}^p \int_{\omega}^p |f(t, \varepsilon)|^p \diamond_{\alpha}^{\lambda, \beta} t \diamond_{\alpha}^{\lambda, \beta} \varepsilon \right)^{\frac{1}{p}} \times \left(\int_{\omega}^p \int_{\omega}^p |\varepsilon(t, \varepsilon)|^q \diamond_{\alpha}^{\lambda, \beta} t \diamond_{\alpha}^{\lambda, \beta} \varepsilon \right)^{\frac{1}{q}}. \end{aligned} \quad (5)$$

In this study, we prove a new fractional inequality of Hilbert-type on time scales using the properties of Theorem 1.3 mentioned above. We also obtain discrete cases of Hilbert-type inequalities related to some special cases of our results.

Main Result

Theorem 3.1 Let $\varepsilon_0, \tau_i, k_i, \theta_i, \varepsilon_i \in \mathbb{T}$, ($i = 1, \dots, n$). Let $p_i, q_i > 1, \pi_i \geq 1$ be constants and $\frac{1}{p_i} + \frac{1}{q_i} = 1$ and let $\diamond_{\alpha}^{\lambda, \beta}$ -differentiable functions and $f_i(\theta_i, \varepsilon_i)$ be decreasing on $[\varepsilon_0, k_i]_{\mathbb{T}} \times [\varepsilon_0, \tau_i]_{\mathbb{T}}$ and $f_i(\varepsilon_0, \varepsilon_i) = f_i(\theta_i, \varepsilon_0) = 0$ ($i=1, \dots, n$). Let $f_i^{\diamond_{\alpha_1}^{\lambda, \beta}}, f_i^{\diamond_{\alpha_2}^{\lambda, \beta}}, f_i^{\diamond_{\alpha_{12}}^{\lambda, \beta}} = f_i^{\diamond_{\alpha_{21}}^{\lambda, \beta}}$ partial derivatives of f_i and let

$$(f_i^{\pi_i}(\theta_i, \varepsilon_i))^{\diamond_{\alpha_1}^{\lambda, \beta} \diamond_{\alpha_2}^{\lambda, \beta}} \leq \left(\pi_i f_i^{\pi_i-1}(\theta_i, \varepsilon_i) f_i^{\diamond_{\alpha_1}^{\lambda, \beta}}(\theta_i, \varepsilon_i) \right)^{\diamond_{\alpha_2}^{\lambda, \beta}} = f_i^{\diamond_{\alpha_{12}}^{\lambda, \beta}}(\theta_i, \varepsilon_i),$$

then

$$\begin{aligned} & \int_{\epsilon_0}^{k_1} \int_{\epsilon_0}^{\tau_1} \dots \int_{\epsilon_0}^{k_n} \int_{\epsilon_0}^{\tau_n} \frac{\prod_{i=1}^n |f_i^{\pi_i}(\theta_i, \epsilon_i)|}{\left(\sum_{i=1}^n \frac{(\theta_i - \epsilon_0)(\epsilon_i - \epsilon_0)}{q_i}\right)^{\sum_{i=1}^n \frac{1}{p_i}}} \diamond_{\alpha}^{\lambda, \beta} \epsilon_n \diamond_{\alpha}^{\lambda, \beta} \theta_n \dots \diamond_{\alpha}^{\lambda, \beta} \epsilon_1 \diamond_{\alpha}^{\lambda, \beta} \theta_1 \\ & \leq B \prod_{i=1}^n \left(\int_{\epsilon_0}^{k_i} \int_{\epsilon_0}^{\tau_i} (h(k_i) - h(\theta_i))(h(\tau_i) - h(\epsilon_i)) \left| f_i^{\diamond_{\alpha}^{\lambda, \beta}}(\theta_i, \epsilon_i) \right|^{p_i} \diamond_{\alpha}^{\lambda, \beta} \epsilon_i \diamond_{\alpha}^{\lambda, \beta} \theta_i \right)^{\frac{1}{p_i}}, \end{aligned} \quad (6)$$

where $B = B(k_1\tau_1, \dots, k_n\tau_n) = \left(n - \sum_{i=1}^n \frac{1}{p_i}\right)^{\sum_{i=1}^n \frac{1}{p_i} - n} \prod_{i=1}^n [(k_i - \epsilon_0)(\tau_i - \epsilon_0)]^{\frac{1}{q_i}}$.

Proof. We can write the following inequality

$$\begin{aligned} f_i^{\pi_i}(\theta_i, \epsilon_i) &= f_i^{\pi_i}(\theta_i, \epsilon_i) - f_i^{\pi_i}(\epsilon_0, \epsilon_i) - f_i^{\pi_i}(\theta_i, \epsilon_0) f_i^{\pi_i}(\epsilon_0, \epsilon_0) \\ &= \int_{\epsilon_0}^{\theta_i} (f_i^{\pi_i}(\eta_i, \epsilon_i))^{\diamond_{\alpha_1}^{\lambda, \beta}} \diamond_{\alpha_1}^{\lambda, \beta} \eta_i - \int_{\epsilon_0}^{\theta_i} (f_i^{\pi_i}(\eta_i, \epsilon_0))^{\diamond_{\alpha_1}^{\lambda, \beta}} \diamond_{\alpha_1}^{\lambda, \beta} \eta_i \\ &= \int_{\epsilon_0}^{\theta_i} \left[(f_i^{\pi_i}(\eta_i, \epsilon_i))^{\diamond_{\alpha_1}^{\lambda, \beta}} - (f_i^{\pi_i}(\eta_i, \epsilon_0))^{\diamond_{\alpha_1}^{\lambda, \beta}} \right] \diamond_{\alpha}^{\lambda, \beta} \eta_i \\ &\leq \int_{\epsilon_0}^{\theta_i} \int_{\epsilon_0}^{\epsilon_i} \left[\pi_i f_i^{\pi_i-1}(\eta_i, \varphi_i) f_i^{\diamond_{\alpha_1}^{\lambda, \beta}}(\eta_i, \varphi_i) \right]^{\diamond_{\alpha_2}^{\lambda, \beta}} \diamond_{\alpha}^{\lambda, \beta} \eta_i \diamond_{\alpha}^{\lambda, \beta} \varphi_i \\ &= \int_{\epsilon_0}^{\theta_i} \int_{\epsilon_0}^{\epsilon_i} f_i^{\diamond_{\alpha}^{\lambda, \beta}}(\eta_i, \varphi_i) \diamond_{\alpha}^{\lambda, \beta} \varphi_i \diamond_{\alpha}^{\lambda, \beta} \eta_i. \end{aligned} \quad (7)$$

Applying (5), we have

$$\begin{aligned} \prod_{i=1}^n f_i^{\pi_i}(\theta_i, \epsilon_i) &\leq \prod_{i=1}^n \int_{\epsilon_0}^{\theta_i} \int_{\epsilon_0}^{\epsilon_i} f_i^{\circ_{\alpha} \lambda, \beta}(\eta_i, \varphi_i) \circ_{\alpha}^{\lambda, \beta} \varphi_i \circ_{\alpha}^{\lambda, \beta} \eta_i \\ &\leq \prod_{i=1}^n ((\theta_i - \epsilon_0)(\epsilon_i - \epsilon_0))^{\frac{1}{q_i}} \left(\int_{\epsilon_0}^{\theta_i} \int_{\epsilon_0}^{\epsilon_i} f_i^{\circ_{\alpha} \lambda, \beta}(\eta_i, \varphi_i) \circ_{\alpha}^{\lambda, \beta} \varphi_i \circ_{\alpha}^{\lambda, \beta} \eta_i \right)^{\frac{1}{p_i}}. \end{aligned} \quad (8)$$

Applying the following inequality

$$\left(\prod_{i=1}^n w_i^{\frac{1}{q_i}} \right)^{\frac{1}{\sum_{i=1}^n \frac{1}{q_i}}} \leq \frac{1}{\sum_{i=1}^n \frac{1}{q_i}} \sum_{i=1}^n \frac{w_i}{q_i}, \quad w_i > 0 \quad (i = 1, \dots, n),$$

we find

$$\begin{aligned} &\frac{\prod_{i=1}^n |f_i^{\pi_i}(\theta_i, \epsilon_i)|}{\left(\sum_{i=1}^n \frac{(\theta_i - \epsilon_0)(\epsilon_i - \epsilon_0)}{q_i} \right)^{\sum_{i=1}^n \frac{1}{q_i}}} \\ &\leq \left(n - \sum_{i=1}^n \frac{1}{p_i} \right)^{\sum_{i=1}^n \frac{1}{p_i} - n} \prod_{i=1}^n \left(\int_{\epsilon_0}^{\theta_i} \int_{\epsilon_0}^{\epsilon_i} f_i^{\circ_{\alpha} \lambda, \beta}(\eta_i, \varphi_i) \circ_{\alpha}^{\lambda, \beta} \varphi_i \circ_{\alpha}^{\lambda, \beta} \eta_i \right)^{\frac{1}{p_i}}. \end{aligned} \quad (9)$$

From inequality (5) and Fubini's theorem, we see that

$$\begin{aligned}
& \int_{\epsilon_0}^{k_1} \int_{\epsilon_0}^{\tau_1} \dots \int_{\epsilon_0}^{k_n} \int_{\epsilon_0}^{\tau_n} \frac{\prod_{i=1}^n |f_i^{\pi_i}(\theta_i, \epsilon_i)|}{\left(\sum_{i=1}^n \frac{(\theta_i - \epsilon_0)(\epsilon_i - \epsilon_0)}{q_i}\right)^{\sum_{i=1}^n \frac{1}{q_i}}} \diamond_{\alpha}^{\lambda, \beta} \epsilon_n \diamond_{\alpha}^{\lambda, \beta} \theta_n \dots \diamond_{\alpha}^{\lambda, \beta} \epsilon_1 \diamond_{\alpha}^{\lambda, \beta} \theta_1 \\
& \leq \left(n - \sum_{i=1}^n \frac{1}{p_i}\right)^{\sum_{i=1}^n \frac{1}{p_i} - n} \times \prod_{i=1}^n \left(\int_{\epsilon_0}^{k_i} \int_{\epsilon_0}^{\tau_i} \left(\int_{\epsilon_0}^{\theta_i} \int_{\epsilon_0}^{\epsilon_i} \left| f_i^{\diamond_{\alpha}^{\lambda, \beta}}(\eta_i, \varphi_i) \right|^{p_i} \diamond_{\alpha}^{\lambda, \beta} \varphi_i \diamond_{\alpha}^{\lambda, \beta} \eta_i \right)^{\frac{1}{p_i}} \diamond_{\alpha}^{\lambda, \beta} \epsilon_i \diamond_{\alpha}^{\lambda, \beta} \theta_i \right) \\
& \leq \left(n - \sum_{i=1}^n \frac{1}{p_i}\right)^{\sum_{i=1}^n \frac{1}{p_i} - n} \\
& \times \prod_{i=1}^n \left((k_i - \epsilon_0)(\tau_i - \epsilon_0) \right)^{\frac{1}{q_i}} \left(\int_{\epsilon_0}^{k_i} \int_{\epsilon_0}^{\tau_i} \left(\int_{\epsilon_0}^{\theta_i} \int_{\epsilon_0}^{\epsilon_i} \left| f_i^{\diamond_{\alpha}^{\lambda, \beta}}(\eta_i, \varphi_i) \right|^{p_i} \diamond_{\alpha}^{\lambda, \beta} \varphi_i \diamond_{\alpha}^{\lambda, \beta} \eta_i \right) \diamond_{\alpha}^{\lambda, \beta} \epsilon_i \diamond_{\alpha}^{\lambda, \beta} \theta_i \right)^{\frac{1}{p_i}} \\
& = B \prod_{i=1}^n \left(\int_{\epsilon_0}^{k_i} \int_{\epsilon_0}^{\tau_i} (k_i - \theta_i)(\tau_i - \epsilon_i) \left| f_i^{\diamond_{\alpha}^{\lambda, \beta}}(\theta_i, \epsilon_i) \right|^{p_i} \diamond_{\alpha}^{\lambda, \beta} \epsilon_i \diamond_{\alpha}^{\lambda, \beta} \theta_i \right)^{\frac{1}{p_i}}. \tag{10}
\end{aligned}$$

Using $k_i \leq h(k_i)$, we obtain

$$\begin{aligned}
& \int_{\epsilon_0}^{k_1} \int_{\epsilon_0}^{\tau_1} \dots \int_{\epsilon_0}^{k_n} \int_{\epsilon_0}^{\tau_n} \frac{\prod_{i=1}^n |f_i^{\pi_i}(\theta_i, \epsilon_i)|}{\left(\sum_{i=1}^n \frac{(\theta_i - \epsilon_0)(\epsilon_i - \epsilon_0)}{q_i}\right)^{\sum_{i=1}^n \frac{1}{q_i}}} \diamond_{\alpha}^{\lambda, \beta} \epsilon_n \diamond_{\alpha}^{\lambda, \beta} \theta_n \dots \diamond_{\alpha}^{\lambda, \beta} \epsilon_1 \diamond_{\alpha}^{\lambda, \beta} \theta_1 \\
& \leq B \prod_{i=1}^n \left(\int_{\epsilon_0}^{k_i} \int_{\epsilon_0}^{\tau_i} (h(k_i) - h(\theta_i))(h(\tau_i) \right. \\
& \quad \left. - h(\epsilon_i)) \left| f_i^{\diamond_{\alpha}^{\lambda, \beta}}(\theta_i, \epsilon_i) \right|^{p_i} \diamond_{\alpha}^{\lambda, \beta} \epsilon_i \diamond_{\alpha}^{\lambda, \beta} \theta_i \right)^{\frac{1}{p_i}}.
\end{aligned}$$

Remarks 3.2

- i. In Theorem 3.1, let $\mathbb{T} = \mathbb{Z}$, $\alpha = 0$, $\lambda = 1$, and $\pi_i = 1$, then we see the results of (Theorem 1.2, [2]).
- ii. In Theorem 3.1, let $\mathbb{T} = \mathbb{R}$, $\alpha = 0$, $\lambda = 1$, then we see the results of (Theorem 1.4, [2]).

Corollary 3.3 In Theorem 3.1, let $n = 2, \pi_1 = \pi_2 = 1$. Also let $f_1^{\circ_{\alpha_1 2}^{\lambda, \beta}}(\theta_1, \epsilon_1) = f^{\circ_{\alpha_2}^{\lambda, \beta} \circ_{\alpha_1}^{\lambda, \beta}}(\theta_1, \epsilon_1), f_2^{\circ_{\alpha_1 2}^{\lambda, \beta}}(\theta_2, \epsilon_2) = f^{\circ_{\alpha_2}^{\lambda, \beta} \circ_{\alpha_1}^{\lambda, \beta}}(\theta_2, \epsilon_2)$.

If $p_1, p_2 > 1$ are such that $\frac{1}{p_1} + \frac{1}{p_2} \geq 1$ and $0 < w = 2 - \frac{1}{p_1} - \frac{1}{p_2} = \frac{1}{q_1} + \frac{1}{q_2} \leq 1$, inequality (6) reduces to

$$\begin{aligned} & \int_{\epsilon_0}^{k_1} \int_{\epsilon_0}^{\tau_1} \left(\int_{\epsilon_0}^{k_2} \int_{\epsilon_0}^{\tau_2} \frac{|f_1(\theta_1, \epsilon_1)| |f_2(\theta_2, \epsilon_2)|}{(f_1(\theta_1 - \epsilon_0)(\epsilon_1 - \epsilon_0) + q_1(\theta_1 - \epsilon_0)(\epsilon_2 - \epsilon_0))^w} {}_{\circ_{\alpha}^{\lambda, \beta}} \theta_2 \circ_{\alpha}^{\lambda, \beta} \epsilon_2 \right) {}_{\circ_{\alpha}^{\lambda, \beta}} \theta_1 \circ_{\alpha}^{\lambda, \beta} \epsilon_1 \\ & \leq \frac{1}{(wq_1q_2)^w} ((k_1 - \epsilon_0)(\tau_1 - \epsilon_0))^{\frac{1}{q_1}} ((k_2 - \epsilon_0)(\tau_2 - \epsilon_0))^{\frac{1}{q_1}} \\ & \times \left(\int_{\epsilon_0}^{k_1} \int_{\epsilon_0}^{\tau_1} (h(k_1) - h(\theta_1))(h(\tau_1) - h(\epsilon_1)) \left| f^{\circ_{\alpha_2}^{\lambda, \beta} \circ_{\alpha_1}^{\lambda, \beta}}(\theta_1, \epsilon_1) \right|^{p_1} {}_{\circ_{\alpha}^{\lambda, \beta}} \theta_1 \circ_{\alpha}^{\lambda, \beta} \epsilon_1 \right)^{\frac{1}{p_1}} \\ & \cdot \left(\int_{\epsilon_0}^{k_2} \int_{\epsilon_0}^{\tau_2} (h(k_2) - h(\theta_2))(h(\tau_2) - h(\epsilon_2)) \left| f^{\circ_{\alpha_2}^{\lambda, \beta} \circ_{\alpha_1}^{\lambda, \beta}}(\theta_2, \epsilon_2) \right|^{p_2} {}_{\circ_{\alpha}^{\lambda, \beta}} \theta_2 \circ_{\alpha}^{\lambda, \beta} \epsilon_2 \right)^{\frac{1}{p_2}}. \end{aligned} \quad (11)$$

Remarks 3.4

- i. Let $\mathbb{T} = \mathbb{R}, \alpha = 0, \lambda = 1$ in (11), then inequality (11) reduces to
- ii.

$$\begin{aligned} & \int_0^{k_1} \int_0^{\tau_1} \left(\int_0^{k_2} \int_0^{\tau_2} \frac{|f_1(\theta_1, \epsilon_1)| |f_2(\theta_2, \epsilon_2)|}{(p_1 \theta_1 \epsilon_1 + q_1 \theta_2 \epsilon_2)^w} d\theta_2 d\epsilon_2 \right) d\theta_1 d\epsilon_1 \leq \frac{1}{(wq_1q_2)^w} (k_1 \tau_1)^{\frac{1}{q_1}} (k_2 \tau_2)^{\frac{1}{q_1}} \\ & \times \left(\int_0^{k_1} \int_0^{\tau_1} (k_1 - \theta_1)(\tau_1 - \epsilon_1) |C_1 C_2 f_1(\theta_1, \epsilon_1)|^{p_1} d\theta_1 d\epsilon_1 \right)^{\frac{1}{p_1}} \\ & \cdot \left(\int_0^{k_2} \int_0^{\tau_2} (k_2 - \theta_2)(\tau_2 - \epsilon_2) |C_1 C_2 f_2(\theta_2, \epsilon_2)|^{p_2} d\theta_2 d\epsilon_2 \right)^{\frac{1}{p_2}}. \end{aligned} \quad (12)$$

- iii. Let $\mathbb{T} = \mathbb{Z}, \alpha = 0, \lambda = 1$ in (11), then inequality (11) reduces to

$$\begin{aligned}
& \sum_{\theta_1=1}^{m_1} \sum_{\epsilon_1=1}^{n_1} \left(\sum_{\theta_2=1}^{m_2} \sum_{\epsilon_2=1}^{n_2} \frac{|\beta_1(\theta_1, \epsilon_1)| |\beta_2(\theta_2, \epsilon_2)|}{(p_1 \theta_1 \epsilon_1 + q_1 \theta_2 \epsilon_2)^w} \right) \leq \frac{1}{(w q_1 q_2)^w} (m_1 n_1)^{\frac{1}{q_1}} (m_2 n_2)^{1 - \frac{1}{q_1}} \\
& \quad \times \left(\sum_{\theta_1=1}^{m_1} \sum_{\epsilon_1=1}^{n_1} (n_1 - \epsilon_1)(m_1 - \theta_1) \left| {}_{\diamond_{\alpha_1}}^{\lambda, \beta} \diamond_{\alpha_2}^{\lambda, \beta} \beta_1(\theta_1, \epsilon_1) \right|^{p_1} \right)^{\frac{1}{p_1}} \\
& \quad \cdot \left(\sum_{\theta_2=1}^{m_2} \sum_{\epsilon_2=1}^{n_2} (n_2 - \epsilon_2)(m_2 - \theta_2) \left| {}_{\diamond_{\alpha_1}}^{\lambda, \beta} \diamond_{\alpha_2}^{\lambda, \beta} \beta_2(\theta_2, \epsilon_2) \right|^{p_2} \right)^{\frac{1}{p_2}}. \tag{13}
\end{aligned}$$

Corollary 3.5 In Corollary 3.3, if we take $w = 1, p_1 = q_2$, and $p_2 = q_1$ with $\frac{1}{p_1} + \frac{1}{p_2} = \frac{1}{q_1} + \frac{1}{q_2} = 1$ then inequality (11) reduces to

$$\begin{aligned}
& \int_{\epsilon_0}^{k_1} \int_{\epsilon_0}^{\tau_1} \left(\int_{\epsilon_0}^{k_2} \int_{\epsilon_0}^{\tau_2} \frac{|f_1(\theta_1, \epsilon_1)| |f_2(\theta_2, \epsilon_2)|}{(f_1(\theta_1 - \epsilon_0)(\epsilon_1 - \epsilon_0) + q_1(\theta_2 - \epsilon_0)(\epsilon_2 - \epsilon_0))^{\diamond_{\alpha} \lambda, \beta} \theta_2 \diamond_{\alpha} \lambda, \beta \epsilon_2} \right) \diamond_{\alpha}^{\lambda, \beta} \theta_1 \diamond_{\alpha}^{\lambda, \beta} \epsilon_1 \\
& \quad \leq \frac{1}{p_1 q_1} ((k_1 - \epsilon_0)(\tau_1 - \epsilon_0))^{1 - \frac{1}{p_1}} ((k_2 - \epsilon_0)(\tau_2 - \epsilon_0))^{1 - \frac{1}{q_1}} \\
& \quad \times \left(\int_{\epsilon_0}^{k_1} \int_{\epsilon_0}^{\tau_1} (\pi(k_1) - \pi(\theta_1))(\pi(\tau_1) - \pi(\epsilon_1)) \left| f^{\diamond_{\alpha_2}^{\lambda, \beta} \diamond_{\alpha_1}^{\lambda, \beta}}(\theta_1, \epsilon_1) \right|^{p_1} \diamond_{\alpha}^{\lambda, \beta} \theta_1 \diamond_{\alpha}^{\lambda, \beta} \epsilon_1 \right)^{\frac{1}{p_1}} \\
& \quad \cdot \left(\int_{\epsilon_0}^{k_2} \int_{\epsilon_0}^{\tau_2} (\pi(k_2) - \epsilon_0)(\pi(\tau_2) - \epsilon_0) \left| f^{\diamond_{\alpha_2}^{\lambda, \beta} \diamond_{\alpha_1}^{\lambda, \beta}}(\theta_2, \epsilon_2) \right|^{p_2} \diamond_{\alpha}^{\lambda, \beta} \theta_2 \diamond_{\alpha}^{\lambda, \beta} \epsilon_2 \right)^{\frac{1}{p_2}}. \tag{14}
\end{aligned}$$

Remarks 3.6

- i. In Corollary 3.5, If we take $\mathbb{T} = \mathbb{R}, \alpha = 0, \lambda = 1$, we have Theorem 4 in [27].
- ii. In Corollary 3.5, If we take $\mathbb{T} = \mathbb{Z}, \alpha = 0, \lambda = 1$, we have Theorem 3 in [27].

Conclusion

The inequality of Hilbert’s in the different structures has been presented before. In this study, we have taken n-dimensional Hilbert inequalities on time scales for diamond alpha calculation and have created new inequalities of the results presented in previous studies. To be more precise, we have created a new form of inequality of Hilbert’s on time scales. The results we have obtained will motivate us to work in different areas.

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Chapter 5

Define The Frontlines of The Battle Against Breast Cancer with Immune Warriors

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1. Introduction

Breast cancer is a highly heterogeneous disease with significant variability in morphologic and pathologic features. Breast cancer, like skin and lung cancer, is a risky type of cancer that can metastasize to other organs (Den Oudsten, der Steeg, A., & De, 2012; Leone & Leone, 2015). Genetic and epigenetic changes in genes regulating mammary epithelial cell proliferation, survival, polarity, and differentiation likely initiate breast carcinogenesis.

Breast cancer has different molecular subtypes based on gene expression profiles (Mota et al., 2017; Yee, Borgia, Semenova, Campbell, & Booth, 2023). The most common molecular subtypes are luminal A, luminal B, HER2-positive (human epidermal growth factor receptor 2), and triple-negative (TNBC) cancers (Harbeck et al., 2019; Iqbal Memon, Din Ujjan, & Masroor Bhatti, 2023). Luminal A cancer comprises estrogen receptor-positive (ER+) and progesterone receptor-positive (PR+) cells. This type of cancer has a lower cell division rate than other molecular subtypes and generally has a better prognosis. Luminal B cancer consists of ER-positive cells but may not be PR+. This type of cancer is more aggressive and has a higher cell division rate than the luminal A type. HER2+ cancer cells produce extreme amounts of HER2 protein. This type of cancer requires a different treatment approach than other molecular subtypes. The TNBC consists of negative cells for both ER and PR receptors and does not have HER2 protein. This type of cancer can be more aggressive than other molecular subtypes, and treatment options are limited (Den Oudsten et al., 2012). Having HER2, activation of ER and/or PR receptors, as well as BRCA (breast cancer gene) mutations, which are among the molecular characteristics of breast cancer, determines the propensity of the disease (Harbeck et al., 2019). These molecular subtypes of breast cancer are essential for its diagnosis, prognosis, and treatment.

Recently, the focus of research has shifted from the tumor mass to the biological character of the tumor, with the molecular level of cancer disease elucidated. In this respect, it is known that the success rate of an individualized cancer treatment that focuses on the cell in the tumor mass that appears in the patient increases. In addition, since breast cancer is a heterogeneous disease in general, multidisciplinary approaches should not be ignored when aiming for an effective treatment. Breast cancer is 70-80% curable if it is diagnosed early and is not metastatic (Harbeck et al., 2019).

Cancer treatments consist of various methods used to destroy or control its growth. Determining a treatment strategy depends on the type and stage of cancer, as well as the condition of the patient's health. Cancer treatments include chemotherapy, radiotherapy, surgery, and immunotherapy. Currently, two major approaches are used to control breast cancer: regional intervention (surgery and

radiation therapy) and systemic treatment. The molecular character of the tumor greatly influences which treatment approach is chosen, such as chemotherapy, anti-HER2 therapy for HER2+ patients, endocrine therapy, and immunotherapy (Harbeck et al., 2019). However, current therapies are not fully adequate for the treatment of invasive breast cancer. In such patients, current therapies aim to control symptoms, improve the patient's life quality, and prolong survival, even to some extent (Iqbal Memon et al., 2023). These goals accompany the planning of numerous ongoing studies.

Multiple therapies, proposed as a combination of therapeutic approaches, improve the clinical management of diseases (Farokhzad & Langer, 2006). Especially in the fight against a multifaceted and treatment-resistant disease such as cancer, the ability to strike the disease from many angles at once increases the effectiveness of treatment. For example, combining hyperthermia, which aims to treat by increasing the temperature in the target tissue, and immunotherapy, which uses the patient's defense system, with other treatments (chemotherapy, radiotherapy, etc.) increases the effectiveness of treatments. Immunotherapy boosts the efficacy of surgery, chemotherapy, hyperthermia, radiotherapy, or targeted therapies used in cancer treatment (Chen & Mellman, 2013).

2. Passive immunity for breast cancer

The immune system plays an extremely important role in cancer development and in response to chemotherapy and clinical outcomes. Metastatic breast cancer is a heterogeneous disease that influences immune cells in the bloodstream and might lead to systemic immune anomalies. Tumor-infiltrating lymphocytes (TILs) are associated with a high pathological response to neoadjuvant chemotherapy in aggressive breast cancer (Poncin et al., 2021; Wagner et al., 2019). Circulating immune cells, including neutrophils, lymphocytes, and eosinophils, affect responses to chemotherapy and cancer outcomes. On the other hand, TILs are crucial in improving the chemotherapy response and clinical outcomes in all breast cancer subtypes.

To form a tumor mass, cancer cells can escape the immune system through a decrease in antigen presentation, a diminution of immune effector cells, and an increase in the expression of checkpoint molecules. The presence of TILs is reduced in ER+ breast cancer. TILs are more common in HER-2+ and TNBC, but also in hormone receptor-positive breast cancer. A study on immune cells related to ductal carcinoma found that 28% of cases were TIL-high (Agahozo et al., 2020). In this study, it has been reported that cases with ER+ HER2+ subtype have a higher proportion of CD8+ T cells than TNBC cases. The increase in ER expression may be responsible for this effect. This creates a Th2 immune

environment and lowers the number of MHC class II molecules in breast cancer cells. Classical HLA molecules (-A, -B, and -C) are down-regulated in 30-40% of higher-grade breast tumors (Nicolini, Rossi, & Ferrari, 2023). In contrast, non-classical HLA-E, HLA-F, and HLA-G molecules promote immune escape. TNBCs have lymphocyte-predominant tumors, benefiting from a 10% increase in TIL (Stanton & Disis, 2016). HER2+ breast cancers have similar immune infiltrate levels (Hwang et al., 2019). Hormone receptor-positive HER2-negative tumors have the minimum immune infiltrate but show a worse prognosis with increased FOXP3 (forkhead box P3, a protein from the FOX family) regulatory T-cell infiltrates.

Immune evasion may occur via the involvement of molecules in antigen presentation and mutations in interferon (IFN) response genes (Gatti-Mays et al., 2019). Pathway changes that promote cancer growth, such as mutations in the PI3K (phosphoinositide 3-kinases) pathway, are essential for suppressing or inhibiting the activation of T cells. Elevated frequencies of programmed cell death ligand 1 positive (PD-L1+) tumor-associated macrophages and depleted T lymphocytes with exhaustion were seen in high-grade ER+ and ER- cancers (Wagner et al., 2019). Another study demonstrated that the HER2+ subgroup had the lowest PD-L1-SP142 expression on tumor cells, indicating a more robust antitumor immune response in HER2+ ductal carcinoma *in situ* (Agahozo et al., 2020). Also, HER2-negative metastatic breast cancer caused elevated monocyte levels and reduced CD4+ T cells (Chauhan et al., 2024).

Tumor cells could increase the production of indoleamine-pyrrole 2,3 dioxygenase (IDO) in response to interferon-gamma and ER signaling. Cancers classified as ER+ exhibit elevated levels of IDO compared to ER- cancers (Nicolini et al., 2023). A study examining the expression and distribution levels of FoxP3 and CD8 in breast carcinoma found that overexpression of FoxP3 and a high FoxP3+/CD8+ ratio were associated with adverse outcomes in terms of both overall survival and disease-free survival (Peng et al., 2019). The CD8+ cytotoxic T lymphocytes (CTLs) and FoxP3+ regulatory T (Treg) cells might behave as prognostic markers for breast cancer patients. Patients with metastatic breast cancer who exhibit systemic immunological markers have an immune-suppressed environment, which is associated with persistent chronic inflammation. However, in a normal process, Treg cells maintain immune homeostasis in the body by suppressing excessive immune system reactions. In contrast, in cancer like breast cancer, this role reverses to promoting tumor development and growth (Liang et al., 2015). The immunosuppressive effect of increasing Treg cells in the tumor microenvironment contributes to cancer progression, which diminishes immune responses to cancer. In breast cancer, a

significantly higher number of Treg cells has been considered as the marker of a poor prognosis (Hashemi et al., 2020). Treg cells suppress the activity of antitumoral immune cells, such as CD8⁺ cytotoxic T cells and NK cells (Hashemi et al., 2020; Togashi, Shitara, & Nishikawa, 2019). This suppression is usually mediated by molecules such as CTLA-4, IL-10, and TGF- β . These molecules inhibit the activation of T cells and limit antigen presentation by impairing the function of dendritic cells (DCs). In these ways, Treg cells resist immunotherapies, creating resistance to therapies and reducing their effectiveness in cancer treatments. Hence, therapeutic strategies that inhibit function of Treg cells enhance immunotherapies' effectiveness (Shan, Somasundaram, Bruno, Workman, & Vignali, 2022).

On the other hand, tumor-promoting immune cells, including Treg cells and myeloid-derived suppressor cells (MDSCs), perform an essential function in maintaining immune homeostasis and peripheral tolerance (Binnewies et al., 2018; X. Lei et al., 2020; Sadeghi, Dehnavi, Sharifat, Amiri, & Khodadadi, 2024). Granulocytic or polymorphonuclear MDSCs (PMN-MDSCs) and monocytic MDSCs (M-MDSCs) are two types of tumor-promoting immune cells within the tumor microenvironment (TME) (Gatti-Mays et al., 2019; Zhao et al., 2018). They have the potential to increase angiogenesis, stimulate cancer cell migration towards endothelial cells, and facilitate metastasis. Inhibiting MDSC trafficking has been shown to enhance T cell-based immunotherapeutic efficacy.

To summarize, TILs, Treg cells, MDSCs, and some mediator molecules (IFNs, IDO, etc.) significantly impact the treatment response and prognosis of breast cancer. Oncogenic cells have mechanisms to evade the immune system, affecting treatment outcomes. Different breast cancer subtypes vary in their immune profiles, which influences treatment strategies. Finally, examining immune responses and immune-related molecules might serve as biomarkers for estimating the rate of breast cancer development and therapeutic efficacy.

3. Immune cells in the tumor microenvironment

In carcinogenesis, cancer development, and metastasis, the TME is an essential player. Additionally, immune cells play a crucial role in treating and preventing breast cancer (Figure 1). Effector T cells, DCs, natural killer (NK) cells, M1 polarized macrophages, and N1 polarized neutrophils are types of anti-tumor immune cells (X. Lei et al., 2020; Sadeghi et al., 2024). These cells recognize neoantigens and ligands, serving in chronic inflammation and immunosurveillance. CD8⁺ CTLs are the primary lymphocyte subset that eliminates cancer cells that express major histocompatibility complex class I molecules (MHC-I). Antigens presented by DCs can induce the transformation of CD8⁺ T cells into effector CD8⁺ T cells that possess cytotoxic capabilities (Sadeghi et al., 2024). Activated CTLs can move into the inflammatory environment as directed by chemokines, facilitated by the expression of CXCR3 (C-X-C Motif Chemokine Receptor 3). Besides, CD4⁺ T cells can stimulate the activation of DCs by delivering tumor antigens to CD8⁺ T cells or by triggering the synthesis of cytokines and co-stimulatory molecules, promoting the activation of DCs and enabling them to activate CD8⁺ T cells efficiently.

As breast cancer progresses, immune cells infiltrate an increase in tumor parenchyma and stroma, including DCs, B cells, CD4⁺ and CD8⁺ cytotoxic T cells, and macrophages. Adoptive transfer of breast TILs is one experimental approach that has the potential to reverse metastases and encourage the development of novel T-cell immunotherapy treatments. $\gamma\delta$ T-cells and NK cells in the TME have also been associated with better prognosis in all breast cancer subtypes (Alaluf, Shalamov, & Sonnenblick, 2024; Sadeghi et al., 2024). Understanding these roles is essential for the prevention and treatment of breast cancer.

Although the exact function of B lymphocytes in the TME as tumor antagonizers is poorly understood, they have been associated with positive therapeutic results in breast cancer patients (Laumont, Banville, Gilardi, Hollern, & Nelson, 2022). According to some research, B cells may promote cancer by reducing CTL function, increasing angiogenesis, and attracting MDSCs through cytokines. It has been reported that Treg cells and Breg (B regulatory) cells are interdependent in the development of metastasis in breast cancer patients (Ishigami et al., 2019). The specific roles of various subsets of tumor-infiltrating B lymphocytes within the TME are expected to be revealed by future research.

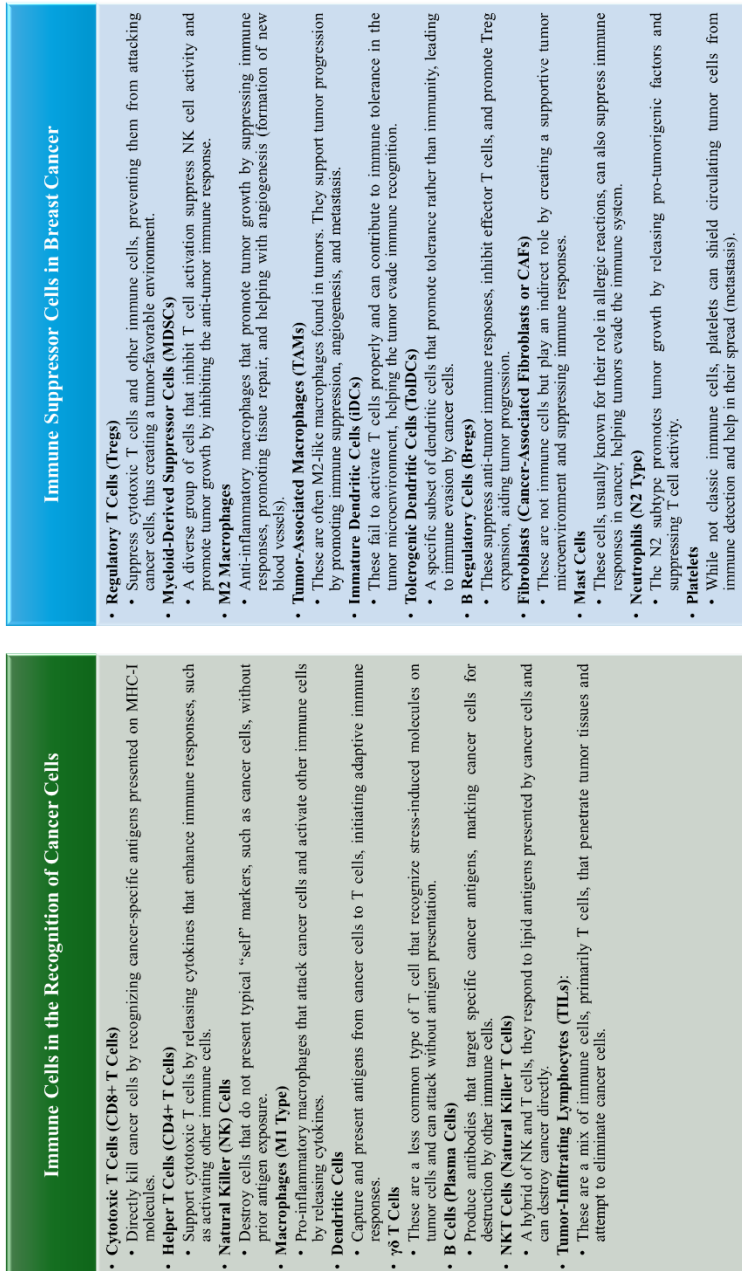


Figure 1. Classification of cell types involved in the identification and destruction of cancer cells, as well as in immunosuppression, tumor growth facilitation, and immune evasion.

4. Immune-boosting vaccines and therapies for breast cancer

Immunotherapy targets tumors specifically while minimizing damage to healthy cells. Various strategies are employed to utilize the immune system for cancer treatment, including cancer vaccines (therapeutic peptide and protein-based, B cell-based, dendritic cell-based, and DNA/mRNA-based), immune checkpoint (PD-1, PD-L1, CTLA-4) inhibitors, directed monoclonal antibodies, antibody-drug conjugates, bispecific antibodies, adoptive cellular therapy, TLR agonists, autologous tumor cells, cytokine-based immunotherapy, $\gamma\delta$ T cells, tumor-associated macrophages, oncolytic viruses, and immuno-metabolic targets (Alaluf et al., 2024; Davodabadi et al., 2022).

A study compared the effects of margetuximab and trastuzumab combined with chemotherapy on survival in patients with previously treated HER 2-positive breast cancer. Their research focused on polymorphic allelic variations (158V or 158F) of CD16A, suggesting enhanced survival for margetuximab in CD16A-158FF patients and trastuzumab in CD16A-158VV patients (Rugo et al., 2023). Another study uses murine HER2+ breast cancer models to test the effect of anti-HER2/neu and anti-4-1BB monoclonal antibody (mAb) combination therapy and found that adding anti-4-1BB mAb to anti-HER2/neu mAb potentiated the cytotoxic antitumor response. However, this combination therapy was shown not to evoke immune memory, and tumors recurred. It has been stated that this situation can be overcome with the dose regulation of anti-4-1BB mAb to 1 mg/kg (Kim et al., 2022).

However, T-cell activity is regulated by modulating the creation of costimulatory signals via several mechanisms. T cell activation encompasses (i) the primary signal, which comes from the binding of the T cell receptor (TCR) to the MHC molecule presented by an antigen-presenting cell (APC), and (ii) the costimulatory signal, which may result from several specific T cell-APC interactions (Chae et al., 2018). Several signaling pathways have been implicated in the modulation of T cell activity, including CTLA-4, PD-1, and PD-1/PD-L1 checkpoint inhibitors. In a study developing a tetravalent bispecific PD-1 x CTLA-4 molecule (MGD019) to achieve optimal co-blockade of PD-1 neutralization and maximal CTLA-4 inhibition, experiments were conducted in vitro in human cells, Cynomolgus monkeys and humans (Berezhnoy et al., 2020). In solid tumor cancer indications, such as breast cancer, combined immunotherapy using antibodies directed against PD-1 and CTLA-4 has shown better clinical effects than single pharmaceuticals.

Another cancer therapy involves the use of autologous tumor-infiltrating lymphocytes. In adoptive cellular therapy (ACT), a small number of anti-tumor cells with appropriate properties are taken from the individual, identified, and

then grown *ex vivo* for treatment (Rosenberg, Restifo, Yang, Morgan, & Dudley, 2008). There has been remarkable success in treating hematological malignancies with chimeric antigen receptor (CAR)-T cell therapy, leading to the development of new ACTs like CAR-macrophage, CAR-natural killer, CAR-natural killer T, and CAR- $\gamma\delta$ T (P. Zhang, Zhang, & Wan, 2023). In addition to cells, exosomes derived from CAR-T cells by secreting perforin and granzyme B have demonstrated efficacy in diminishing the development of triple-negative breast cancer without noticeable side effects *in vivo* (Yang et al., 2021).

Tumor-based cancer vaccines have several advantages, like ensuring more safety than chemotherapy and preventing malignant tumor recurrence through long-term immunological memories. Nanotechnology-based nanoparticles are used as adjuvants, immunogens, and delivery vehicles to activate the immune system (Davodabadi et al., 2022). A study uses nanoparticles to deliver a mRNA vaccine encoding tumor antigen MUC1 (type 1 transmembrane mucin) to DCs in lymph nodes, activating and expanding tumor-specific T cells (Liu et al., 2018). The NP-based vaccine successfully expresses tumor antigen, induces a robust and antigen-specific response against TNBC 4T1 cells, and enhances anti-tumor immune response.

Peptide-based vaccination has been explored as an alternative to treatments for tumors. Peptides are based on a region of the epidermal growth factor receptor (EGFR) extracellular domain IV, interrupting immune tolerance and stimulating immune response against cancer. It was mentioned that the EGFR p580 antiserum inhibited the growth of MDA-MB-453 breast cancer cells, which expresses HER2 but not EGFR (Doyle et al., 2018).

Lastly, bispecific antibodies, autologous tumor cells, TLR agonists, $\gamma\delta$ T cells, tumor-associated macrophages, radiotherapy, oncolytic viruses, cytokine-based immunotherapy, and immuno-metabolic targeting are other modalities employed in the treatment of breast cancer.

Table 1. Immunotherapy approaches and therapeutic targets have been examined in various studies.

Immune Therapy	Treatment	Targets	Reference
Directed Monoclonal Antibodies	Trastuzumab and Margetuximab	Margetuximab-enhanced chemotherapy is a therapeutic option for patients with pretreated HER2+.	(Rugo et al., 2023)
	anti-HER2/neu and anti-4-1BB	Treatment with anti-4-1BB mAb causes different types of immunological memory in naive and activated CD8+ T cells.	(Kim et al., 2022)
Antibody-Drug Conjugates	Trastuzumab emtansine (T-DM1)	Clinical practice on HER2+ breast cancer patients. Trastuzumab: HER2-directed monoclonal antibody. Emtansine: Cytotoxic microtubule polymerization inhibitor.	(Michel, Bermejo, Gondos, Marmé, & Schneeweiss, 2015)
Immune Checkpoint Inhibitors (PD-1, PD-L1, CTLA-4)	Engineered tetravalent bispecific PD-1xCTLA-4 molecule (MGD019)	Dual PD-1 and CTLA-4 blockade.	(Bereznoy et al., 2020)
Adaptive Cellular Therapy	Exosomes produced by mesothelin (MSLN)-targeted CAR-T cells	Mesothelin-expressing triple-negative breast cancer.	(Yang et al., 2021)
Cancer Vaccines	Therapeutic Peptide and Protein-Based	Iso-aspartyl (iso-Asp)-modified EGFR p580 immune sera inhibit the growth of EGFR-overexpressing human A431 and MDA-MB-453 tumor cells that express HER2 but not EGFR.	(Doyle et al., 2018)
	DNA/mRNA-Based	MUC1 (type 1 transmembrane mucin) to DCs in lymph nodes.	(Liu et al., 2018)

5. Immune approaches as adjunctive therapy to conventional therapies

Immune approaches as adjunctive therapies have gained significant attention in recent years, aiming to enhance the efficacy of conventional cancer treatments like chemotherapy, radiation, and surgery by strengthening the immune system in the body. These approaches include immune checkpoint inhibitors, oncolytic viruses, CAR-T cell therapy, cytokine therapies, cancer vaccines, ACTs, combination therapies, and personalized medicine approaches (Blattman & Greenberg, 2004; Blattman, Greenberg, Guth, & Dow, 2004; H. Zhang & Chen, 2018). Immune checkpoint inhibitors inhibit checkpoint proteins, while CAR-T cell therapy extracts genetically engineered T cells to target cancer cells. Cancer vaccines enhance the immune response against specific cancer antigens, whereas oncolytic viruses selectively target and eradicate cancer cells while eliciting an immunological response. Cytokine treatments enhance the immune response against cancer, and ACT infuses expanded and genetically modified immune cells to eliminate residual cancer cells and prevent recurrence. Combination therapies, such as chemotherapy and immunotherapy, radiation and immunotherapy, and surgery and immunotherapy, target residual disease and reduce the risk of recurrence. However, challenges include developing novel strategies for tumor resistance, managing immune-related adverse events, identifying predictive biomarkers, and optimizing therapy timing and sequence (Emens et al., 2024; Y. Lei, Li, Huang, Zheng, & Liu, 2021).

Treatment efficacy for TNBC is greatly improved when the mRNA-expressing tumor antigen MUC1 vaccination is administered in combination with an anti-CTLA-4 monoclonal antibody (Liu et al., 2018). Nanotechnology offers ideal tools for multi-therapy approaches. The research combines a drug combination methyltryptophan-paclitaxel (MP) by attaching the immunosuppressive enzyme indoleamine-2,3-dioxygenase (IDO) inhibitor to the chemotherapeutic agent paclitaxel (PTX) (Hu, Zheng, Xu, Gao, & Lu, 2020). MP binds to human serum albumin, enhancing the concentration of D-1-methyltryptophan (D-1MT) in tumors. MP NPs enhance the anti-tumor effect by strengthening the codelivery of PTX and D-1MT in tumors. MP NPs improve the immune environment, increasing effector CD8⁺ T cells and decreasing Treg cells.

New research has shown that $\gamma\delta$ T cells are an immune effector subgroup that might be used to create innovative cancer immunotherapies. The genotype of mitochondrial DNA influences the composition of the gut microbiota, which demonstrates the connections of mitochondria with $\gamma\delta 17$ T cells (Kawaguchi, Maeshima, & Toi, 2022).

6. Conclusion

In conclusion, breast cancer is a highly heterogeneous disease influenced by various molecular subtypes, genetic mutations, and interactions with the immune system. Breast cancer patients are cured via different treatment methods, such as surgery, chemotherapy, and radiation therapy, alongside advanced immunotherapy techniques. Understanding the TME and the immune system's involvement is critical in improving prognosis and treatment response. In breast cancer, TILs assist as prognostic indicators for chemotherapy response and survival. Immunotherapy such as immune checkpoint inhibitors, cancer vaccines, CAR-T cell therapy, and other adjunctive therapies have offered promise as an adjunct to the existing treatment regimens. Such agents, which harness the immune responses to eradicate cancer, have been shown to increase the survival rates of patients with especially very aggressive types of breast cancer like TNBC and HER2+. However, cancer treatment utilizing these therapies also presents challenges regarding tumor evasion, immune-mediated side effects, and the need for individualized strategy. Exploring potential cancer immunotherapy based on biomarkers, new targets for drug therapy, and methods for treatment personalization gives hope that effective and lasting control of malignancies will be possible.

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Chapter 6

Therapeutic Effect Of Magnetic Field On Cancer

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1. Introduction

Cancer is a significant disease that threatens human health worldwide. Despite significant advancements in cancer treatment, the morbidity and mortality rates remain highly prevalent, according to the 2022 global cancer statistics (Bray et al., 2018, 2024). In cancer treatment, although traditional methods such as surgery, chemotherapy, and radiotherapy are used, each of these methods has its own unique limitations in terms of efficacy, cost, and undesirable side effects. In this regard, the need for novel and more effective treatment methods to address these deficiencies has increased. Magnetic fields have been widely suggested as a potential therapeutic modality due to their high efficacy, low side effects, wide range of applications, and low cost advantages, and their effects on biological systems are being closely studied by scientists (L. Zhang et al., 2017).

Magnetic fields are commonly used in industrial and agricultural production, science and technology medicine, and other applications. A magnetic field can have an effect on a wide range of biological metabolism and processes in cells and organisms. In the literature, magnetic fields have been reported to have anti-carcinogenic potential both *in vivo* and *in vitro*, additionally, that magnetic treatment has potential for pain reduction, wound healing support, osteonecrosis, regulation of muscle functions, peripheral nerve regeneration, and anti-inflammation (Ding et al., 2011; Eccles, 2005; Jing et al., 2010; Kiss et al., 2013; Schuster & Rapoport, 2016; Shang et al., 2019; Strauch et al., 2007; Suszyński et al., 2014; Zhao et al., 2017; Zhu et al., 2017). Compared to existing treatments, magnetic fields hold an important place in cancer therapy due to their reliability, high efficiency, low cost, non-invasive nature and absence of scarring and infection risks. Magnetic fields are known to suppress angiogenesis of tumor and enhance the immune response in living organisms. Magnetic fields have an effect on biological functions at the cellular level by affecting, cell cycle, cell morphology, mitochondrial function, and cell membrane structure. The effect of the magnetic field observed at the molecular level leads to tumor suppression by interfering with DNA synthesis, reactive oxygen species (ROS) levels, epidermal growth factor receptor orientation, and the transmission of second messenger molecules (G. Zhang et al., 2023a). This review aims at summarising current knowledge of magnetic field therapy on cancer and its underlying mechanisms, as well as future prospects of magnetic field therapy.

2. Magnetic and Electromagnetic Fields

Magnetic field (MF) is the force field that forms around magnets or a moving electric charge (Prša & Kasaš-Lažetić, 2018). The magnetic field produced by natural magnets is generated by the alignment and mutual reinforcement of the

magnetic moments of atoms in a certain order. Electromagnetic fields (EMF) are generated by electromagnets or current-carrying wires and produce a magnetic field that varies over time (A. Xu et al., 2021b).

In the magnetic field, the international unit Tesla (T) is the unit of magnetic flux density. One Tesla is equal to one Weber per square meter, which is equal to 10^4 gauss (G), which is the unit of magnetic field in the centimeter-gram-second system. So, $1 \text{ G} = 100 \text{ } \mu\text{T}$. The magnetic flux density is proportionate to the magnetic permeability of the magnetic field and the magnetic field strength (Maffei, 2022b). The magnetic flux density can be calculated by the following formula:

$$B = \mu \times H$$

B: magnetic flux density (tesla)

μ: magnetic permeability (henry/meterkilogram-second squared)

H: magnetic field strength (amperes/meterkilogram)

Frequency refers to the rate of change over time of a periodic quantity, such as the instantaneous field strength of a low-frequency electric or magnetic field. The unit of frequency, a measure of the number of cycles per unit of time, is the Hertz (Hz) (Anonymous, 2024). The power flux density of the electromagnetic field (S), consisting of the energetic fractions of the magnetic field and electric components, is measured in watts per square meter (W m^{-2}) (Maffei, 2022a).

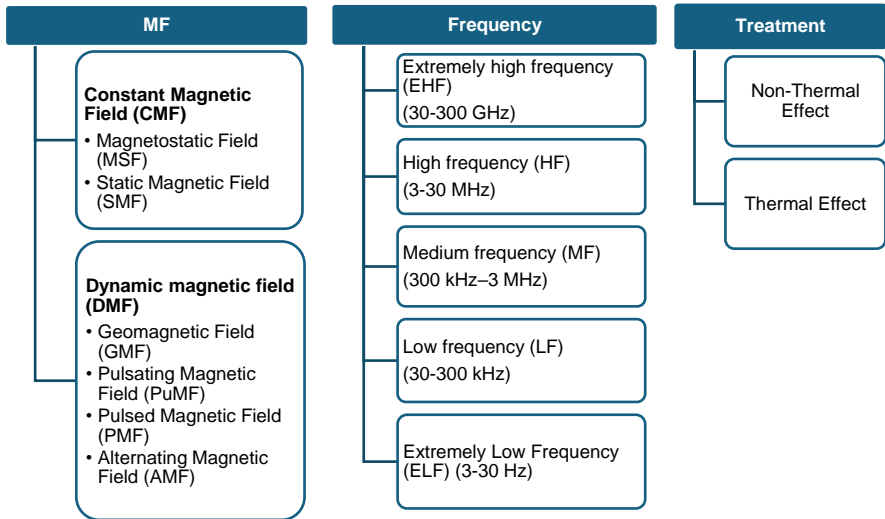
2.1. Classification of Magnetic Field

Magnetic fields (MF) are categorised into two types according to their properties: constant magnetic field (CMF) or dynamic magnetic field (DMF) (Y. Liu et al., 2024a). CMF can be generated by permanent magnets or solenoids with unidirectional currents, also called as magnetostatic field (MSF) or static magnetic field (SMF) (G. Zhang et al., 2023b). DMF can be categorised according to the mode of magnetic field generation, which varies with time: geomagnetic field (GMF), pulsating magnetic field (PuMF), pulsed magnetic field (PMF), and alternating magnetic field (AMF) (Hildebrandt, 2002; A. Xu et al., 2021a; G. Zhang et al., 2023b). AMFs are produced either by a regularly moving magnet or by an electromagnetic coil with a current of a given frequency. PMFs are generated by electromagnetic coils fuelled by current pulses, PuMFs by electromagnetic coils fuelled by current from rectifier data and GMFs by the Earth and the ionosphere (Guo et al., 2024; Maffei, 2022a).

SMFs are classified according to the magnetic field intensity as low MFs (<1 mT), medium MFs (1 mT - 1 T), high MFs (1 T - 5 T) and ultrahigh MFs (>5 T)

(Hunt et al., 2009; Y. Liu et al., 2024b; Van Huizen et al., 2019b). According to frequency, magnetic fields can be subdivided into low frequency MF, radio-frequency MF, medium frequency MF and high frequency MFs (Figure 1) (Y. Liu et al., 2024b). The treatment of magnetic fields involves two mechanisms: non-thermal effect (non-ionising radiation, NI) and thermal effect (ionising radiation).

Figure 1. Classification of magnetic field types.



2.2. Use of Magnetic Field in Biological Systems

Magnetic fields have been known to have biologically effects on living organisms since the mid-19th century through the induction of electric fields and currents (Gaffey & Tenforde, 1981). Specific magnetic properties, so-called biomagnetism, are known to exist in different tissues and organs in organisms (G. Zhang et al., 2023b). In the literature, it has been reported that the magnetic susceptibilities of cellular lipid protein, and water components in living organisms differ (Zablotskii et al., 2018). Shin *et al.* reported that investigating brain microstructural information based on magnetic susceptibility differences of iron and myelin can be used as a useful tool to improve understanding of disease pathogenesis and lesion characterization, as they are involved in normal brain function and are important biomarkers of neurological disorders (Shin et al., 2021). Thus, the application of biomagnetism differences between biological components in disease detection and diagnosis is of interest in the medical field.

SMFs, which cause various physio-chemical effects because of the intrinsic magnetism of organisms, can alter the position, orientation and morphology of intracellular substructures and affect various biological metabolism and

processes, including structural adaptation, proliferation, and stress responses (Tao et al., 2019). Therefore, research into stimulating living cultures with different types of magnetic fields is also important. SMFs are widely used in many fields such as industrial and agricultural production, modern science and technology, especially in medicine and healthcare. The process of magnetic field generation and its accurate quantification as a factor that impacts cells, tissues and organisms is the most important research topic of magnetic fields in biotechnology. In the literature, it has been reported that magnetic resonance imaging resolution and imaging capabilities have improved with the increase in SMF intensity and 4-9.4 T research systems have been developed for clinical imaging applications (Tian et al., 2021). Effects of static or oscillating weak magnetic fields on stem cells, calcium concentration, electron transfer in cryptochrome, ROS, circadian clock, action potentials, anxiety, analgesia, development, neuronal activities, memory, DNA, genetics and many other functions have also been reported (Van Huizen et al., 2019a; Wang et al., 2022; J. Xu et al., 2021; Zadeh-Haghighi & Simon, 2022). The fact that the effects of SMFs used in medicine on biological systems and their underlying mechanisms have not yet been fully elucidated has led to the need for further investigation of magnetic fields (Table 1).

Table 1. The biological effects of magnetic fields

Tumor cells	Application conditions	Effect of application	Ref.
Human neuroblastoma (SH-SY5Y)	1 mT, 50 Hz DMF for 72 h	Increased ROS levels Induced apoptosis	(Benassi et al., 2016)
Human breast cancer (MCF-7)	10 mT SMF for 24 and 48 h	Decreased viability Decreased differentiation Increased ROS levels	(Hajipour Verdom et al., 2018)
Human breast cancer (MCF-7 and MDA-MB-231)	0.011 T, 8 Hz PMF for twice a day for 5 days	Decreased viability Inhibited cell proliferation Induced cell death Induced cellular senescence	(Pantelis et al., 2024)
MCF-7 and MDA-MB-231 cell lines	1 mT, 50 Hz ELF-MF for 24 h	Decreased viability Inhibited cell proliferation	(Elexpuru-Zabaleta et al., 2023)
Mouse breast cancer (4T1)	~150 mT SMF for 24 h	Inhibited cell migration Repressed telomerase activity	(Fan et al., 2020)
Jurkat Lymphoma cells	4.75 T SMF	Inhibited cell proliferation	(Aldinucci et al., 2003)
Human Epidermal Stem Cells (hESC)	5 mT, 50 Hz ELF-EMF for 7 days (30 min/day)	Promoted cell proliferation Increased cell growth Increased proportion of S-phase cells	(M. Zhang et al., 2013)
Prostate cancer (LNCaP, PC3, and DU145)	0.2 mT, 60 Hz MF	Decreased cell growth Induced apoptosis through ROS	(Koh et al., 2008)
Male Wistar rats	7 mT, 50 Hz ELF-MF for 24 h	Stimulated pro-inflammatory cytokines	(Wyszkowska et al., 2018)
Human leukaemia (U937)	6 mT SMF for 72 h	Increased intracellular Ca ²⁺ Mitochondria localized near nucleus	(Dini et al., 2009)

3. The Effect of Magnetic Fields in Cancer Therapy

Cancer cells can be affected by MFs to different degrees and this effect is known to be related to non-thermal (non-ionising radiation) and thermal (ionising radiation) mechanisms in the treatment of MFs. High-frequency MFs (gamma rays and X-rays, etc.) cause direct damage to DNA, while low-frequency MFs (LF-MFs) have a biochemical effect on the reactions of the cells (Diab, 2019). ELF-MFs have been found to have anticancer activity, to reduce the risk of certain tumors, and to have potential benefits in the healing process of cancer patients, according to numerous studies in the literature (Khan et al., 2021). As a result, MFs can be proposed as a strategy for cancer therapy.

3.1. Thermal Effects of Magnetic Field Therapy

Hyperthermia (HT) is a widely used anticancer treatment modality in combination with radiotherapy and chemotherapy to increase the body's tissue temperature, based on the application of heat (39-45 °C) to prevent the growth of cancerous cells and kill them (Chang et al., 2018; X. Liu et al., 2020; Peiravi et al., 2022). The aim is to increase the sensitivity of tumor tissues and, on the other hand, to affect the defence system (Chichel et al., 2007). The increase in tissue temperature with HT can lead to oxygenation of the tumor by altering vascularity and increasing blood flow, as well as killing cells by affecting cell membranes, nucleic acid repair enzymes, proteins, and cellular structures. However, although this method triggers the death of tumor cells, it can cause serious side effects as it also affects healthy tissues (Peiravi et al., 2022). Therefore, it is recommended to use nanotechnological methods to increase the sensitivity of HT with a harmless, effective, and easy treatment approach. Studies have shown that nanoparticles (NPs) induce DNA damage and expression of heat shock proteins by applying heat only to tumor tissues in HT and direct cells to death (Szwed & Marczak, 2024).

Magnetic hyperthermia (MHT) is based on the principle of heat generation by increasing the hyperthermia efficiency of magnetic nanoparticles (MNPs) in the presence of AMF, and thus, with the widespread use of nanotechnology, MHT has been proposed as an alternative method in tumor therapy (Beik et al., 2016; GILCHRIST et al., 1957; Peiravi et al., 2022). The MNPs-mediated MHT (MNPs-MHT) therapeutic modality has a great advantage in that it allows the magnetic killing of cancer cells without the need for deep tissue penetration and without damaging the surrounding normal tissues (Kumar & Mohammad, 2011; Shubayev et al., 2009). MNPs-MHT enables the realization of intracellular hyperthermia by applying therapeutic heat directly to cancer cells and, as a result of these therapeutic advantages, MNPs-MHT-based cancer therapies have been

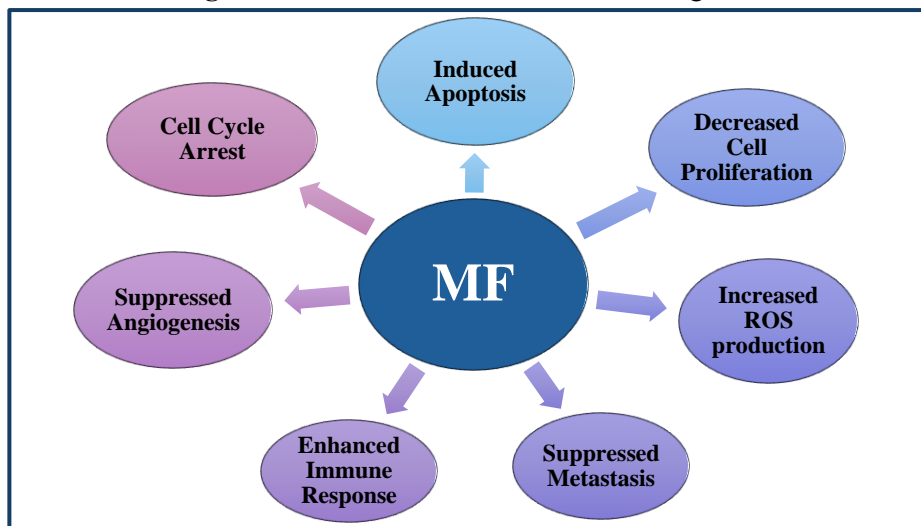
transferred from the laboratory stage to clinical studies and used in the treatment of breast, prostate, and glioblastoma cancer (Acar et al., 2022; Espinosa et al., 2018; Jordan et al., 1999). Though MNPs-MHT treatment has been applied in clinical trials, the obstacles limiting the efficacy of MNPs-MHT on cancer therapy need to be investigated to overcome the challenges of this therapeutic approach.

In MNPs-MHT treatment, one of the main aims is to synthesis multifunctional MNPs with appropriately functionalized surfaces that exhibit the highest possible saturation magnetization using antibodies, chemical compounds, and DNA probes allowing them to selectively bind to target tissues or cells. Furthermore, while the shape and size of MNPs are important for their therapeutic efficacy, surface modifications that help to maintain their stability and biocompatibility are also important (Rajan & Sahu, 2020). Polyethylene glycol (PEG), polyethyleneimine (PEI), polyvinyl alcohol (PVA), silica and polyvinylpyrrolidone (PVP) are the most commonly used biocompatible coating materials for MNPs (Cho et al., 2019). MNPs are used in bioimaging, cell labelling and targeted drug delivery, particularly in hyperthermia (Bañobre-López et al., 2013; Dey et al., 2017; Kolosnjaj-Tabi et al., 2013; F. Liu et al., 2011; Solak et al., 2021). The application of colloidal iron oxide and iron oxide-based core-shell nanostructures has shown promising potential in this field due to their high efficiency in carcinogenic cell destruction while showing limited toxicity to normal cells (Kossatz et al., 2014; Martinelli et al., 2019; Peiravi et al., 2022). In addition to being minimally invasive as it is injected intra-tumorally or intravenously, this method can provide sufficient thermal dosage to the targeted area while sparing healthy tissue. After the MNPs reach the target, the heat generated by the application of an external AMF is limited to the area covering the MNPs and is directed throughout the tissue (Peiravi et al., 2022). With this treatment method, it has been shown in the literature that the amount of iron-based nanoparticles will not cause toxicity in healthy cells and that most of the MNPs are evacuated by the body in a short time after treatment (Fukuda et al., 2012; Herring et al., 2013; Kim et al., 2011; LeBrun & Zhu*, 2018).

3.2. Non-Thermal Effects of Magnetic Field Therapy

Non-thermal effects of MF can be defined as their direct interaction with biological cells without relying on the principle of heat (Israel et al., 2013; A. Xu et al., 2021a). In addition to having antiproliferative, apoptotic, autophagic, angiogenic, and antimetastatic effects in cancer cells, MFs have also been reported to stop the cell cycle and improve the inflammatory response (Figure 2) (A. Xu et al., 2021a).

Figure 2. Potential anticancer effects of magnetic field



The cell cycle, which is closely associated with cell growth and death, includes G1, S, G2 and M phases and abnormal expression of cell cycle proteins in cancer cells may lead to uncontrolled cell proliferation (Otto & Sicinski, 2017). Most of the current chemotherapy and radiotherapy methods disrupt the integrity of DNA at cell cycle checkpoints, thereby inhibiting the proliferation of cancer cells and leading to their death. Therefore, targeting these cycle proteins is considered as a therapeutic strategy (Otto & Sicinski, 2017). The literature has described that MF suppresses the cell proliferation by keeping them in G2 phase (Miyakoshi, 2005). Chen *et al.* observed that exposure of human leukaemia (K562) cell line to SMFs (8.8 mT) caused DNA damage and arrest in G2/M phase and SMFs enhanced the anticancer effect of cisplatin (W.-F. Chen et al., 2010). Nie *et al.* demonstrated that exposure of melanoma cells (B16-F10) to LF-MF (7.5 Hz, 0.4 T, 43 days) induced an arrest of the cell cycle in the G2/M phase (Nie, Du, et al., 2013).

Apoptosis is mediated by mitochondrial (intrinsic) and cell death receptor (extrinsic) pathways (Mohammad et al., 2015). Targeting pro-apoptotic and anti-apoptotic proteins and mitochondrial membrane permeability, especially in the mitochondrial pathway, has become attractive in cancer therapies by contributing to the induction of apoptosis (Ko et al., 2007; Portt et al., 2011). Yuan *et al.* observed that exposure of nephroblastoma and neuroblastoma cells to LF-MF (50 Hz, 5.1 mT, 2 h per day) inhibited cell proliferation, induced apoptosis and increased cisplatin efficacy *in vivo* (Yuan et al., 2018). Gürhan *et al.* demonstrated that in human fibrosarcoma (HT-1080) cells exposed to SMFs, the

increase in intracellular ROS levels led to the release of cytochrome c into the cytoplasm, thereby triggering apoptotic cell death (Gurhan et al., 2021). Koh *et al.* reported that after MF (60 Hz, 48 h) exposure, intensity-dependent ROS accumulation occurred in prostate cancer (LNCaP, PC3, and DU145) cell lines and the cells were directed to apoptosis (Koh et al., 2008). So far, it has been established that miRNAs play a role in regulating a number of biological processes, such as autophagy and apoptosis (Yu et al., 2012). Xu *et al.* showed that LF-MFs inhibited growth of tumor and induced autophagic cell death by upregulating the expression level of miR-486, which plays a role in cell autophagy in lung cancer, in a Lewis Lung Cancer mouse model (Y. Xu et al., 2017). Although MF has been implicated in the induction of apoptosis and autophagy in a number of cancers, there are only a limited number of studies in this area and further research is needed.

Angiogenesis has become a therapeutic target in chronic inflammation and cancer because of its importance in embryonic development, tumor growth, and metastatic spread (Z.-L. Liu et al., 2023). The migration of vascular endothelial cells has a significant role in the progression of angiogenesis of tumor cells regulated by a variety of anti-angiogenic and pro-angiogenic molecules. Targeting vascular endothelial growth factor (VEGF-A, VEGF) and vascular endothelial growth factor receptor-2 (VEGFR-2) is particularly important in cancer therapy (Ferrara et al., 2003). In the literature, Strelczyk *et al.* showed that SMF of 600 mT for 10 days suppressed angiogenesis and delayed vascular maturation *in vivo* by reducing vessel diameter and functional vessel density (Strelczyk et al., 2009). Williams *et al.* showed that C3H/HeJ mice treated with a pulsating magnetic field of 120 pulses per second (0, 10 mT, 15 mT, or 20 mT for 10 minutes per day) significantly reduced tumor growth and vascularization (Williams et al., 2001). Monache *et al.* demonstrated that human umbilical vein endothelial cells (HUVEC) exposed to MF (50 Hz, 2mT) had decreased proliferative, migratory, and tube-like processes. Furthermore, MF treatment significantly downregulated the levels of VEGFR2 and decreased the ability of endothelial cells to form new vessels by affecting the VEGF signaling pathway (Delle Monache et al., 2013). Together, these findings suggest that MF therapy is a promising treatment modality that may have an impact on angiogenesis of tumor.

The immune function of the organism plays an important role in tumor initiation and metastatic spread. Therefore, effective strategies to re-model the immune system in tumors are becoming a key element of cancer immunotherapy (Finck et al., 2020). Nie *et al.* showed that tumor-bearing mice treated with MF (7.5 Hz, 0.4 T) increased lifetime, suppressed cytokine production, including

keratinocyte-derived chemokine (KC), granulocyte colony-stimulating factor (G-CSF), and interleukin-6 (IL-6) indicated that MF had an effect on improving immunity (Nie, Chen, et al., 2013). As for tumor metastasis, a leading cause of death in cancer patients, occurs when cancer cells spread beyond the source site of a tumor (Tracey A. Martin, Lin Ye, Andrew J. Sanders, Jane Lane, n.d.). Therefore, inhibition of metastasis has been an important target of cancer treatment modalities. Song *et al.* showed that SMF can inhibit cell metastasis in ovarian cancer in a ROS-dependent manner (Song et al., 2021). Tofani *et al.* indicated that MF (5.5 mT, 50 Hz) significantly inhibited tumor growth and metastasis in breast cancer MDA-MB-435 cell line (Tofani et al., 2002). Nie *et al.* found that metastasis was suppressed in melanoma B16-F10 cells after MF (0.4 T and 7.5 Hz) exposure (Nie, Du, et al., 2013). Song *et al.* stated that SMFs can suppress ovarian cancer metastasis *in vitro* and *in vivo* (Song et al., 2021).

4. Magnetic Fields in Combination Therapies

The fact that cancer-related mortality rates are still very high despite current cancer treatments has necessitated the development of new strategies that are cost-effective and highly effective. Combination therapy, one of such approaches, has an important role in cancer treatment as it is a treatment method that combines two or more therapeutic agents (Yap et al., 2013). Compared to the monotherapy approach, which targets actively proliferating cells in a non-selective manner (without discriminating between healthy and cancerous cells), the synergistic effect of combining anticancer agents increases the efficacy of treatment (Partridge et al., 2001). Combination therapies aim to reduce toxicity and side effects that occur as a result of drug resistance caused by chemotherapy-induced high dosage and long-term treatment (Albain et al., 2008). In addition to reducing drug resistance, this treatment method provides therapeutic benefits such as inducing apoptosis, reducing tumor growth, cancer stem cell populations and metastatic potential (Mokhtari et al., 2013). In summary, as shown in Table 2, MF can be applied as an adjuvant therapy to improve the effects of chemotherapeutic drugs by inducing cell cycle arrest, apoptosis, and DNA damage in cancer treatment.

Table 2. Combinational approaches with magnetic field for cancer therapy

Combinational approaches	Type of cancer	Application conditions	Effect of application	Ref.
SMF + Adriamycin	Human leukemia (K562)	8.8 mT SMF for 12 h, with Adriamycin (25 ng/ml)	Cytotoxic effect Arrested G2/M phase Increased DNA damage	(Hao et al., 2011)
SMF + Paclitaxel	K562 cell line	8.8 mT SMF for 24 h, with Paclitaxel (10 ng/ml, 24 h)	Inhibited the metabolic activity Arrested G2/M phase Increased cell membrane damage	(Sun et al., 2012)
SMF + Cisplatin	Ovarian carcinoma (Sensitive (A2780) and resistant (A2780CP))	15 mT SMF for 24, 48 and 96 h) with Cisplatin (IC ₅₀ values for 24, 48, and 96 h)	Increased DNA damage Genotoxicity Induced apoptosis Induced necrosis	(Zafari et al., 2024)
SMF + Cisplatin	Murine Lewis lung carcinomas (LLCs)	3 mT SMF for 35 min/day and cisplatin (3 mg/kg, i.p.)	Inhibited cell proliferation Longer survival time Cytotoxic effect	(Tofani, 2003)
SMF + Doxorubicin	Female B6C3F1 mice with transplanted mammary adenocarcinoma	110 mT SMF and doxorubicin (10 mg/kg, i.p.)	Tumor regression	(Gray et al., 2000)
SMF + Cisplatin	Human cervical cancer (HeLa)	10 mT SMF for 48 h and cisplatin (IC ₅₀ values)	Decreased cell viability Increased ROS production	(Kamalipooya et al., 2017)
PMF + Temozolomide	Human glioblastoma (T98G)	2 mT, 75 Hz PMF for 1 h/day and temozolomide (10 µM for 24 h)	Decreased cell proliferation Epigenetically influencing tumor suppressors and the regulation of oncogenes	(Pasi et al., 2016)
LF-MF + Temozolomide	Human glioblastoma (U87 and T98G)	10 mT, 100 Hz LF-MF for 144 h and temozolomide (100 µM)	Increased ROS production	(Akbarnejad et al., 2017)
LF-MF + 5-fluorouracil (5-FU)	MCF-7 cell line	1 mT, 50 Hz LF-MF for 12 h and 5-fluorouracil (5-FU) (5 µM for 24 h)	Decreased cell proliferation Cytotoxic effect Accumulation of cancer cells in S phase	(Han et al., 2018)

Extremely low-frequency electromagnetic field (ELF-EMF) + Folic acid-modified magnetic nanoparticles (FA-MNPs)	Human hepatoma (BEL-7402)	0.7 mT, 100 Hz ELF-EMF and FA-MNPs for 24 h	Inhibited cell proliferation Induced apoptosis	(B. Chen et al., 2014)
AMF+ Photothermal Therapy	Malignant cell lines (SKOV3, PC3, and A431)	12 mT, 110 kHz AC magnetic field, Iron oxide MNPs and laser irradiation 808 nm at 0.3 W/cm ²	Dual action yielded complete apoptosis-mediated cell death	(Espinosa et al., 2016)
AMF + Immune Therapy	4T1 (breast cancer) cell line	1.7 mT, CoFe ₂ O ₄ @MnFe ₂ O ₄ NPs for 10 min at 50 °C (MHT) and α -PD-L1 treatment	The combined therapy demonstrated the great potentials in the fight against both primary and metastatic tumors	(Pan et al., 2020)

5. Conclusion

In conclusion, numerous studies have shown that different types of MF have different effects on tumor cells and that these effects are related to thermal and non-thermal mechanisms. This review discusses the potential of MFs in anti-tumor therapies to suppress cancer cell proliferation, arrest the cell cycle, inhibit neovascularization, suppress metastasis, and promote cell death in both *in vivo* and *in vitro* models. In addition, the synergistic potential of MFs in combination with chemotherapeutic agents, photothermal therapy or immunotherapy was discussed, which might be more effective in combined anticancer therapy. The potential of MF therapy in oncology needs to be systematically investigated and elucidated in more detail with further studies.

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